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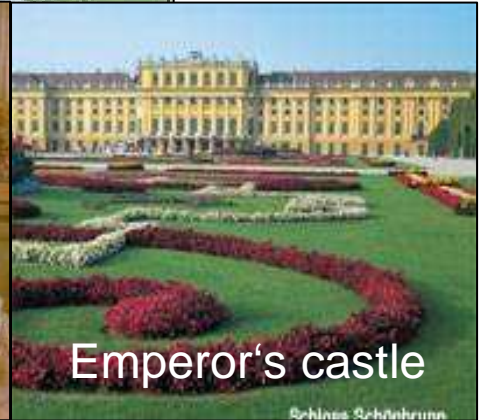
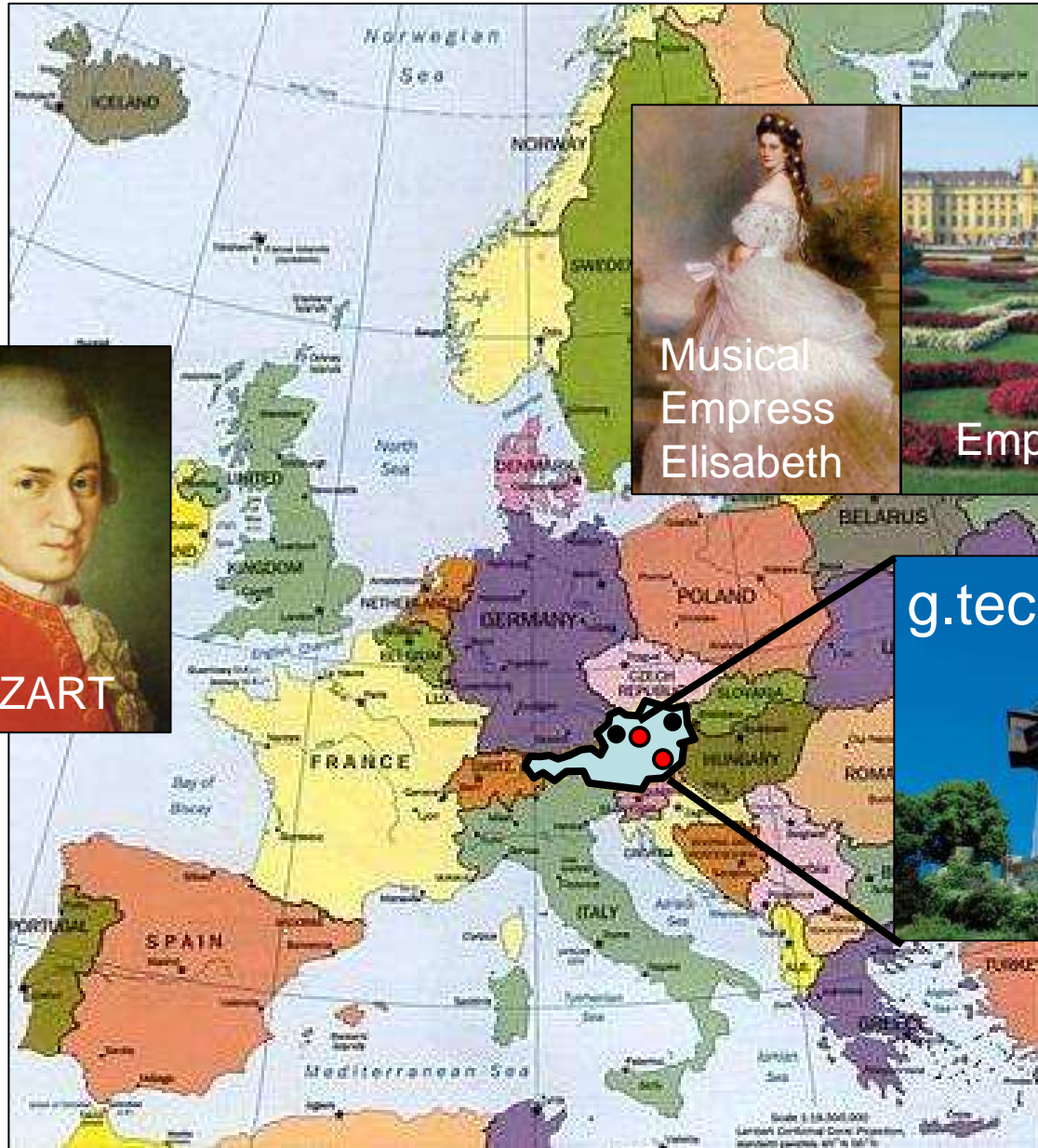
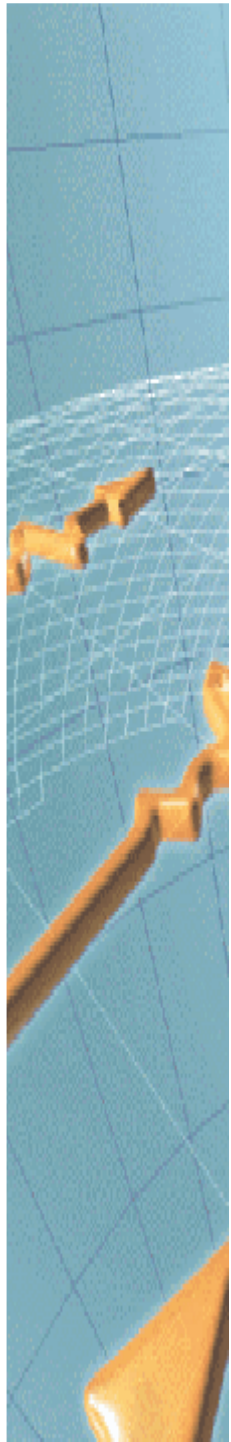
g.tec



# Brain-Computer Interface

**Christoph Guger, CEO  
Guger Technologies OEG  
g.tec medical engineering GmbH  
Graz & Linz, Austria**

biomedical engineering program



## g.tec – “accelerate your biosignal research”



### company fields

- bio-engineering, medical electronics (bio-electricity)
- developing and offering hard- and software products for biosignal research  
(**single cell activity, EEG, ECoG**; muscle cells: **ECG, EMG**; other tissue: **EOG, ...**)
- performs user specific adaptations and developments
- mainly based on rapid prototyping environment under *MATLAB/Simulink*

### company description

- private company, located in Graz and Schiedlberg (Linz), Austria
- inter-disciplinary team (biomedical- , telematics engineers, psychologists)
- customers: universities, university hospitals, R&D departments, industry

## Cooperations



EU IST– Virtual Reality



**Tracking subject responses** in the VE by neuro-physiological measurements: building better VE, therapy applications for patients with anxiety psychosis, ...

- Virtual Environments and Computer Graphics, UPC, Barcelona  
Mel Slater, Chris Groenegrass



- University of Technology Graz, Austria  
Robert Leeb, Gert Pfurtscheller



- Insituto de Neurociencias, UMH, Alicante, Spain  
Mavi Sanchez-Vives

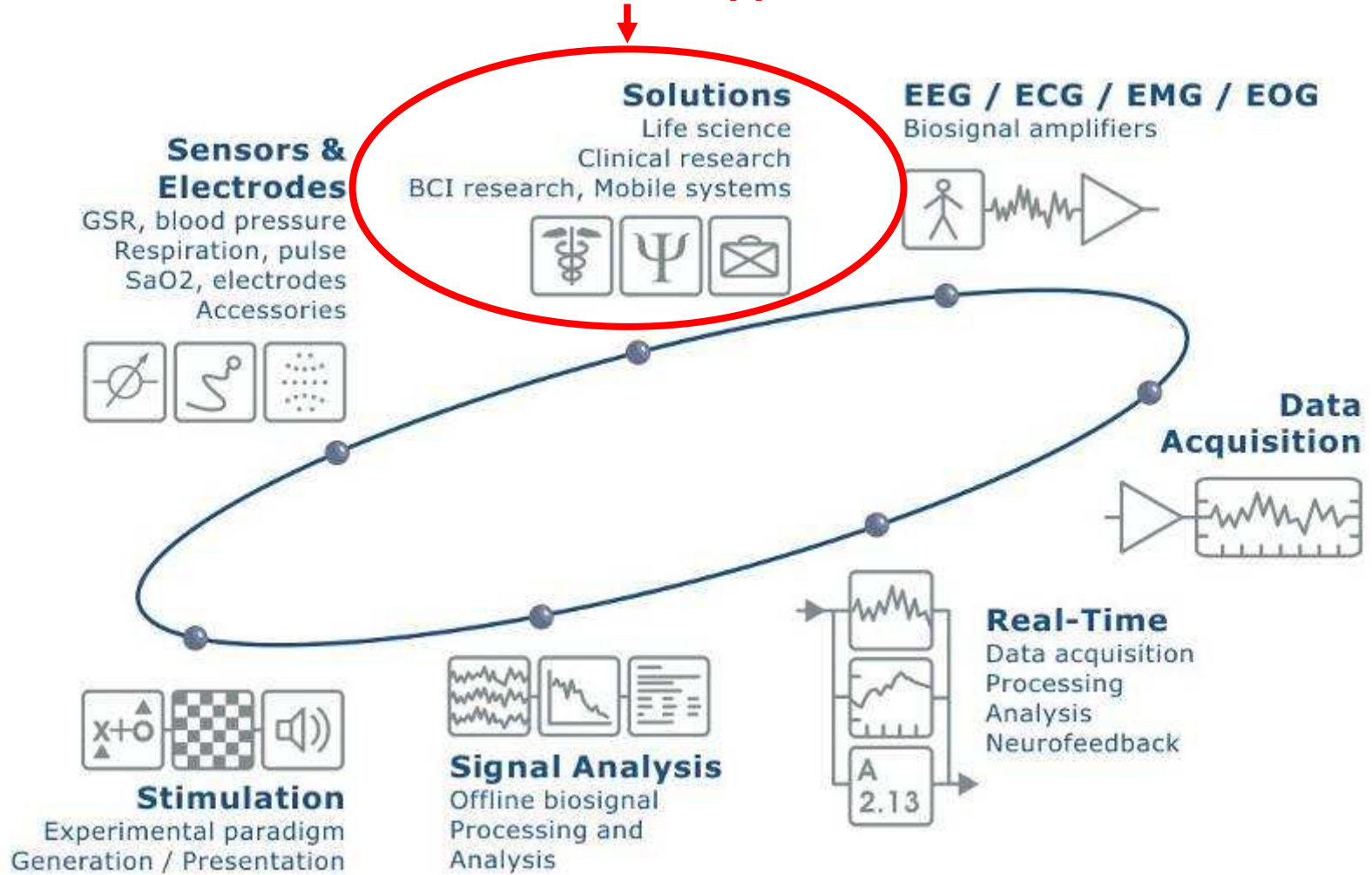


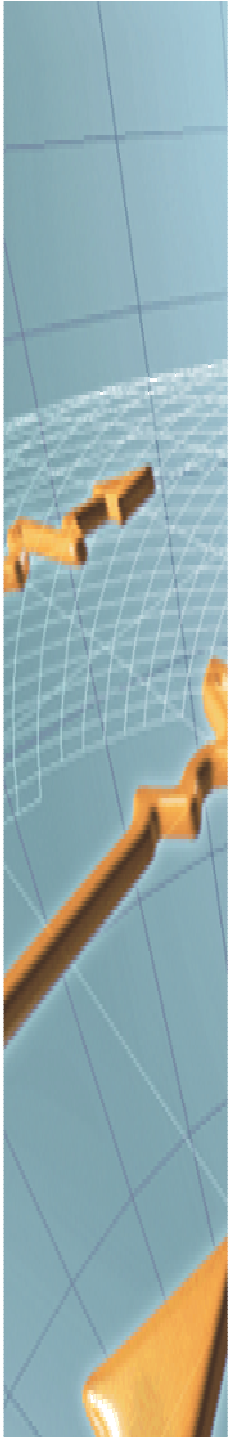
- UPF Barcelona  
Paul Verschure



# Range of Products

## CASE STUDIES of BCI applications





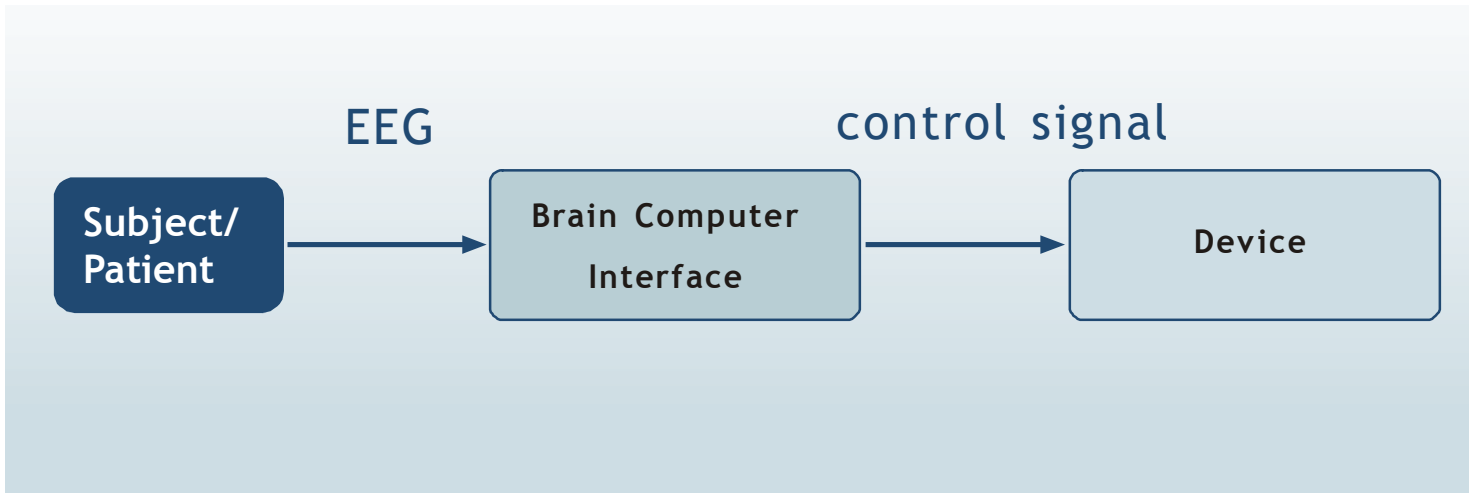
## Content

- a) What is a BCI?
- b) Applications
- c) Components of a BCI
- d) Physiological background
- e) ERD/ERS
- f) Slow cortical potentials
- g) SSVEPs
- h) P300
- i) Spelling with the BCI
- j) Smart home control



## Brain Computer Interface

### III) Closed loop Applications: Brain-Computer-Interface (BCI) in VR



... establishes the only communication channel without using any muscle activity ...

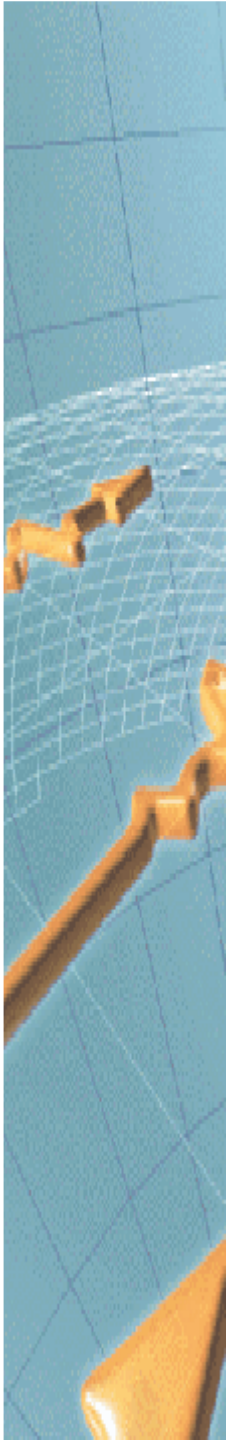
a BCI **transforms EEG** signals into **control signals**

HCI – Human Computer Interface

DBI – Direct Brain Interface (University of Michigan)

TTD – Thought Translation Device (University of Tübingen)

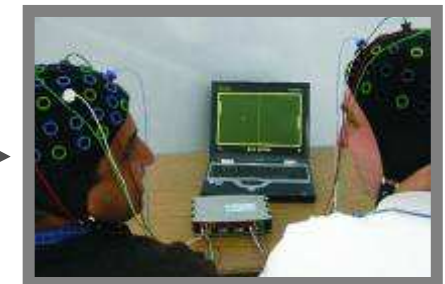
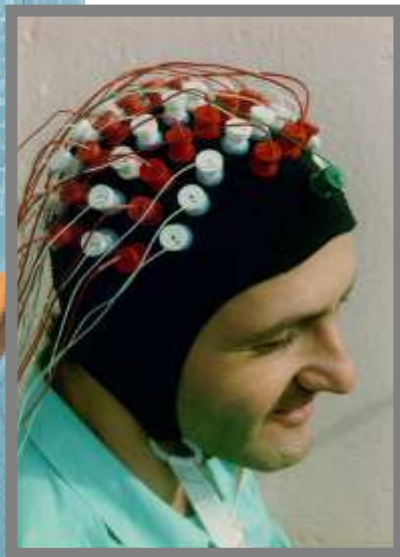




## Applications of a BCI in patients

- patients with **amyotrophic lateral sclerosis** (ALS)
- **locked-In Syndrome** (LIS) to communicate
- patients with **amputations** to control a robotic limb
- patients with **spinal cord lesions** to control a FES device or a wheelchair
- gaming
- composing music
- walking through VE, controlling VE

# Some examples of BCI applications

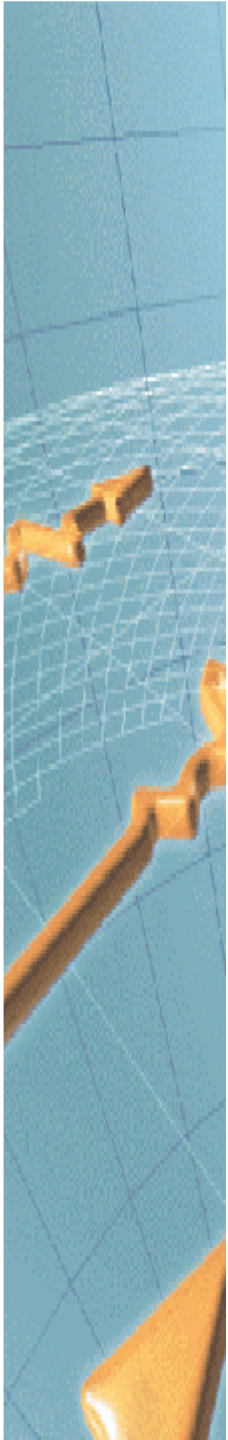


# Applications of a BCI in subjects/patients



## Potential users worldwide

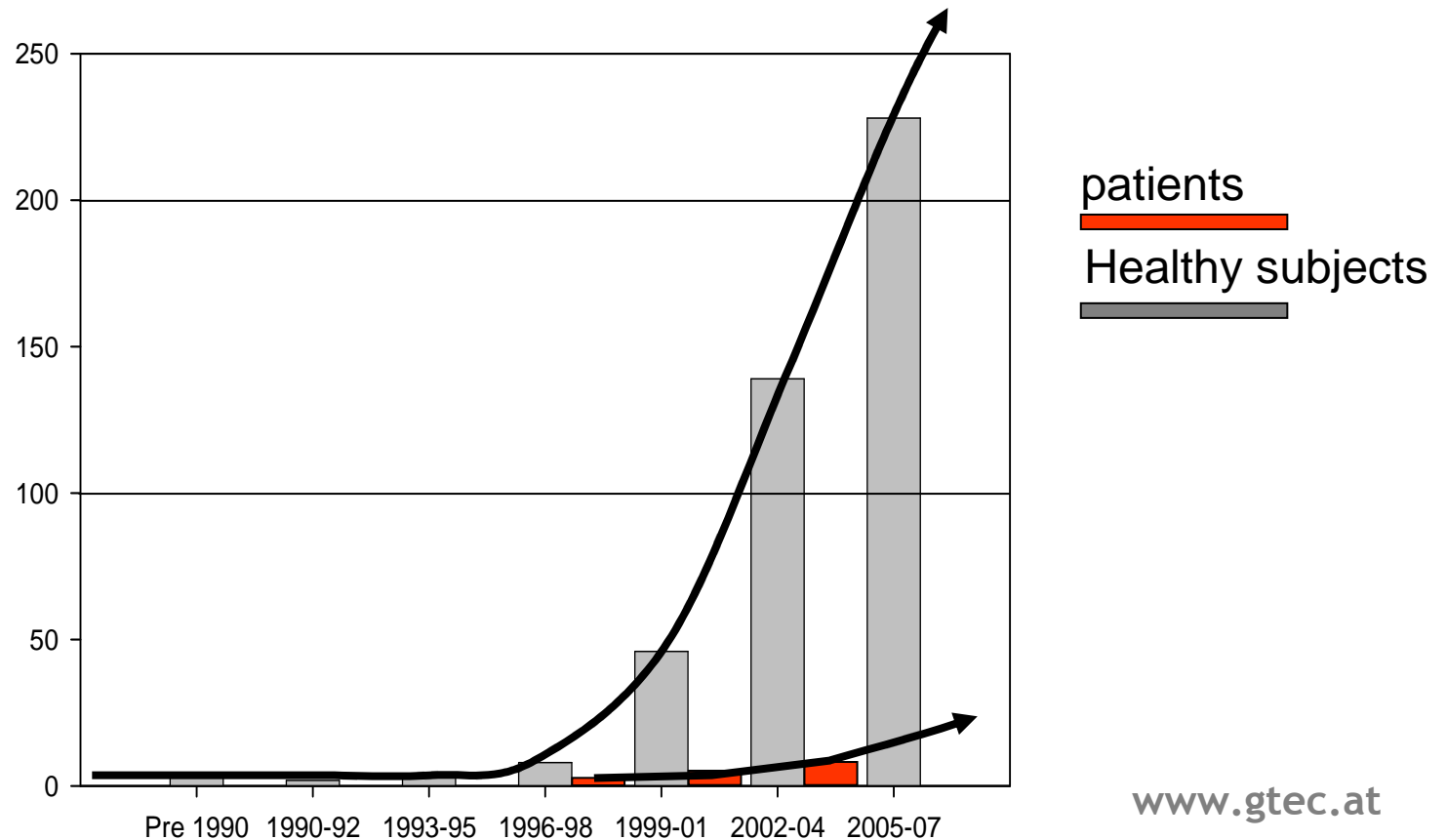
Cerebral palsy	– 16,000,000
Brainstem stroke	– 10,000,000
Other stroke	– 60,000,000
Spinal cord injury	– 5,000,000
Postpolio syndrome	– 7,000,000
Amyotrophic lateral sclerosis	– 400,000/3,000,000
Multiple sclerosis	– 2,000,000
Muscular dystrophy	– 1,000,000
Guillain-Barre syndrome	– 70,000



## Evolution of BCI research

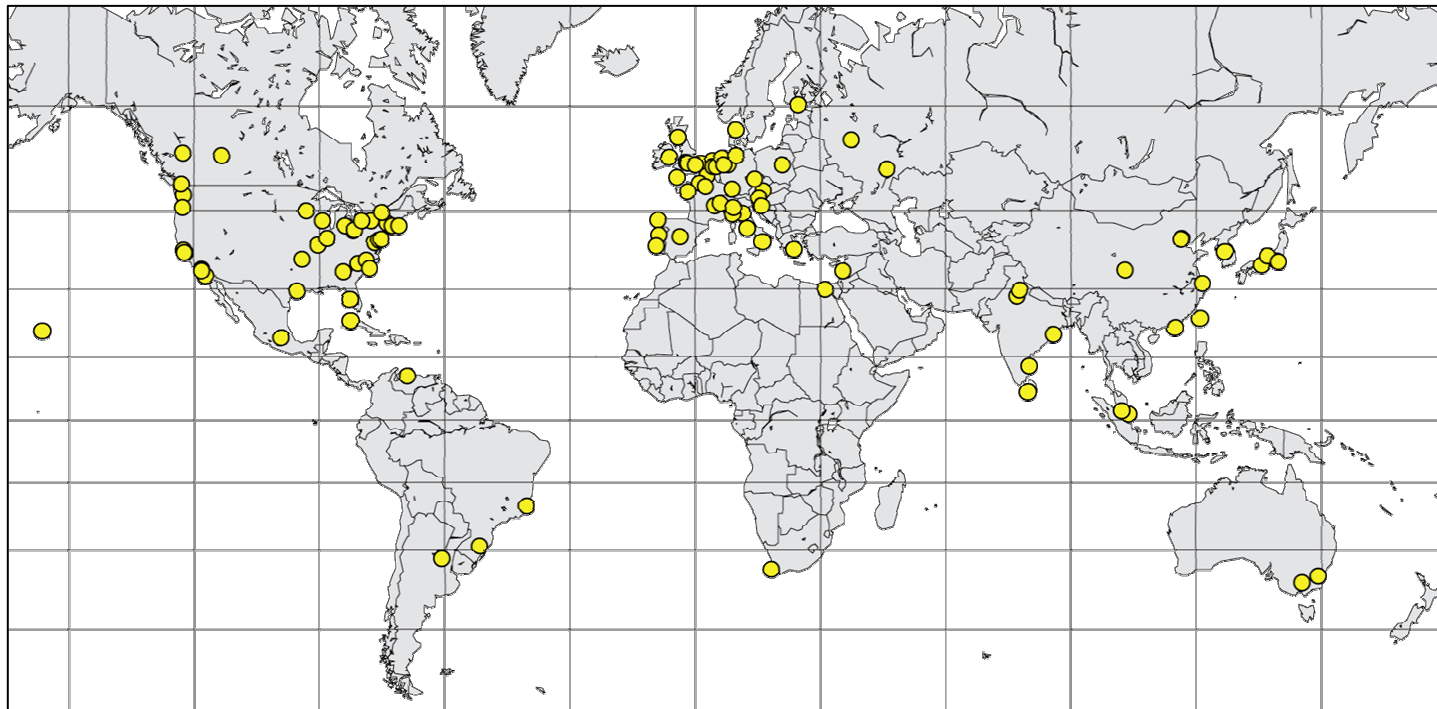
- 1995 ~ 5 labs active in BCI research, first demonstrations
- 2005 > 70 laboratories active all over the world
- 2007 > 120 laboratories involved in BCI research

### Growth of BCI publications in peer-Reviewed Papers



# Evolution of BCI research

- “BCI Activity Map” > 120 sites

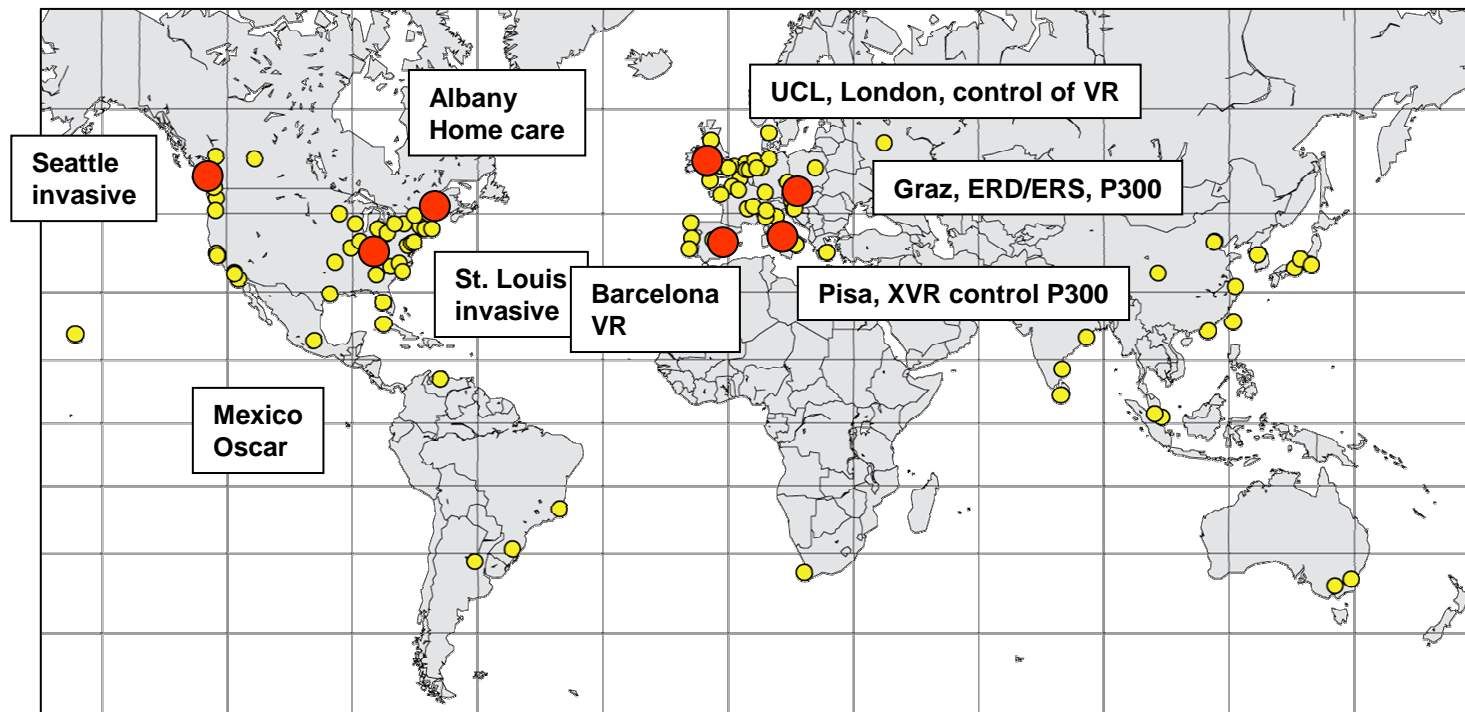


Adapted from Schalk et al.

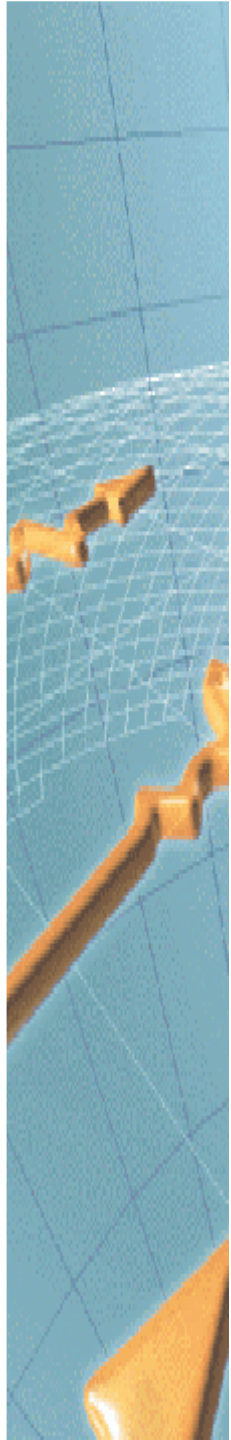


# Evolution of BCI research

- Case Studies from



Case studies 2007



## Changes of brain electrical activity and mental strategies

- Slow cortical potentials (anticipation tasks)  
DC-derivation, artifact problem, difficult strategy, feedback method
- Steady-State Evoked potentials (SSVEP, SSSEP)  
Flickering light with specific frequency
- Event-related, non-phase-locked changes of oscillatory activity  
**ERD/ERS (motor imagery tasks)**  
Changes of mu-rhythm, alpha activity and beta activity over sensorimotor areas, imagination of hand-, foot-, tongue- movements
- **Evoked potentials (focus on attention task)**  
Thalamic gating, various methods of stimulation (visual, tactile, electrical, auditory, ...), P300

## Measurement of brain signals

Multi-channel analysis system with derivations simultaneously and also directly in the brain

- *Electroencephalogram*

non-invasive

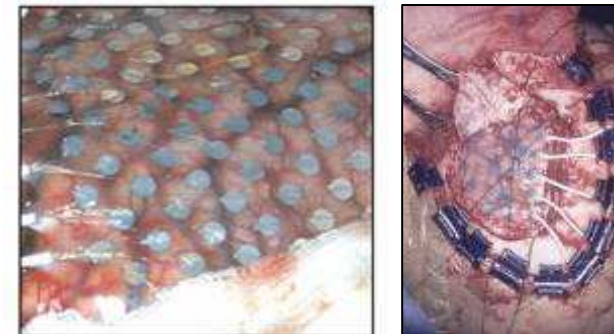
bad spatial resolution



- *Electrocorticogram*

direkty measured on brain's surface

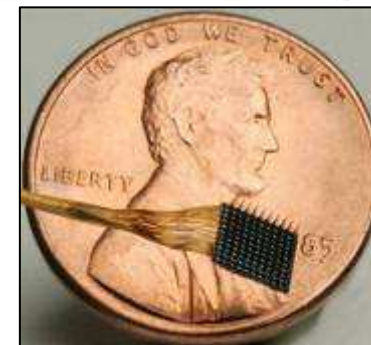
good spatial resolution

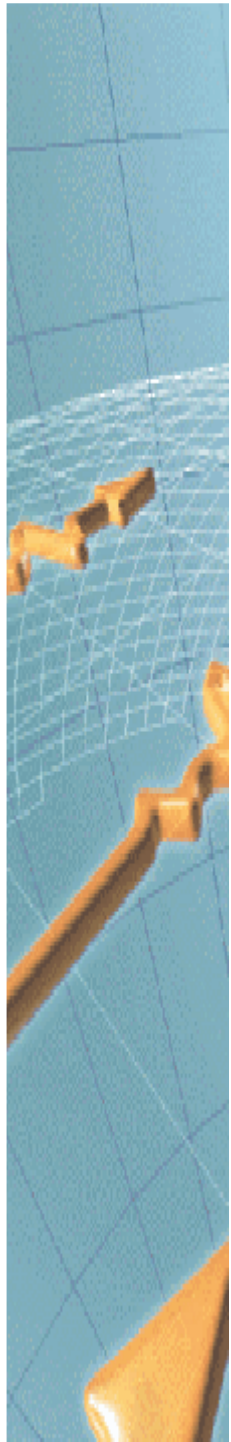


- *Micro-electrode arrays*

implanted into the brain

best signal quality





## Excursus: Measuring brain activity

### Electroencephalogram (EEG)

small electrodes (#1 - #256) attached to the surface of the scalp  
place electrodes at certain predefined positions according to the  
“international 10/20 system”

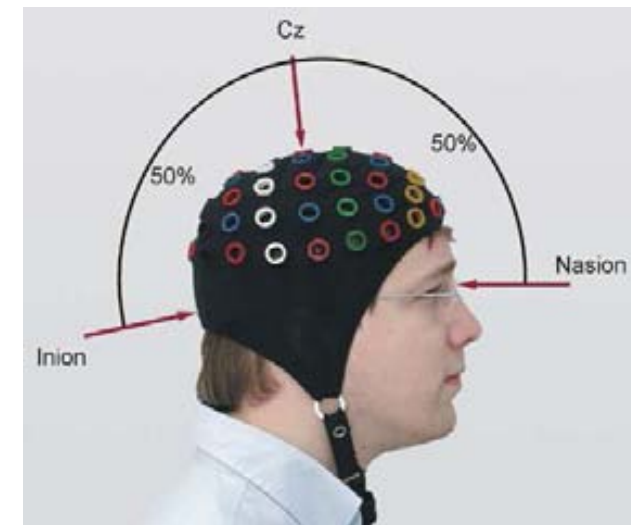


EEG amplitudes: **5 – 100  $\mu$ V**

EEG frequencies: **1 – 40 Hz**

**EEG: non-stationary time signal  
varies greatly between subjects  
low signal-to-noise ratio**

- spatio-temporal patterns
- non-invasive



## Excursus: Measuring brain activity

### Electro-corticogram (ECoG)

4 mm diameter

~ 100 electrodes

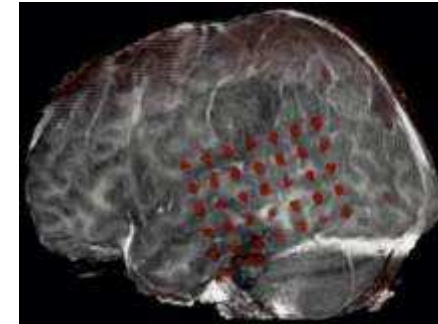
EEG amplitudes: **0.5 mV**

EEG frequencies: **1 – 100 Hz**

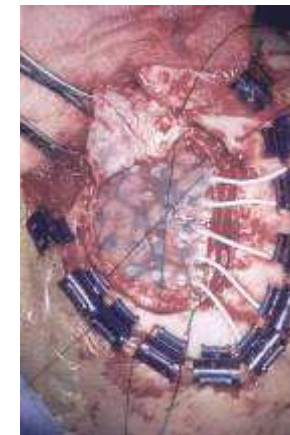
- resolution considerably better than EEG
- provides opportunity for multi-channel control
- more direct correlation to activity

**invasive**

**limited study opportunities**

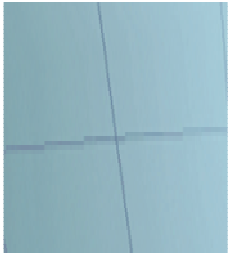


modified from University of Michigan



modified from University of Michigan



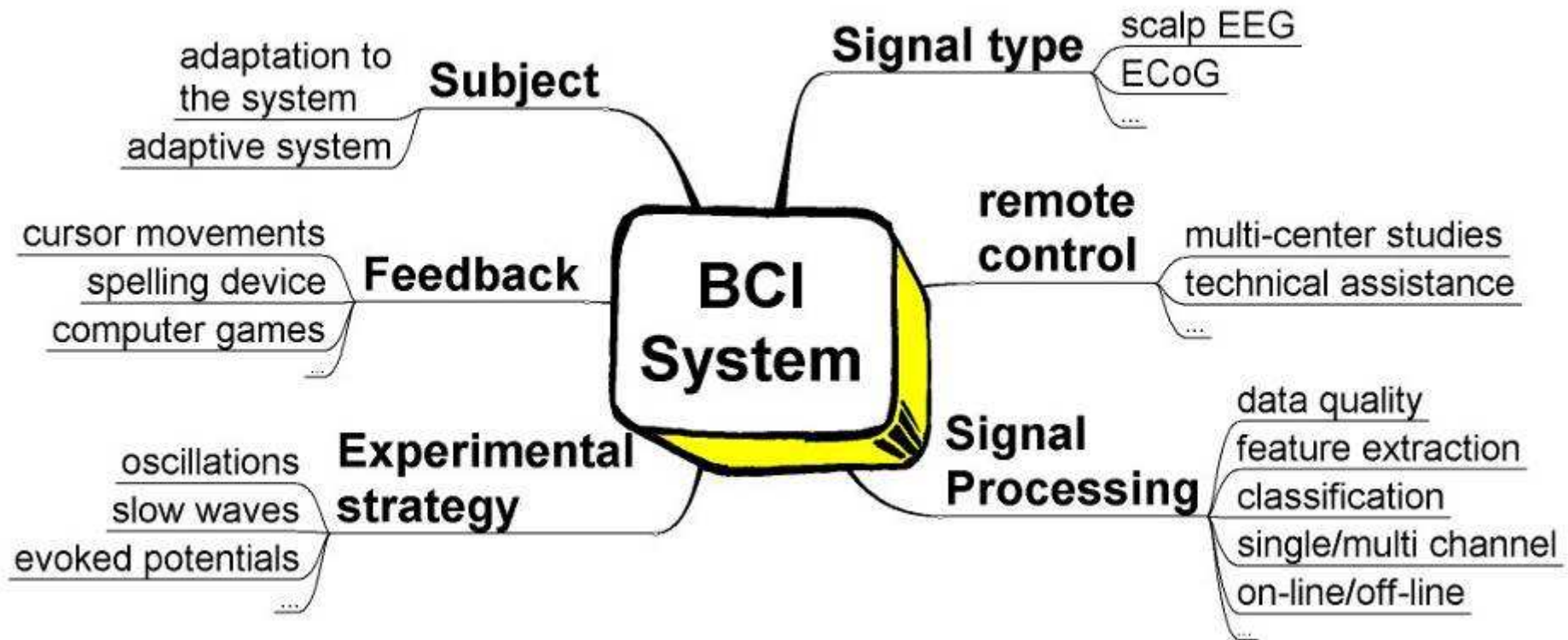


# Influencing components

adaptation  
to subject



technical issues





# Steps in BCI development

**Step 1:** Selection of parameter estimation and classification algorithms

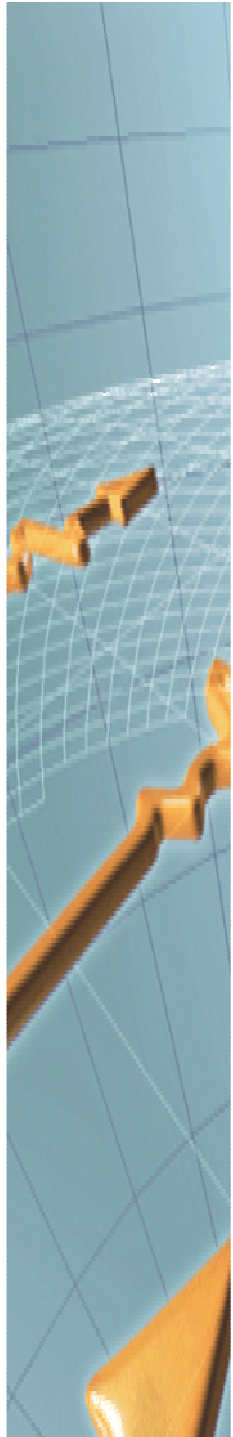
**Step 2:** Implementation of the algorithms

**Step 3:** Off-line simulation

**Step 4:** Connection to the real world

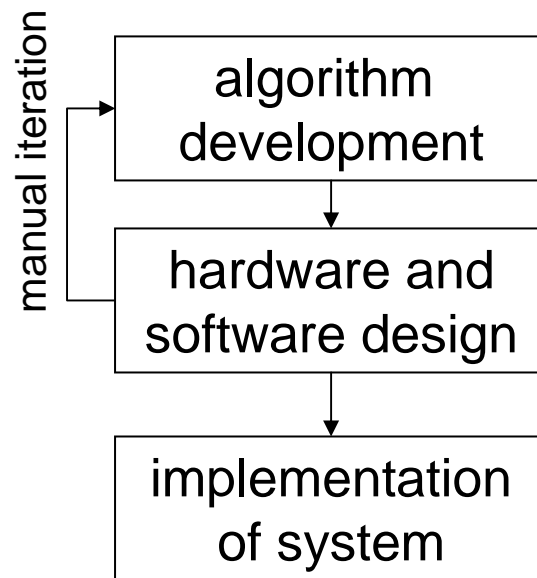
**Step 5:** Real-time code generation

**Step 6:** Real-time tests

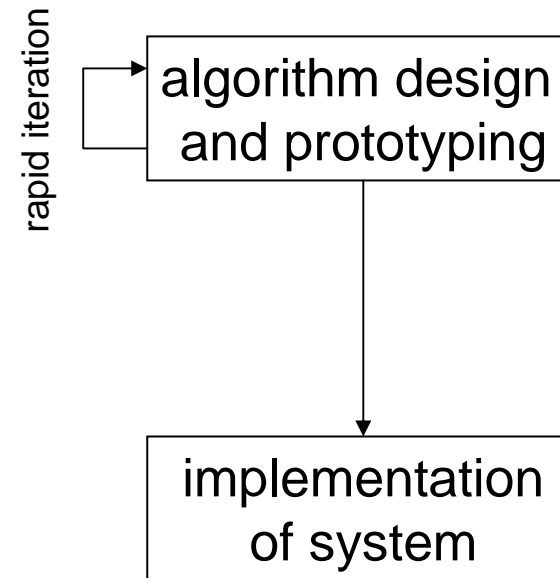


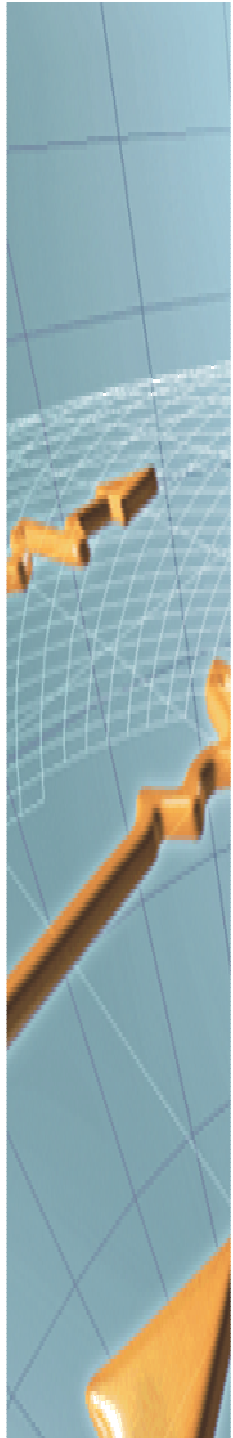
# Why Rapid Prototyping?

## traditional approach



## rapid prototyping process

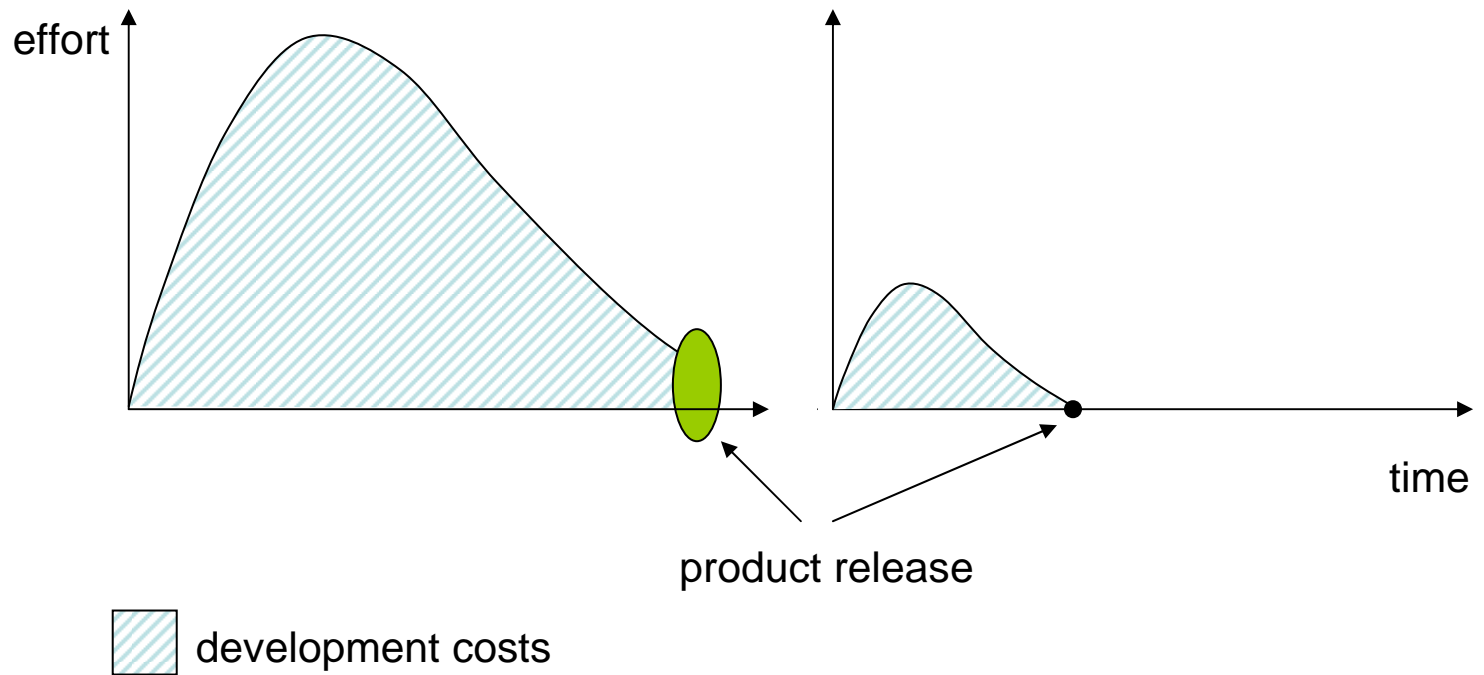




# Why Rapid Prototyping?

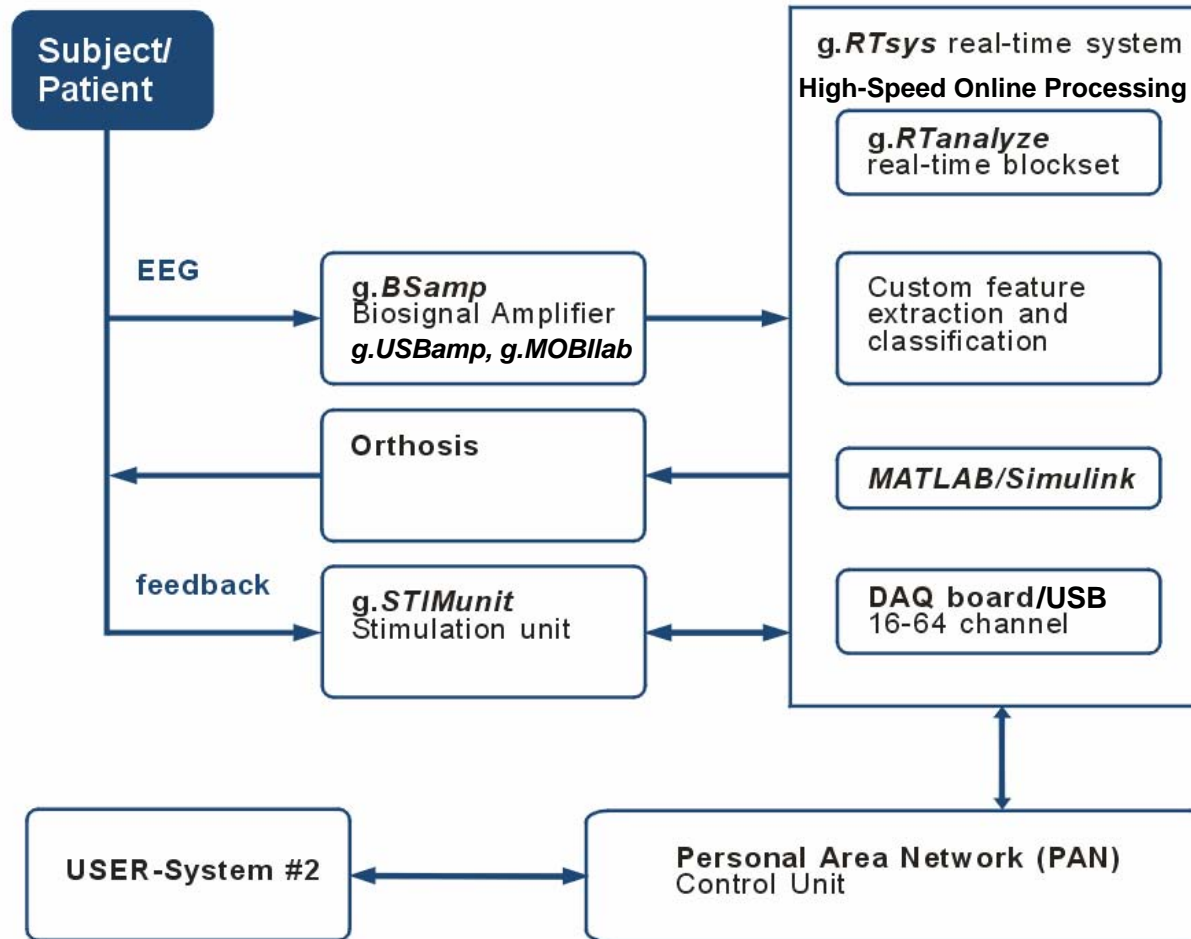
traditional approach

rapid prototyping process

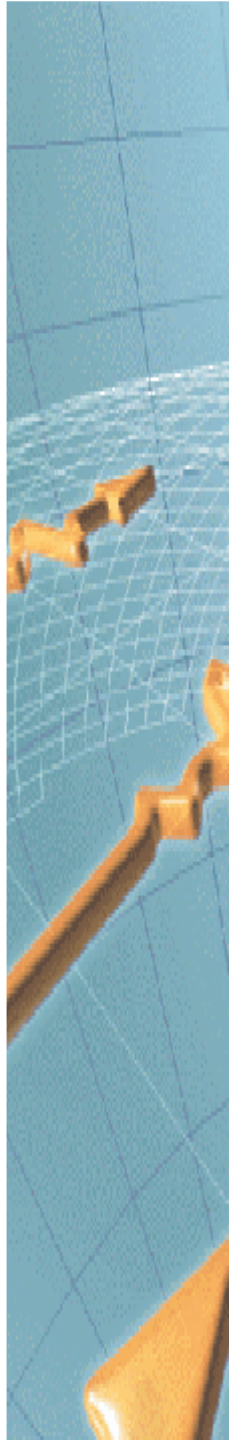


# Closed loop system g.BCIsys

USER-System #1

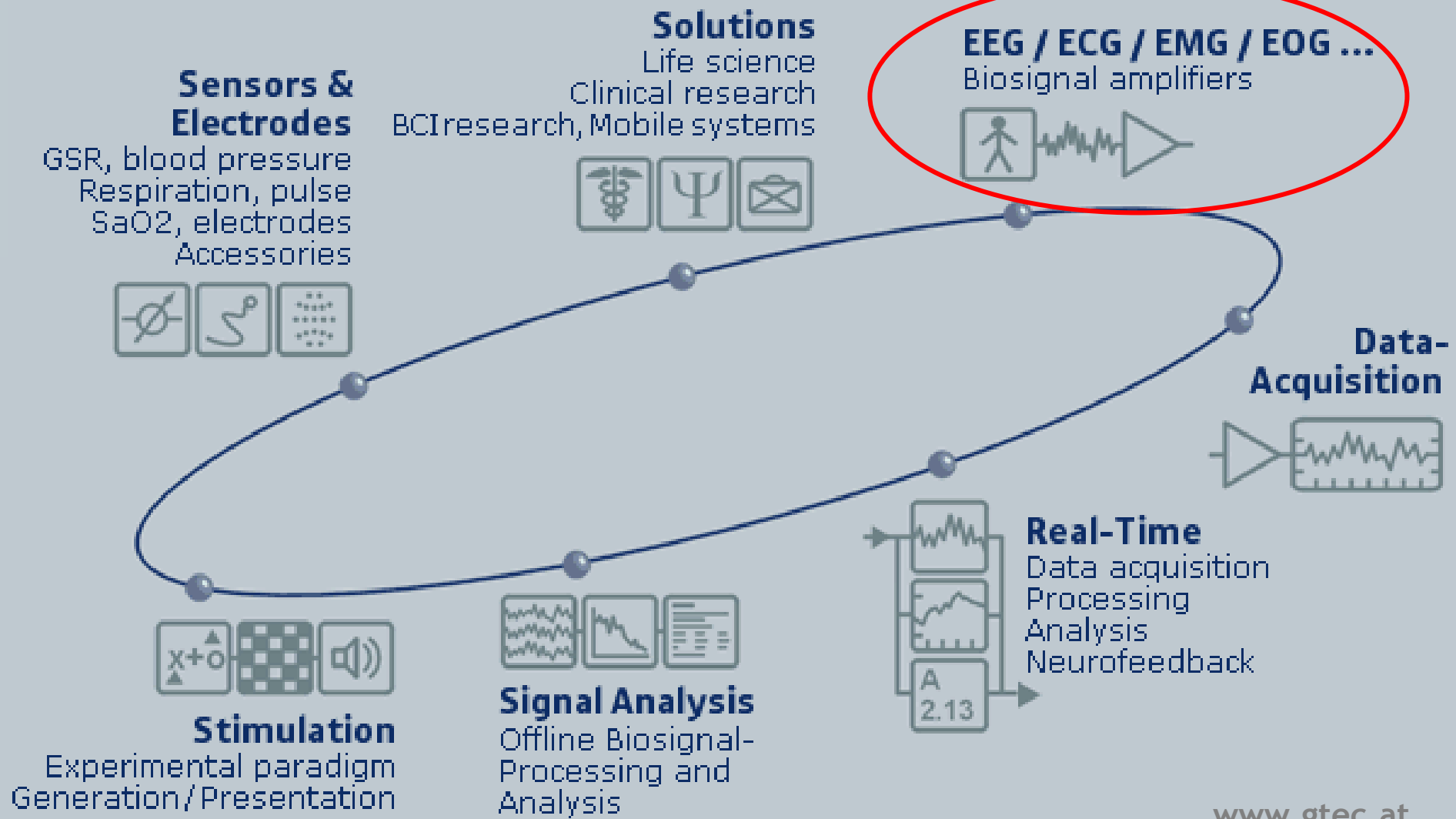






## Requirements to successfully run BCI experiments

# Product range



# Hardware Development

EEG, ECoG, EMG, EOG, ECG amplifiers  
1-128 channels



- A. USB based biosignal amplifier
  - 16 integrated 24 Bit ADCs
  - Floating point DSP
    - re-referencing
    - oversampling (~20000 times)
    - bandpass and notch filtering



- B. Mobile device
  - 2-4 AA batteries
  - 1 integrated 16 Bit ADC
  - serial/USB interface
  - 1 week operation time
  - TCP/IP remote control



- C. Stand-alone device
  - analog output
  - combine it to DAQ board (e.g. NI)
    - resolution
    - sampling frequency
  - PCI or PCMCIA board



# Software Programming Environment

## A. C++ Application Program Interface

- allows to integrate amplifier

## B. MATLAB API

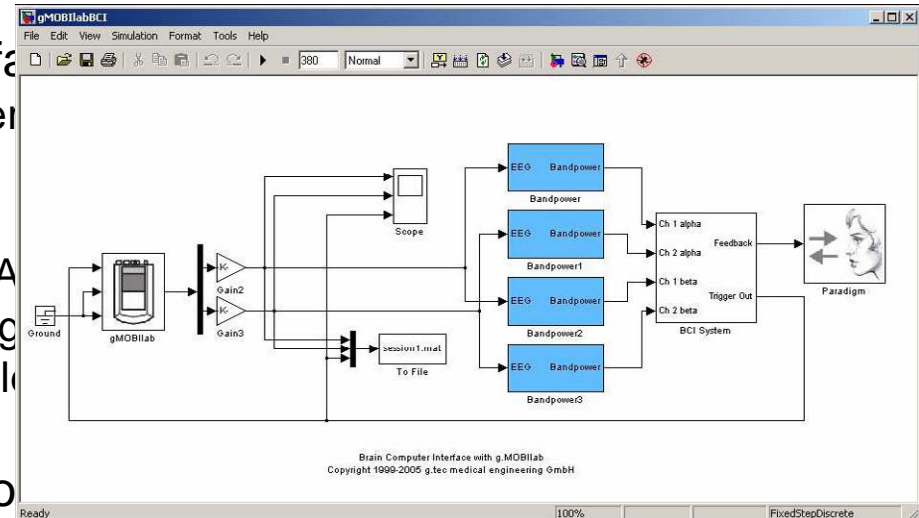
- integrate amplifiers into MA
- access to all toolboxes (Sig
- access to user written M-file

## C. Simulink Highspeed on-line Pro

- amplifier device driver block under Simulink
- copy the block into Simulink model and connect the signal processing (S-functions) and paradigm blocks (MATLAB code)
- just exchange the amplifier device driver and work with the same signal processing blocks

*All three options give full access to hardware*

- bandpass, notch settings
- sampling frequency
- impedance check
- data buffer
- ...



# Selection of parameter estimation algorithms

## (I) Non adaptive estimation:

Band power (optimal frequency bands)

KALCHER et al. 1993

AR parameters

PFURTSCHELLER et al. 1997

WOLPAW 1997 ✓

Hjorth parameters

GUGER 1997, OBERMAIER et al. 1999

Common Spatial Patterns (CSP)

MÜLLER - GERKING et al. 1999,

RAMOSER 2000

GUGER 2000

## (II) Adaptive estimation

AAR parameters (RLS algorithm)

SCHLÖGL

## Selection of classification algorithms

### (I) Neural networks ( $\geq 2$ classes)

LVQ, DSLVQ

FLOTZINGER et al. 1994

PREGENZER and PFURTSCHHELLER 1999

### (II) Linear discriminant (2 classes) ✓

signed distance function

PFURTSCHHELLER et al. 1998

LUGGER et al. 1998

### (III) Hidden Markov Models ( $\geq 2$ classes)

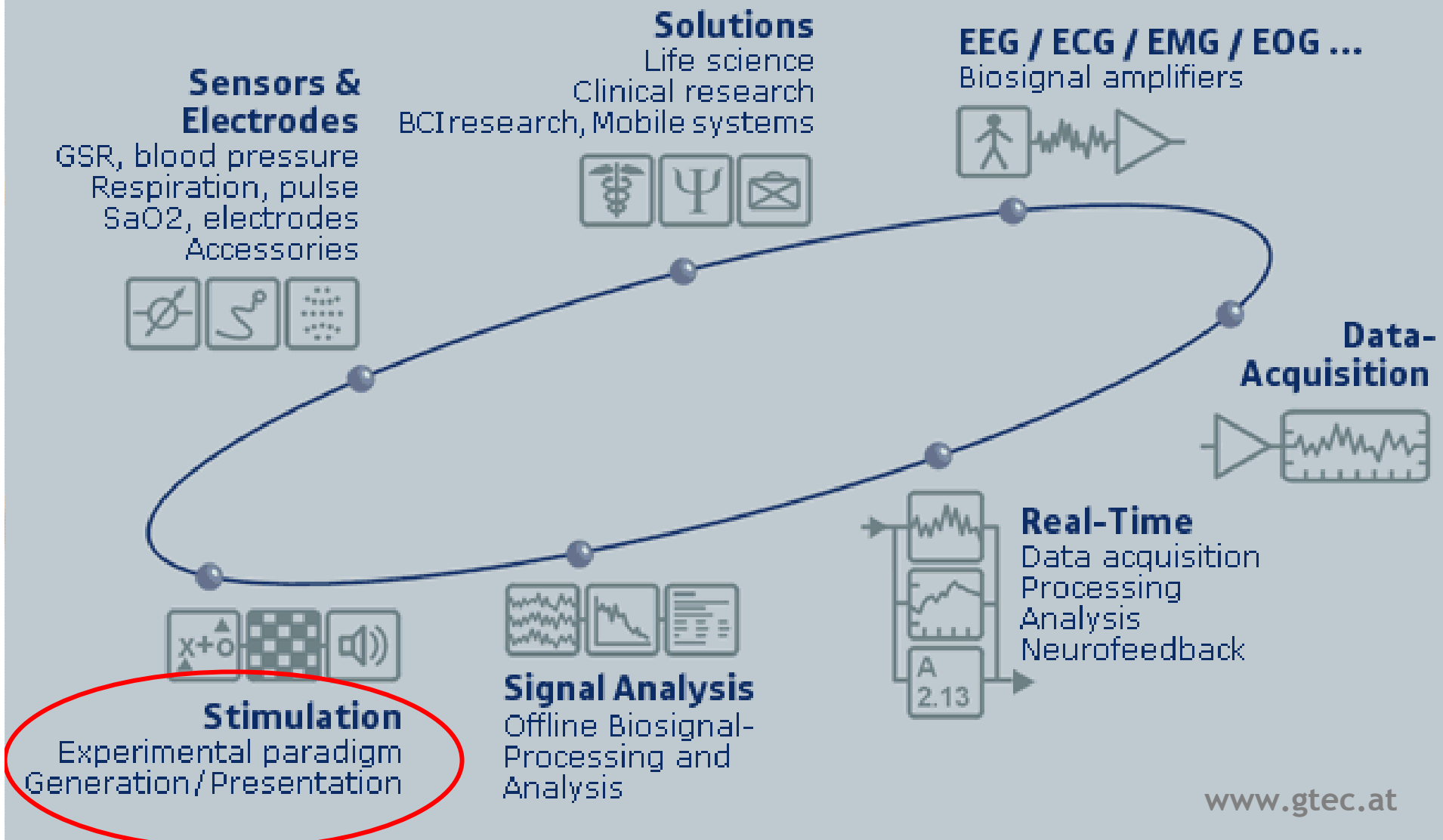
OBERMAIER et al. 2001

### (IV) Support-Vector Machines

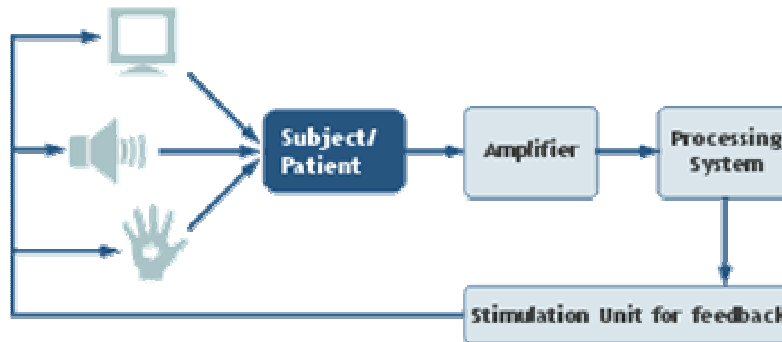
MÜLLER



# Product range

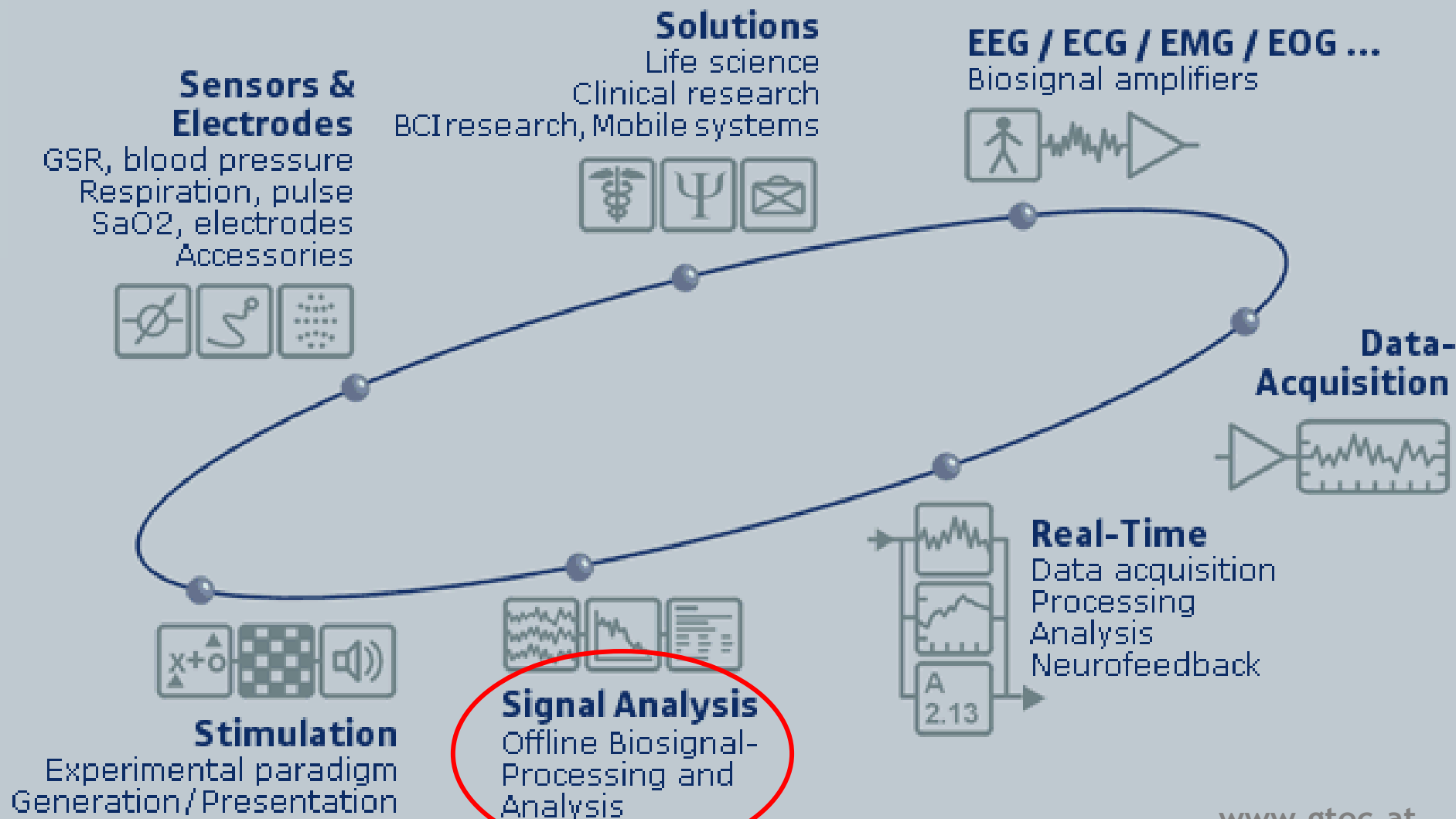


## g.STIMunit – Stimulation Unit

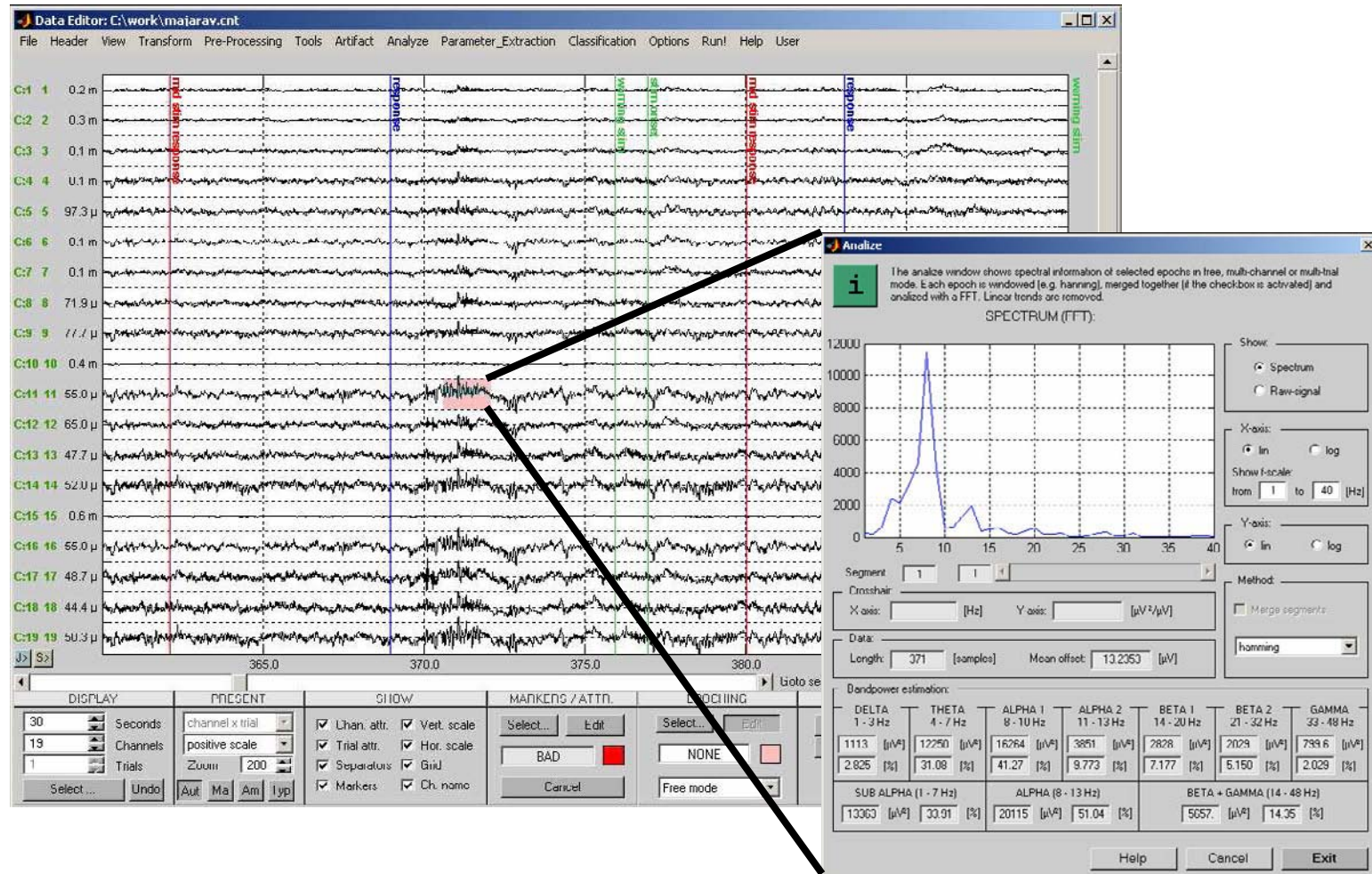


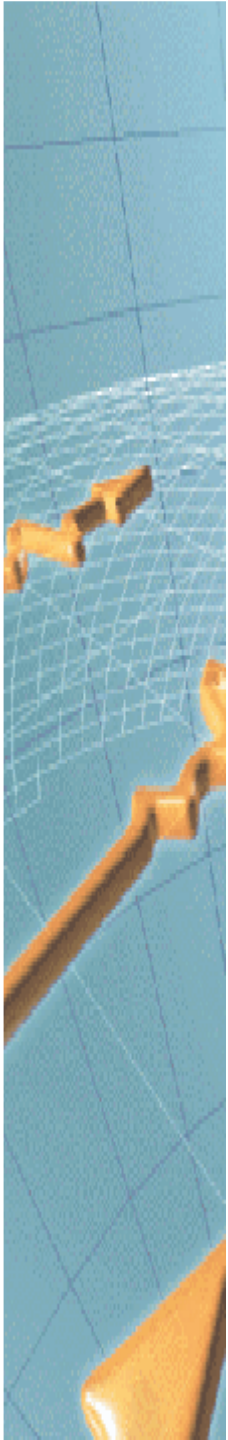
- library for standard neuro- and psycho-physiological paradigms
- accurate timing for visual, auditory and tactile stimulation
- MATLAB based paradigm parser for easy development of user-specific experiments
- logging of subject responses and real-time biofeedback to the subject/patient
- create easily test batteries for cognitive tasks (human intelligence and neural efficiency) and motor tasks (rehabilitation for stroke, epilepsy, Parkinson's disease)
- simulate traffic flow or flight control scenes to investigate the workload of pilots

# Product range



# g.BSanalyze – Offline Processing Software



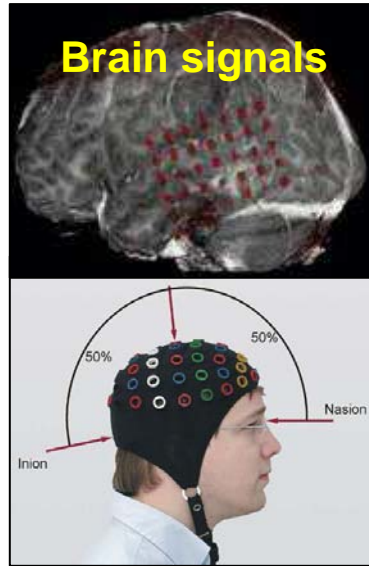


## Requirements for high quality EEG recordings and BCI applications

- The lab: shielding, light, monitor position, chair, silence
- Technical aspects: amplifier placement, electrode leads, type of electrode/cap, impedance, ...
- The artifact problem: amplifier, electrodes, physiological artifacts, systematic artifacts
- Instruction of the subject: fixation cross, muscle relax, eye-blinks, duration of runs, breaks, motivation



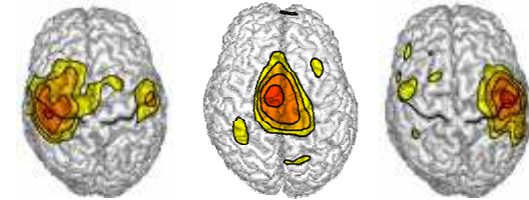
# How can the computer read your thoughts?



**High-end and robust  
brain signal amplifier**



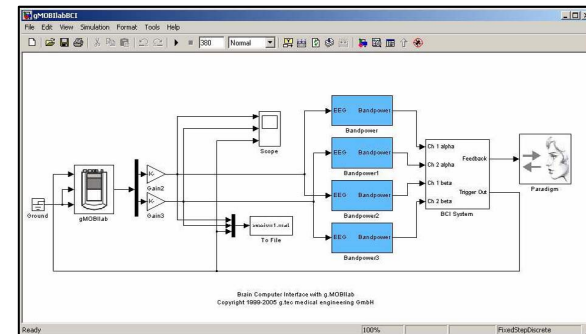
**Signal processing &  
Pattern recognition**



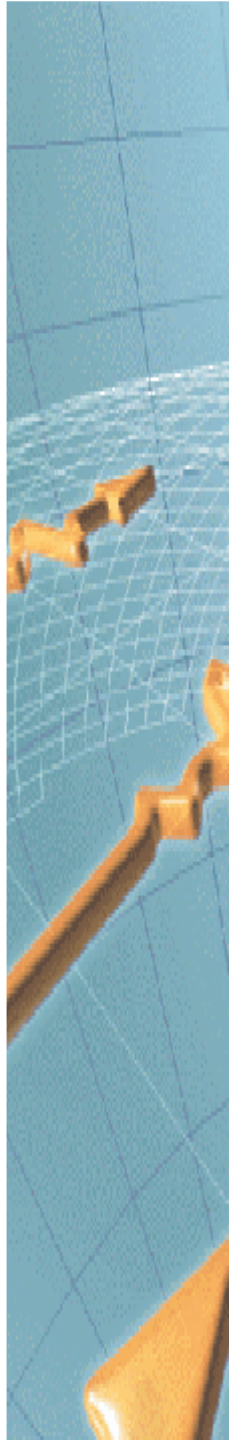
**Produce unique brain  
activity patterns**

**Think about a  
hand/foot movements**

**Concentrate on an  
event - flashing letter**







## Changes of brain electrical activity and mental strategies

- **Slow cortical potentials (anticipation tasks)**  
DC-derivation, artifact problem, difficult strategy, feedback method
- **Steady state evoked potentials (focus of attention task)**  
Thalamic gating, various methods of stimulation (visual, tactile, electrical, auditory, ...)
- **Phase-locked potentials, readiness potentials, motor potentials (motor tasks)**  
Template matching, spatial distribution, large number of electrodes, ECoG electrode grid
- **Event-related, non-phase-locked changes of oscillatory activity ERD/ERS (motor imagery tasks)**  
Changes of mu-rhythm, alpha activity and beta activity over sensorimotor areas, Imageries of hand-, foot-, tongue- movements



## Communication for the 'locked-in'

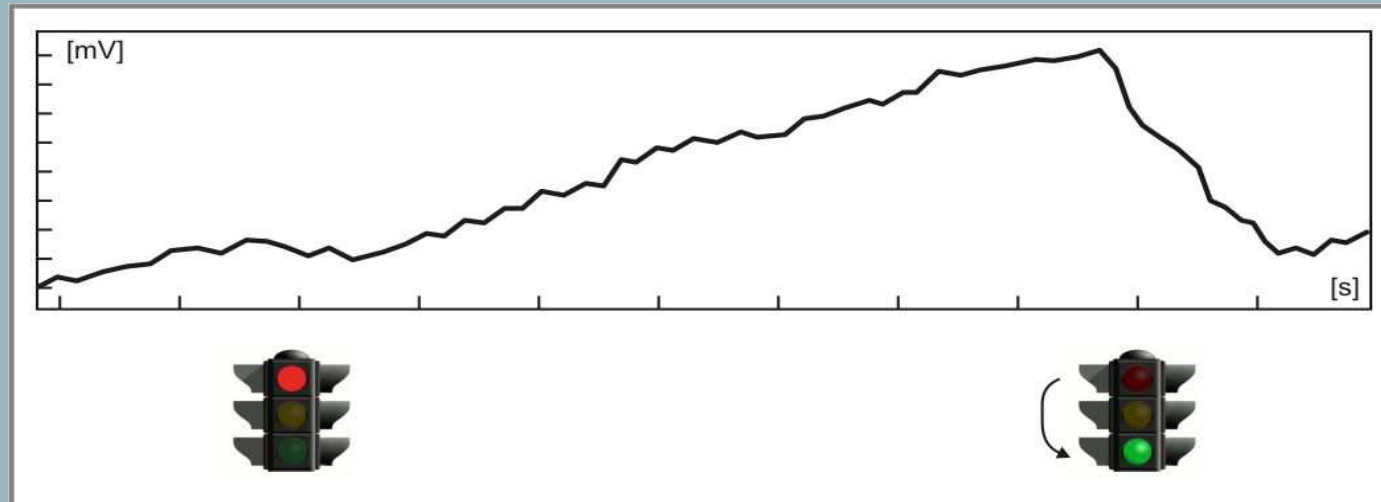


**ALS patient in Germany using a BCI system for communication**  
Birbaumer, Kübler, Hinterberger,... Tübingen

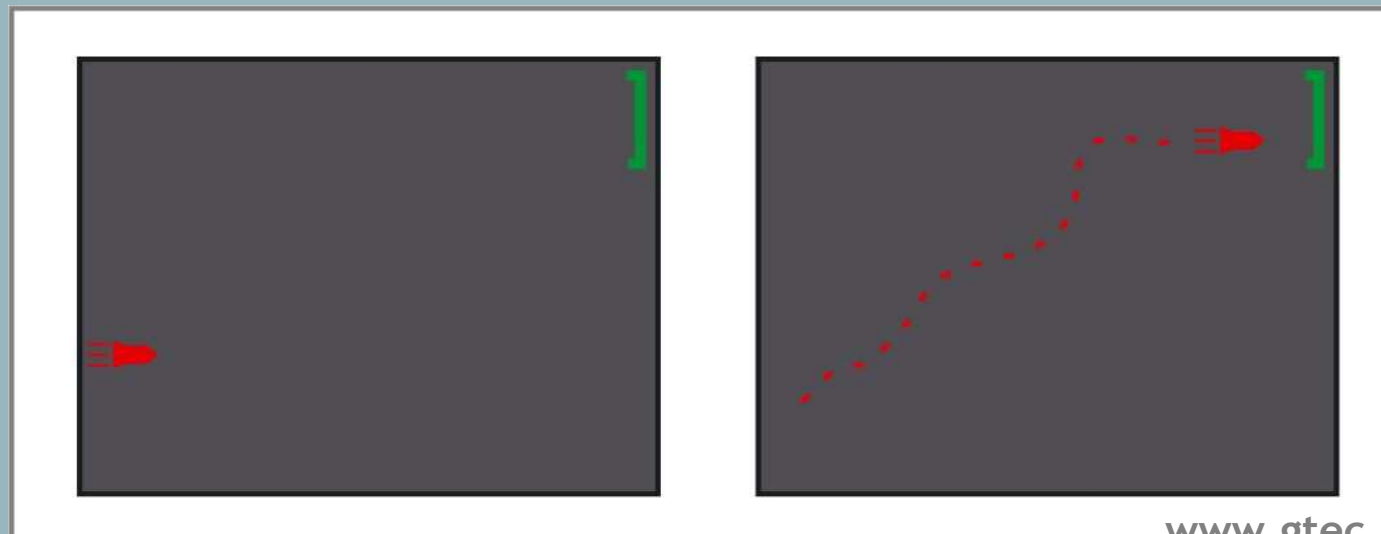


# Slow Cortical Potentials

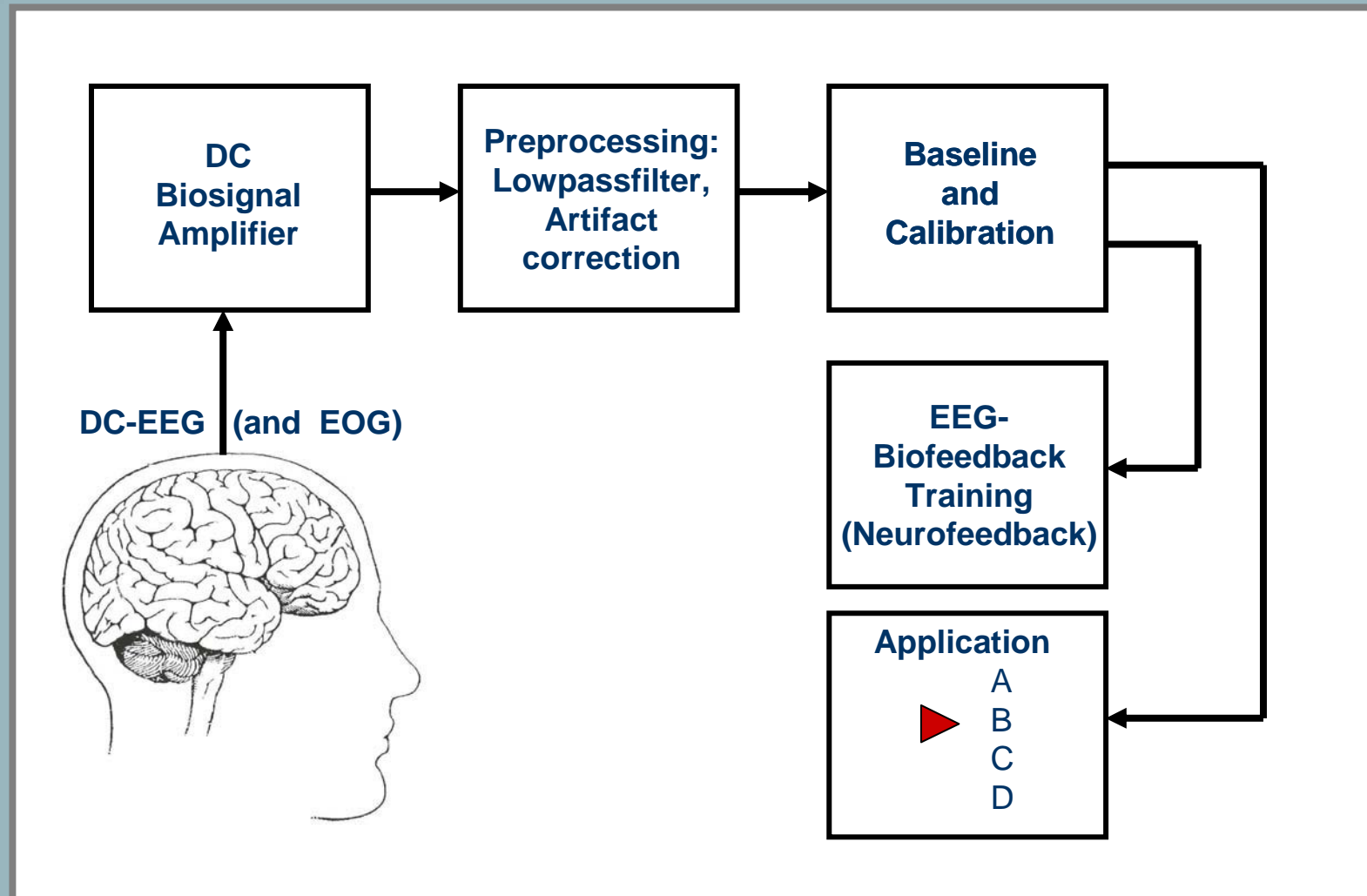
**MENTAL  
TASK**

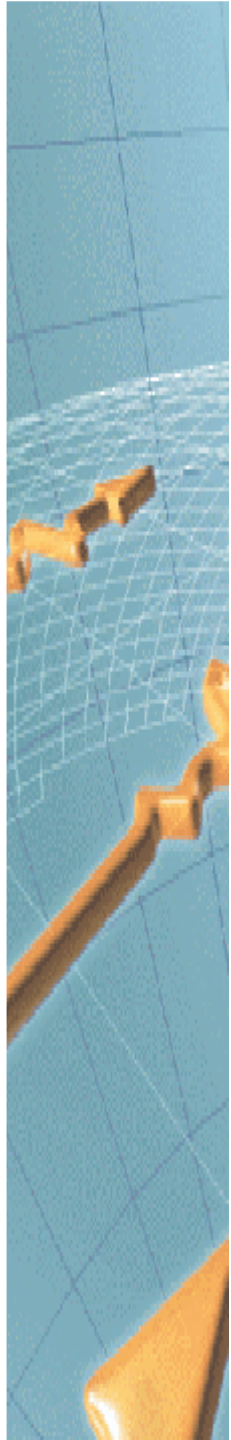


**BIOFEEDBACK  
TRAINING**



## Slow Cortical Potentials



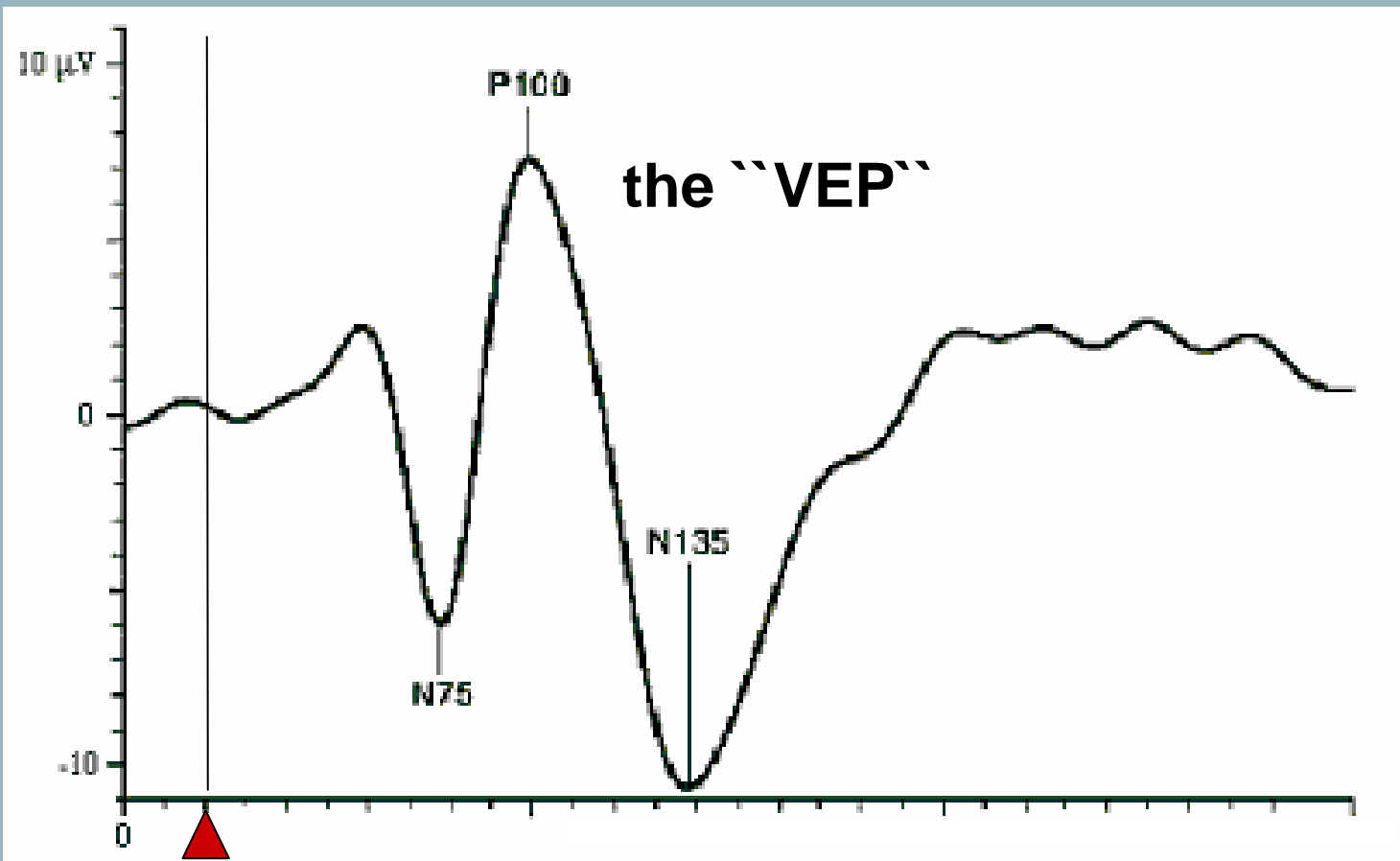


## Changes of brain electrical activity and mental strategies

- Slow cortical potentials (anticipation tasks)  
DC-derivation, artifact problem, difficult strategy, feedback method
- Steady state evoked potentials (focus of attention task)  
Thalamic gating, various methods of stimulation (visual, tactile, electrical, auditory, ...)
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Template matching, spatial distribution, large number of electrodes, ECoG electrode grid
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ERD/ERS (motor imagery tasks)  
Changes of mu-rhythm, alpha activity and beta activity over sensorimotor areas,  
Imageries of hand-, foot-, tongue- movements



# Steady-State Visual Evoked Potentials (SSVEP)







# Steady-State Visual Evoked Potentials (SSVEP)

## Frequency of stimulation

0 ... 2 Hz

3 ... 5 Hz

6 ... 24 Hz

## Brain response

transient (single) VEP

undefined response

SSVEP



# Steady-State Visual Evoked Potentials (SSVEP)

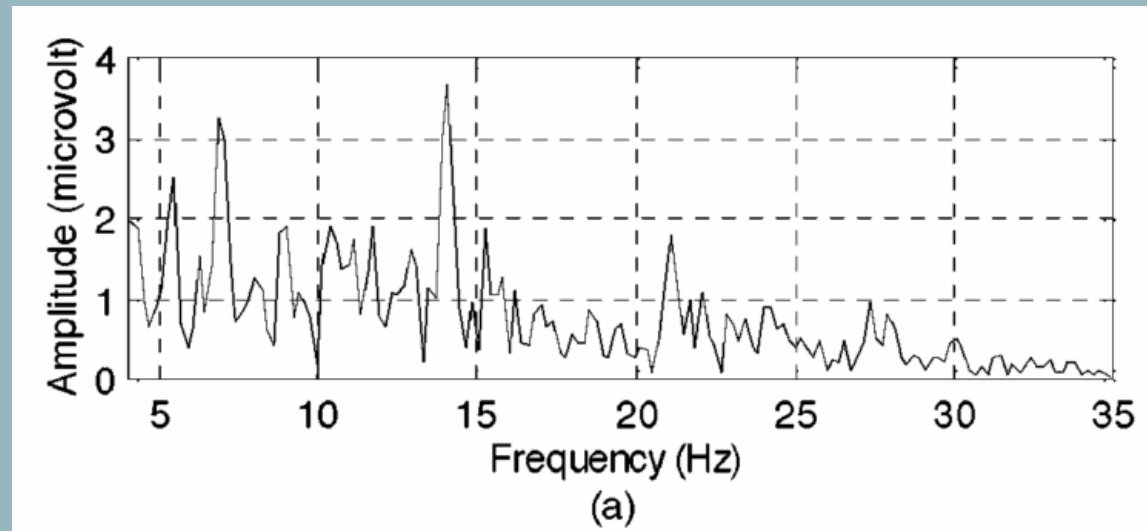
7 Hz





## Steady-State Visual Evoked Potentials

**7 Hz**





# Steady-State Visual Evoked Potentials (SSVEP)





## Steady-State Visual Evoked Potentials

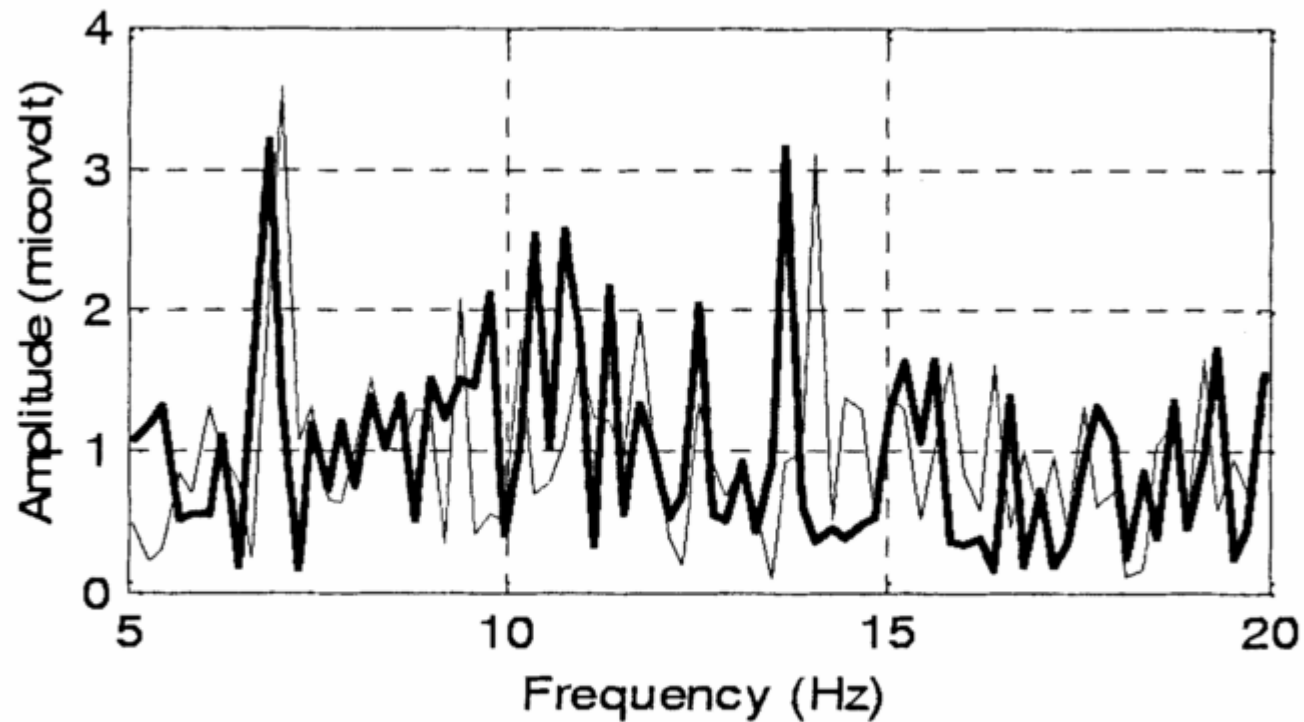
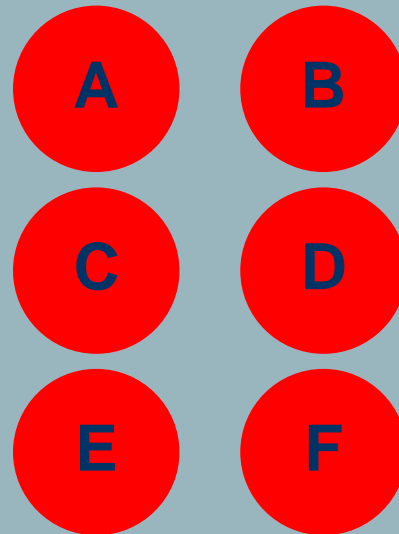


Fig. 1. Amplitude spectra of SSVEPs induced by 6.83- (thick) and 7.03-Hz (thin) visual stimulation.



## Steady-State Visual Evoked Potentials (SSVEP)

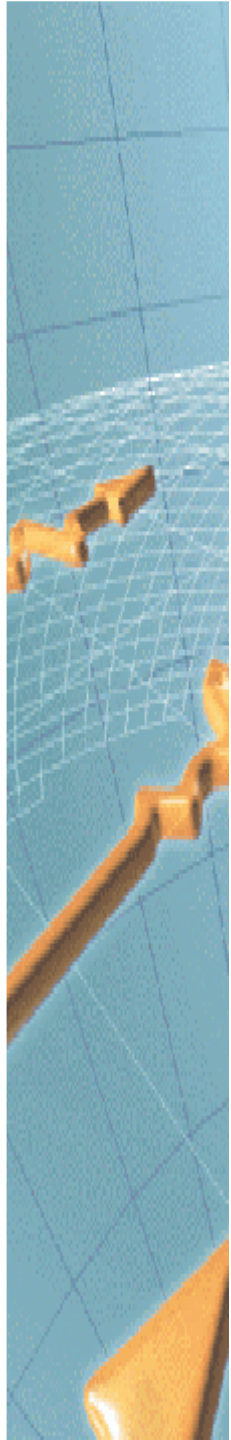


**up to 48 different frequencies possible!**





## ERD/ERS BCI



## Changes of brain electrical activity and mental strategies

- Slow cortical potentials (anticipation tasks)  
DC-derivation, artifact problem, difficult strategy, feedback method
- Steady state evoked potentials (focus of attention task)  
Thalamic gating, various methods of stimulation (visual, tactile, electrical, auditory, ...)
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ERD/ERS (motor imagery tasks)  
Changes of mu-rhythm, alpha activity and beta activity over sensorimotor areas,  
Imageries of hand-, foot-, tongue- movements

## The ``Motor Imagery Task``

**Event-related desynchronization (ERD) and synchronization (ERS) over sensory-motor areas occur for ...**

**... planning of movements**

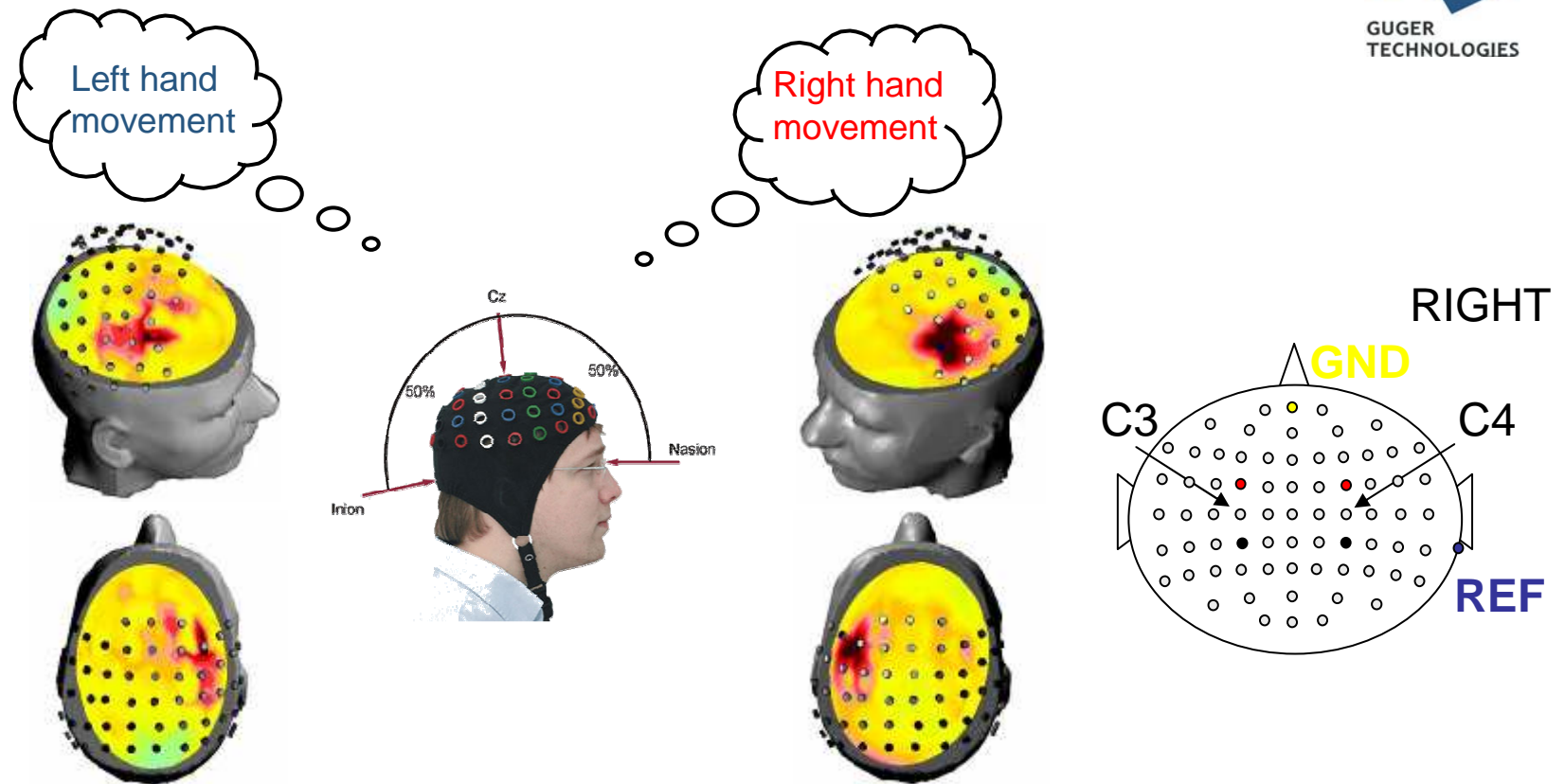
**... execution of movements**

**... imagination of movements**

**... passive movements**

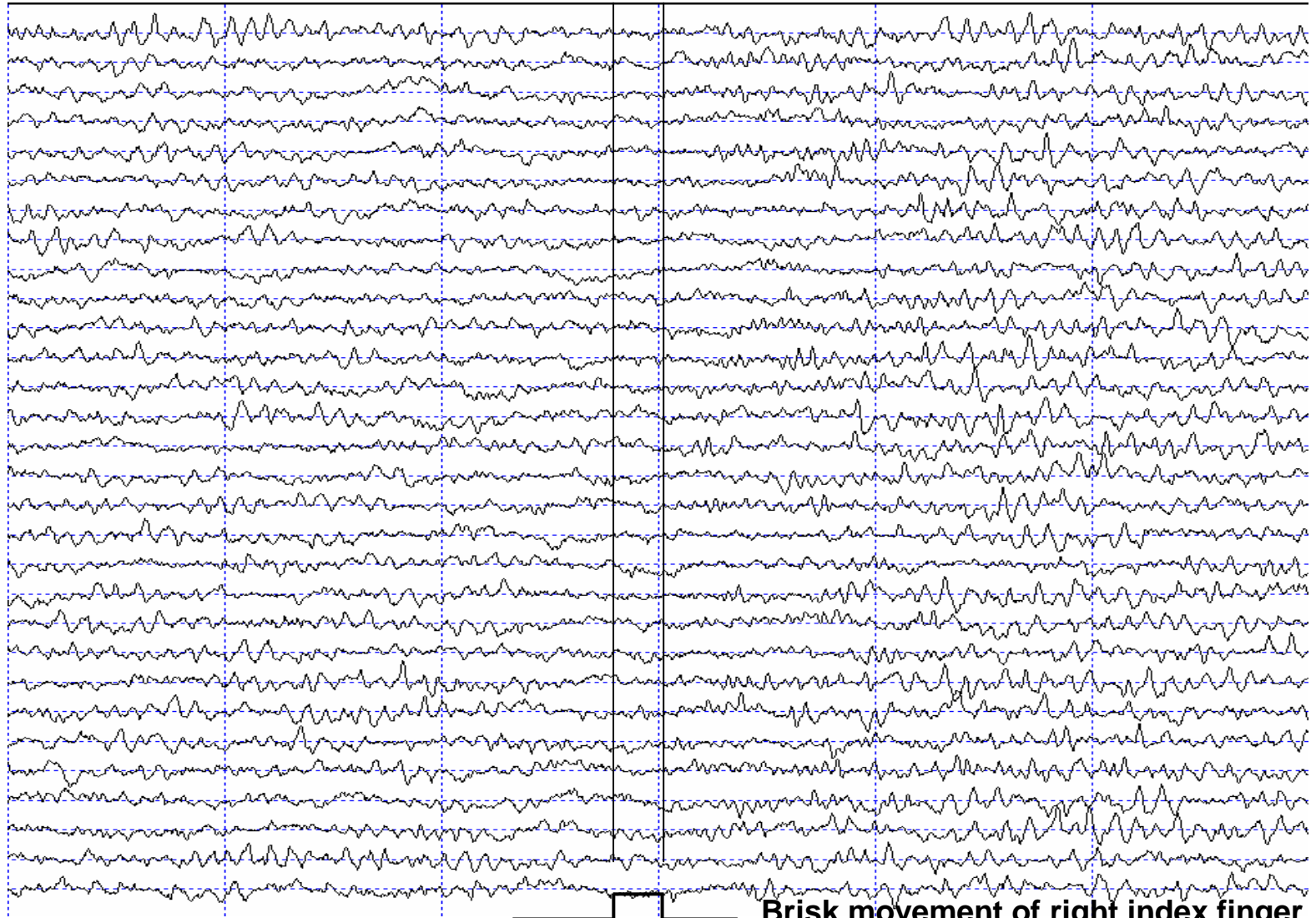
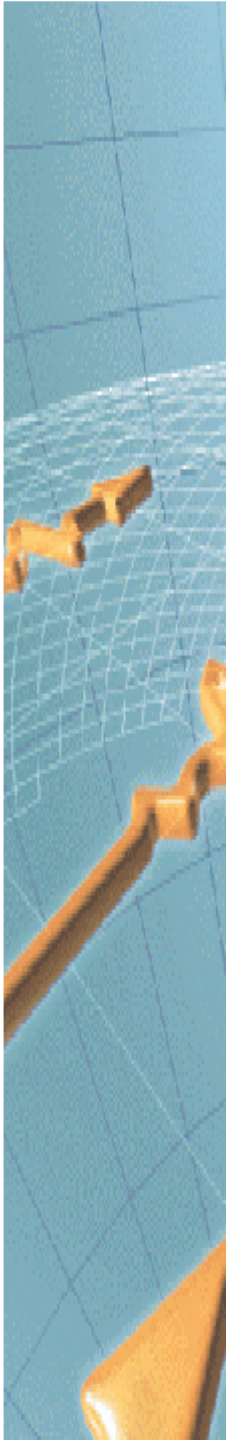
**(... observation of movements)**

## Physiological Background – why does it work



Imagination of hand movement causes an ERD which is used to classify the side of movement. The desynchronization occurs in motor and related areas of the brain. Therefore, for analyzing and classifying ERD-patterns the electrodes must be placed close to sensorimotor areas.

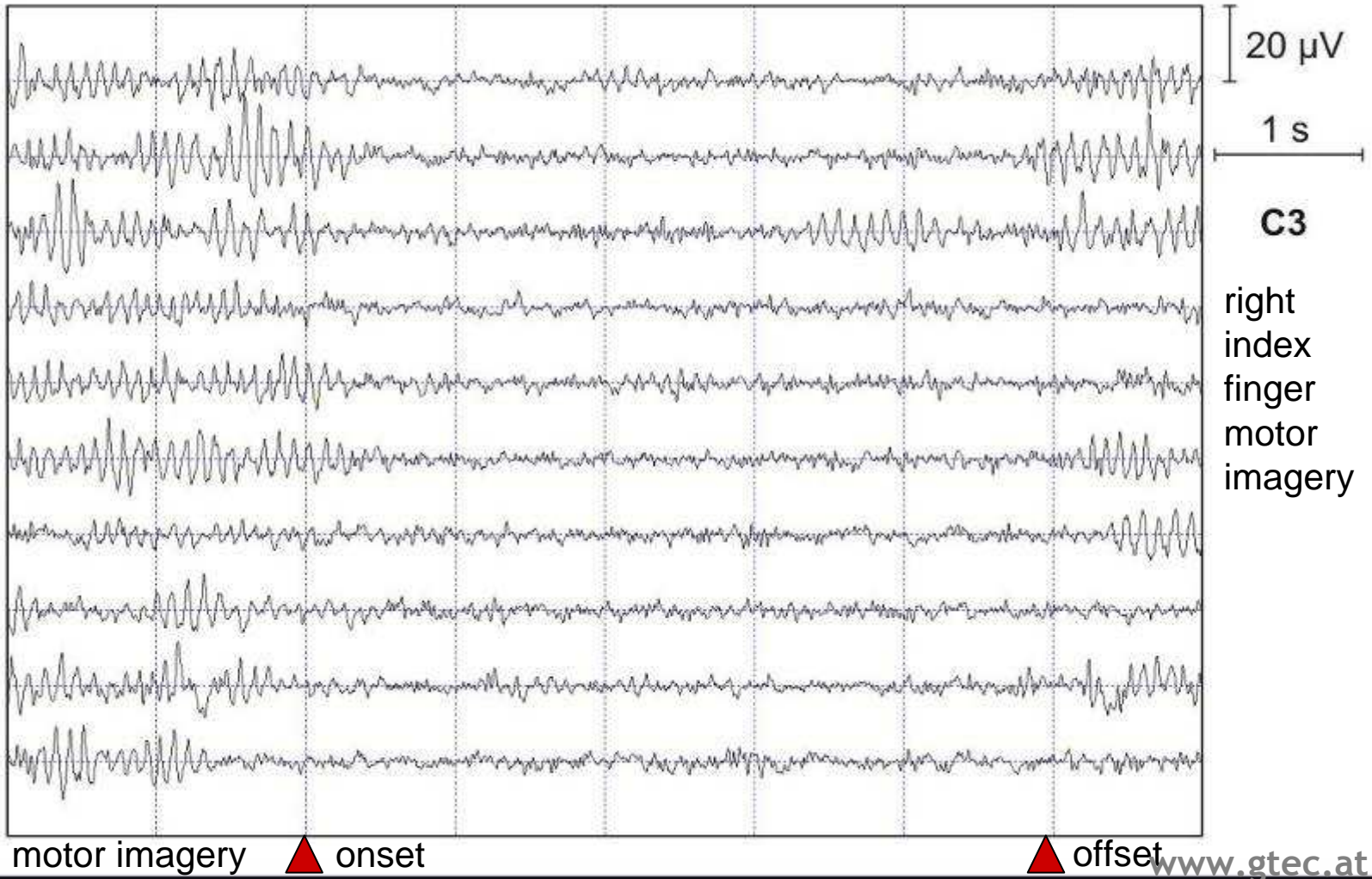
# C3 The `Finger Movement Task`



Brisk movement of right index finger



# Oscillatory EEG Activity (example)



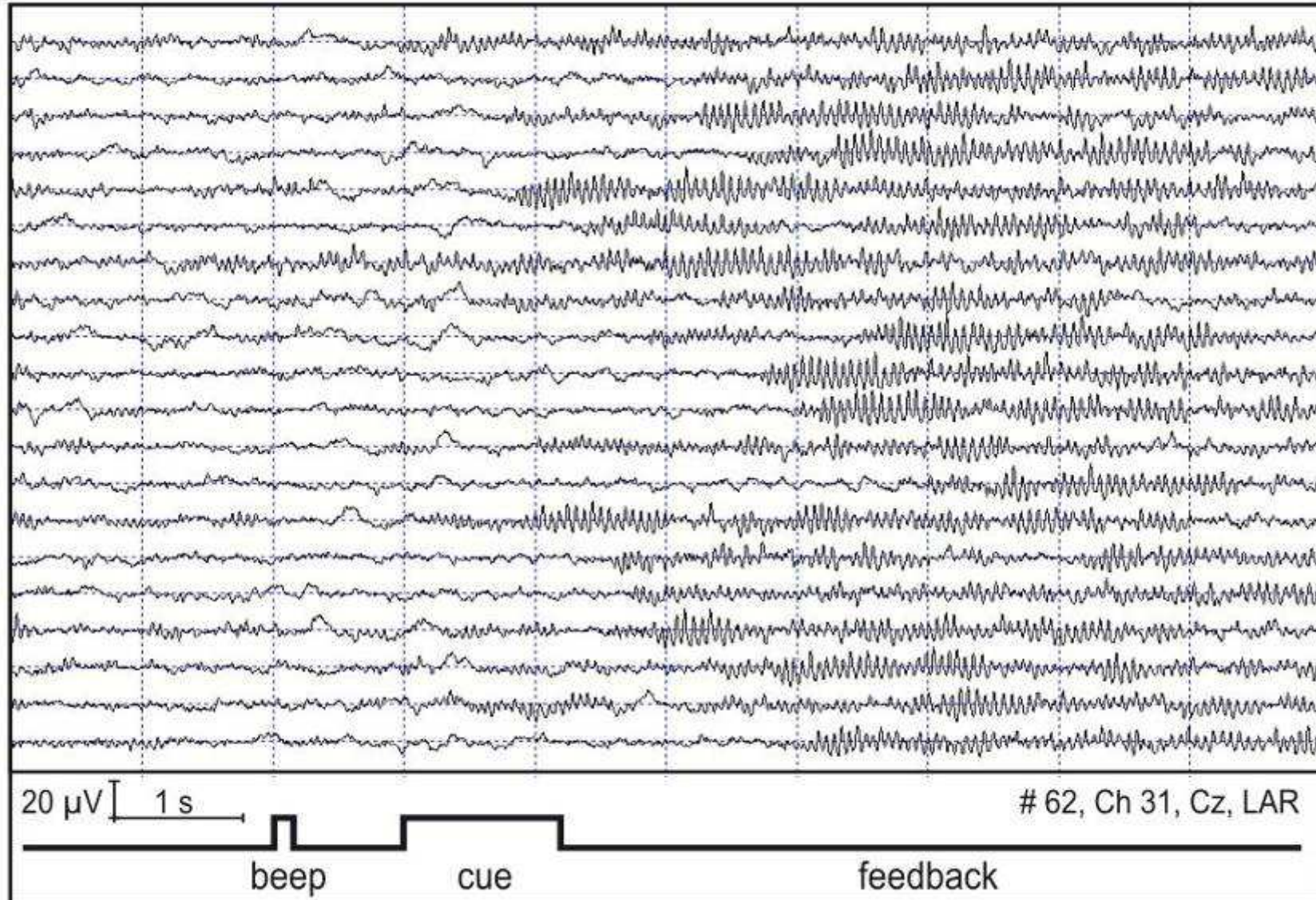
motor imagery

▲ onset

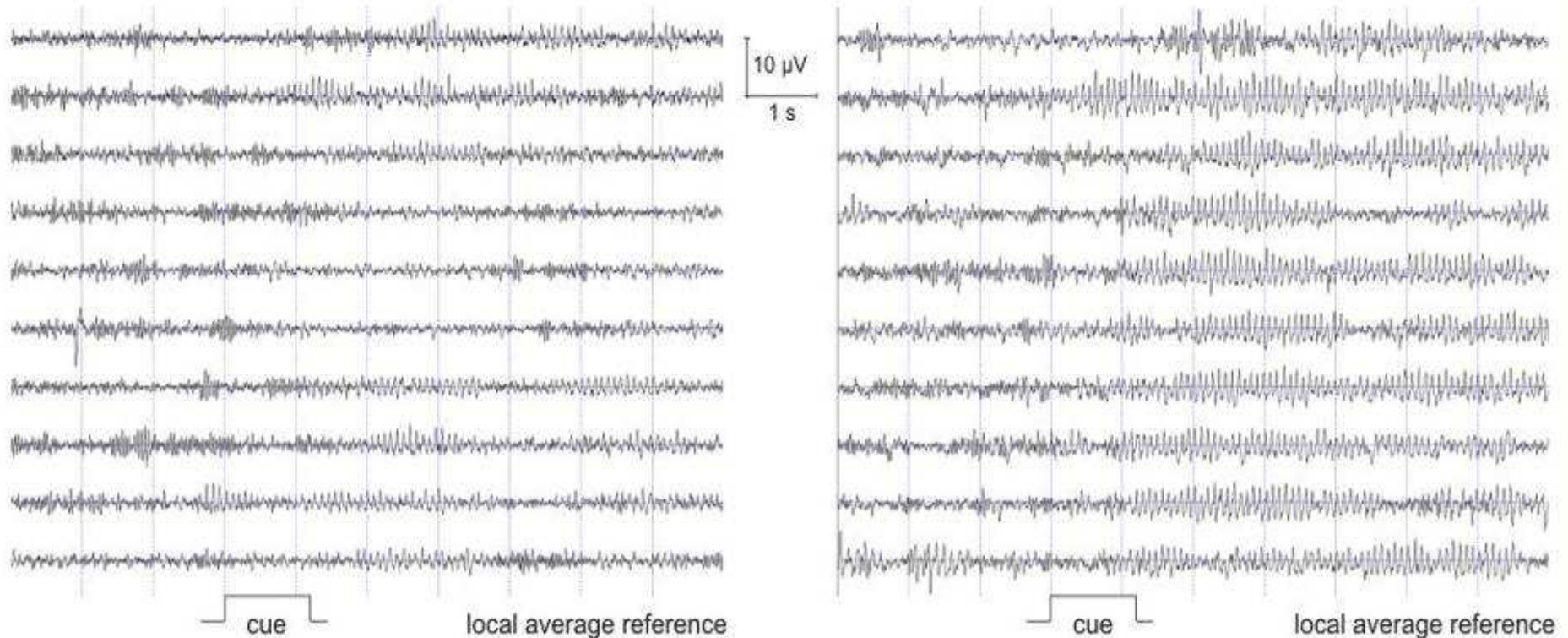
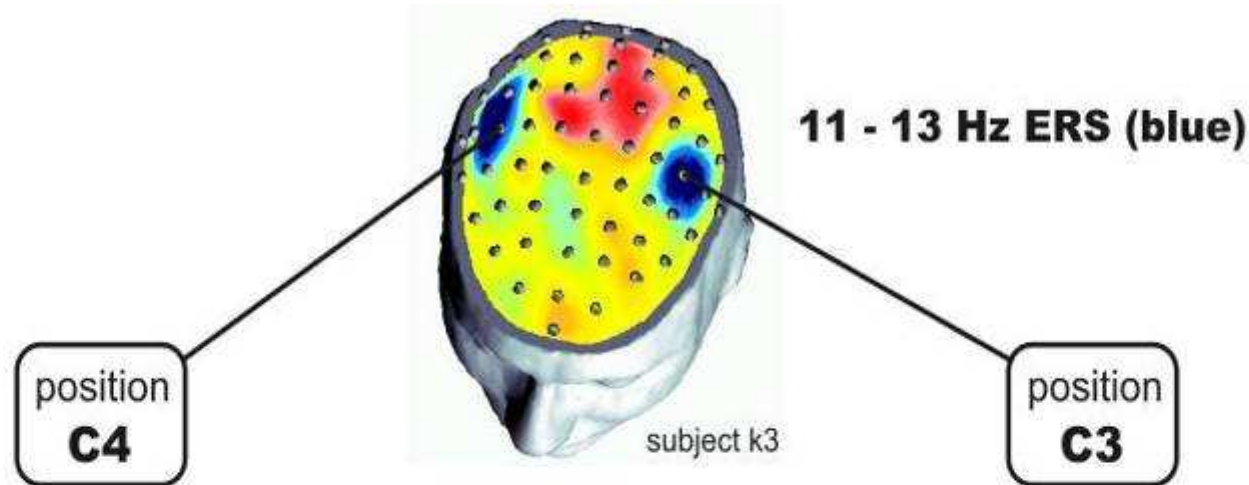
▲ offset



# Oscillatory EEG Activity (example)

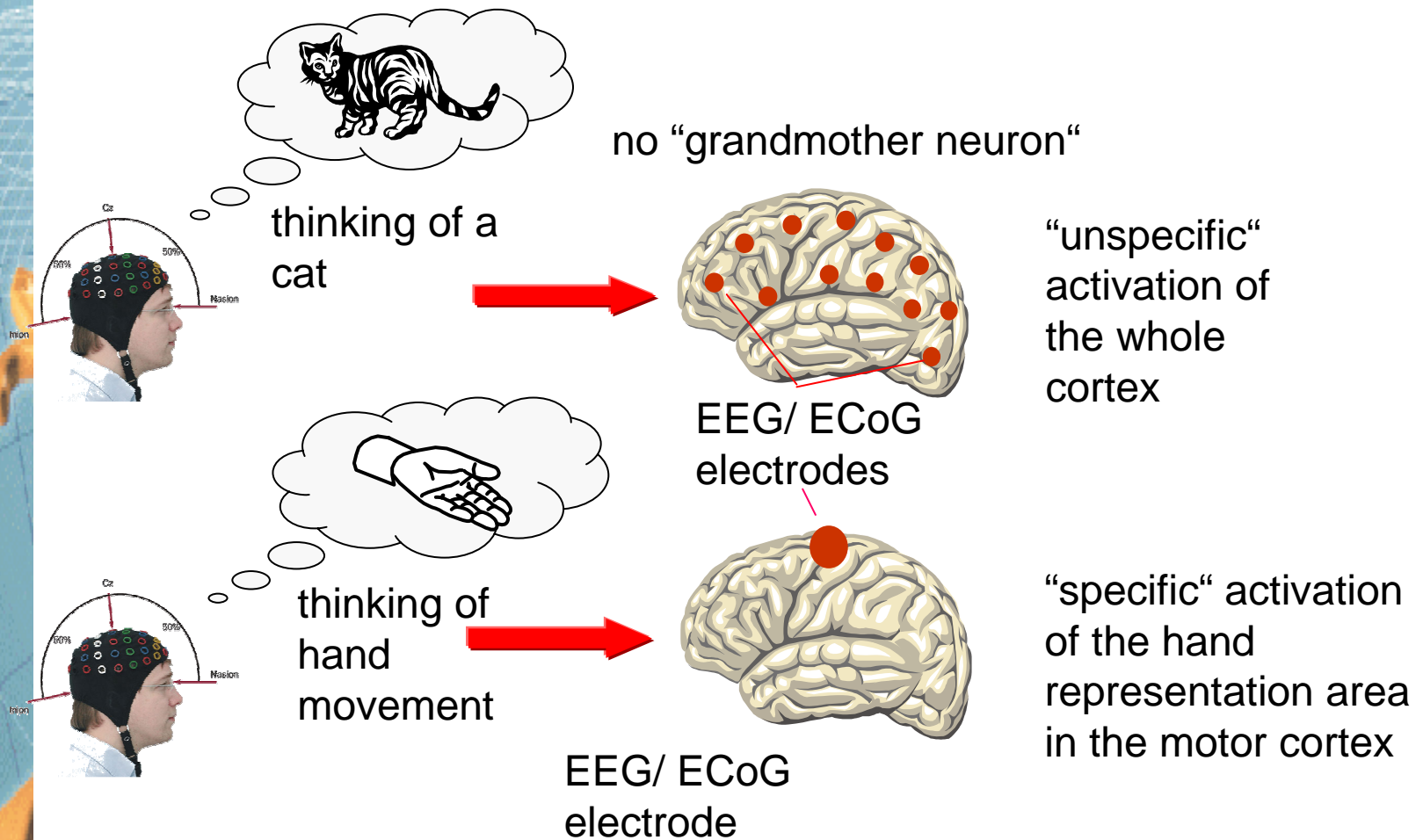


# Hand-area mu-ERS during foot motor imagery



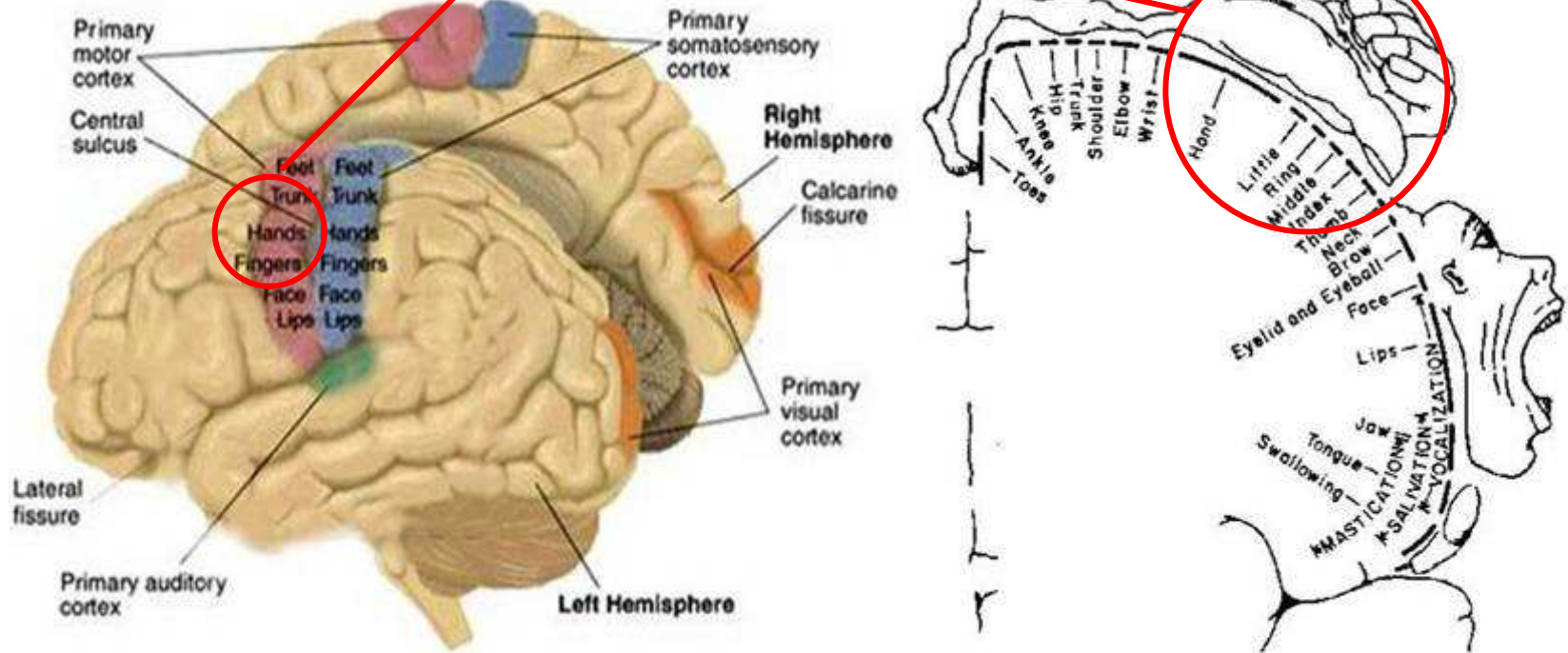


# Which type of “thought” should be used?

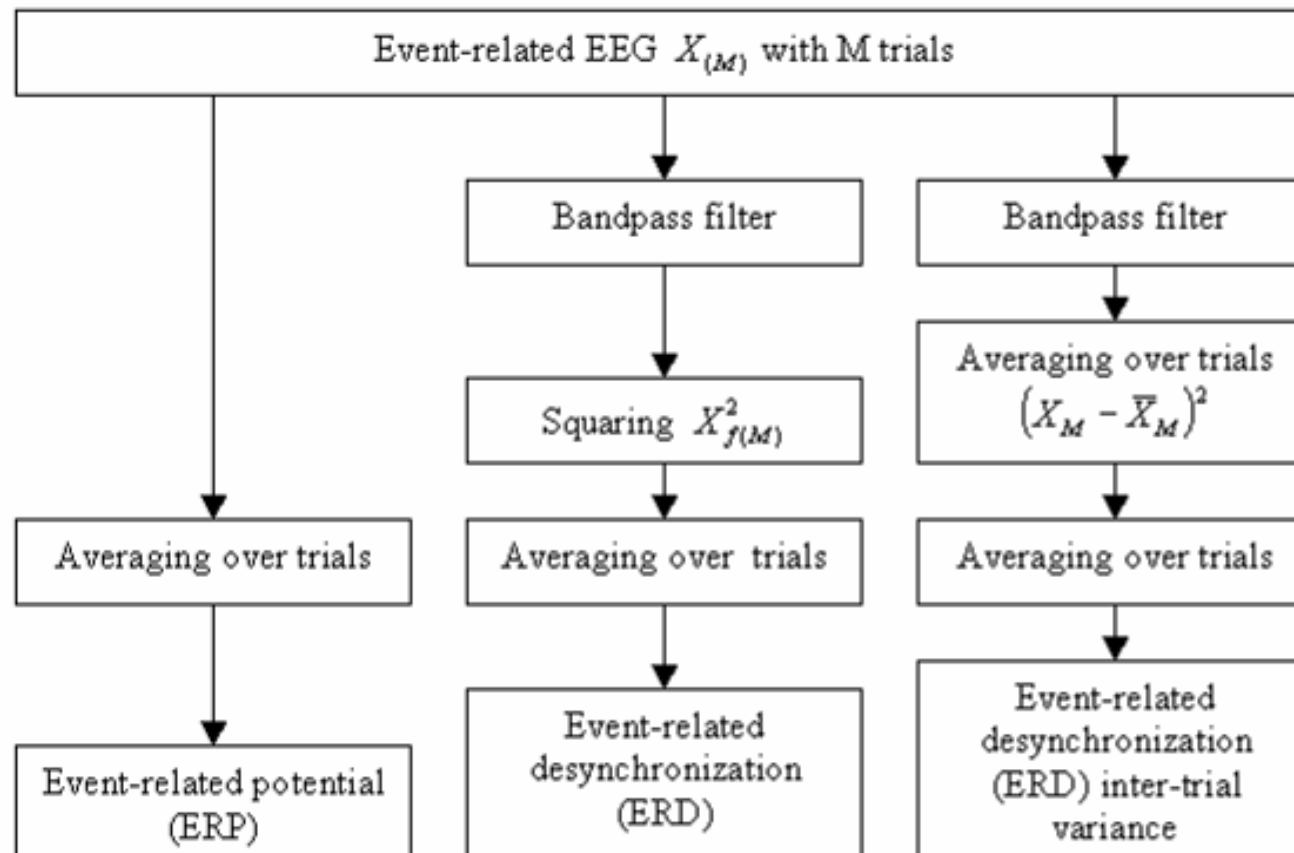


# Somatotopic organisation of the motor cortex

## Hand representation area



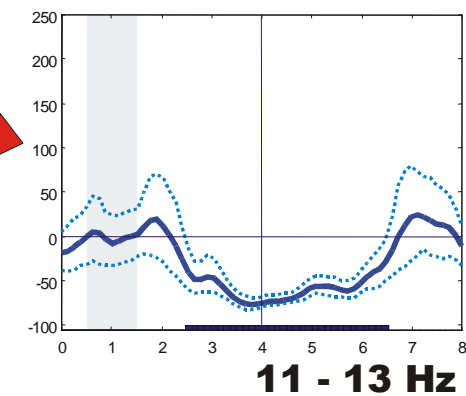
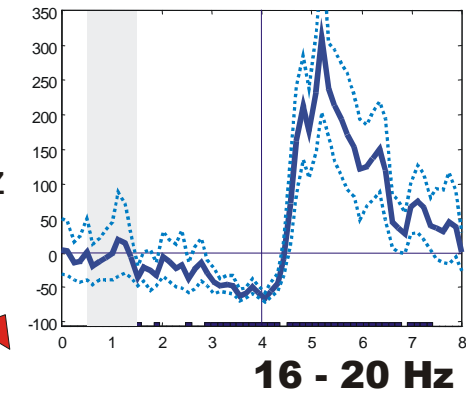
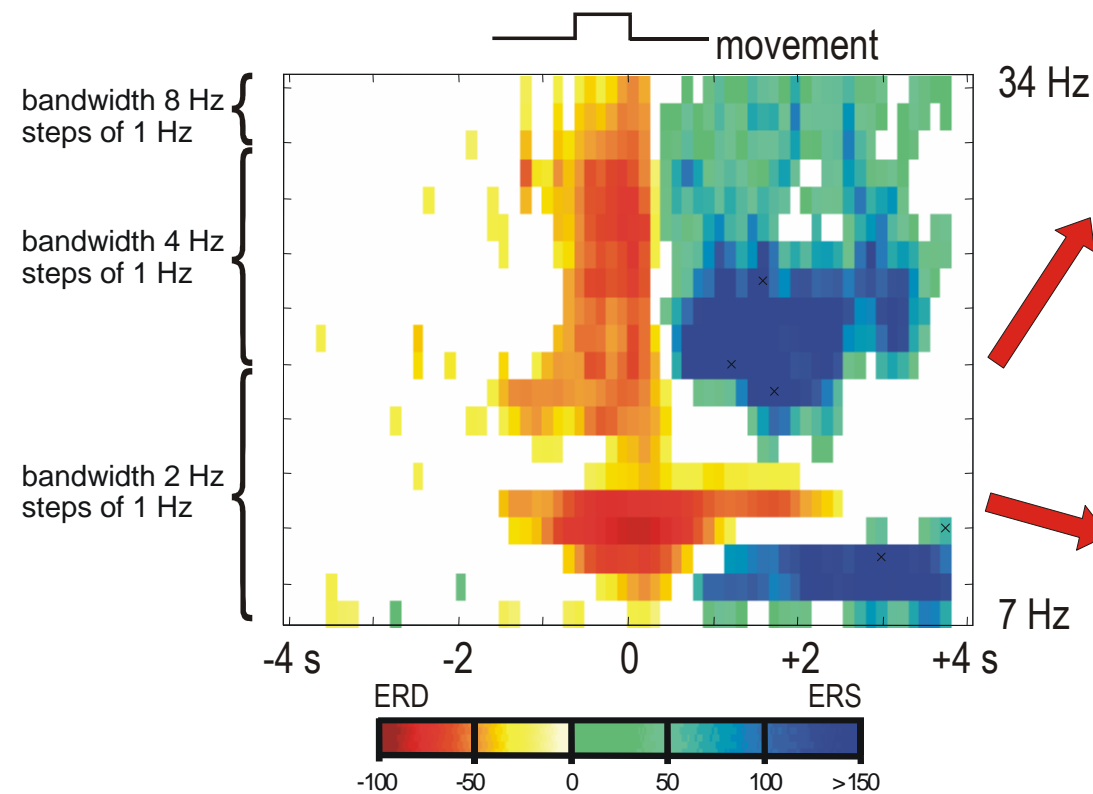
# Event-related-desynchronisation/synchronization

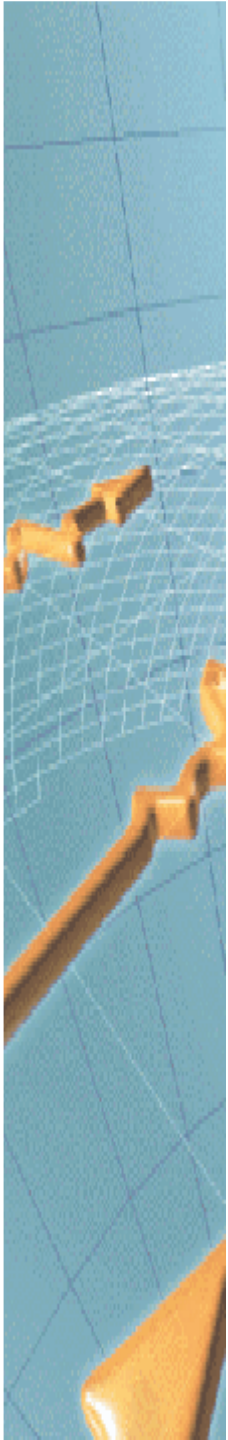


## Time-frequency mapping of ERD / ERS

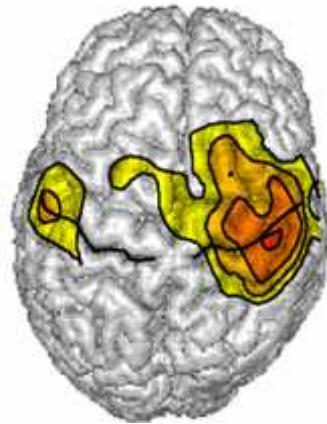
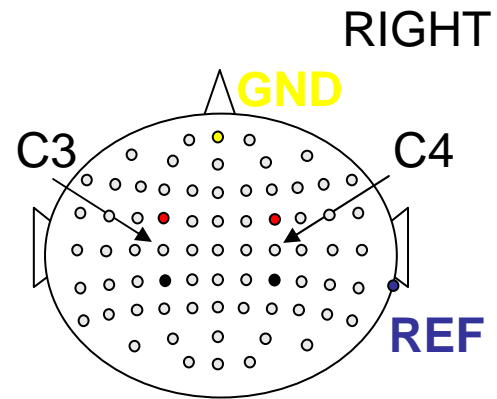
ERD/ERS map for electrode C3, right index finger movement

(significant values,  $p < .05$ )

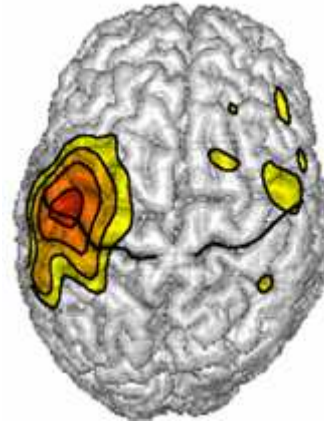




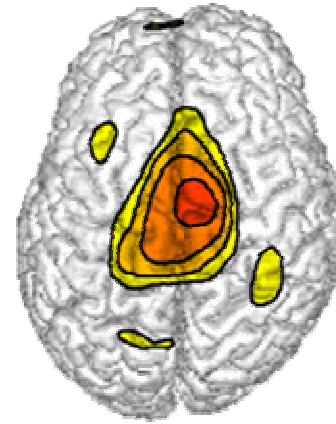
## Mental strategies



Left hand

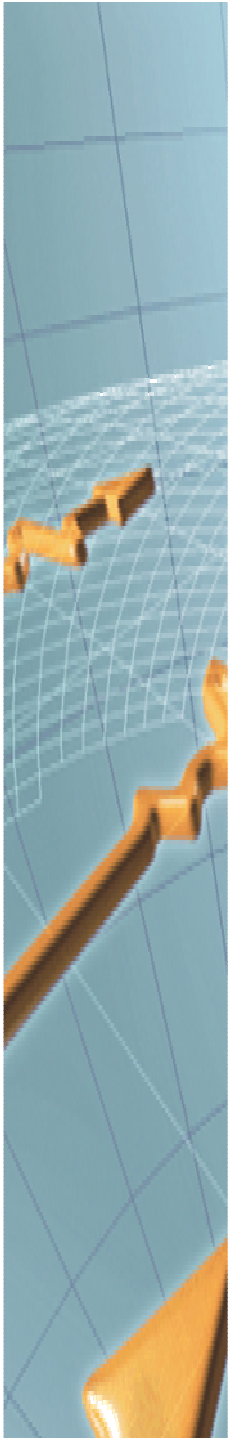


Right hand  
**motor imagery**



Foot

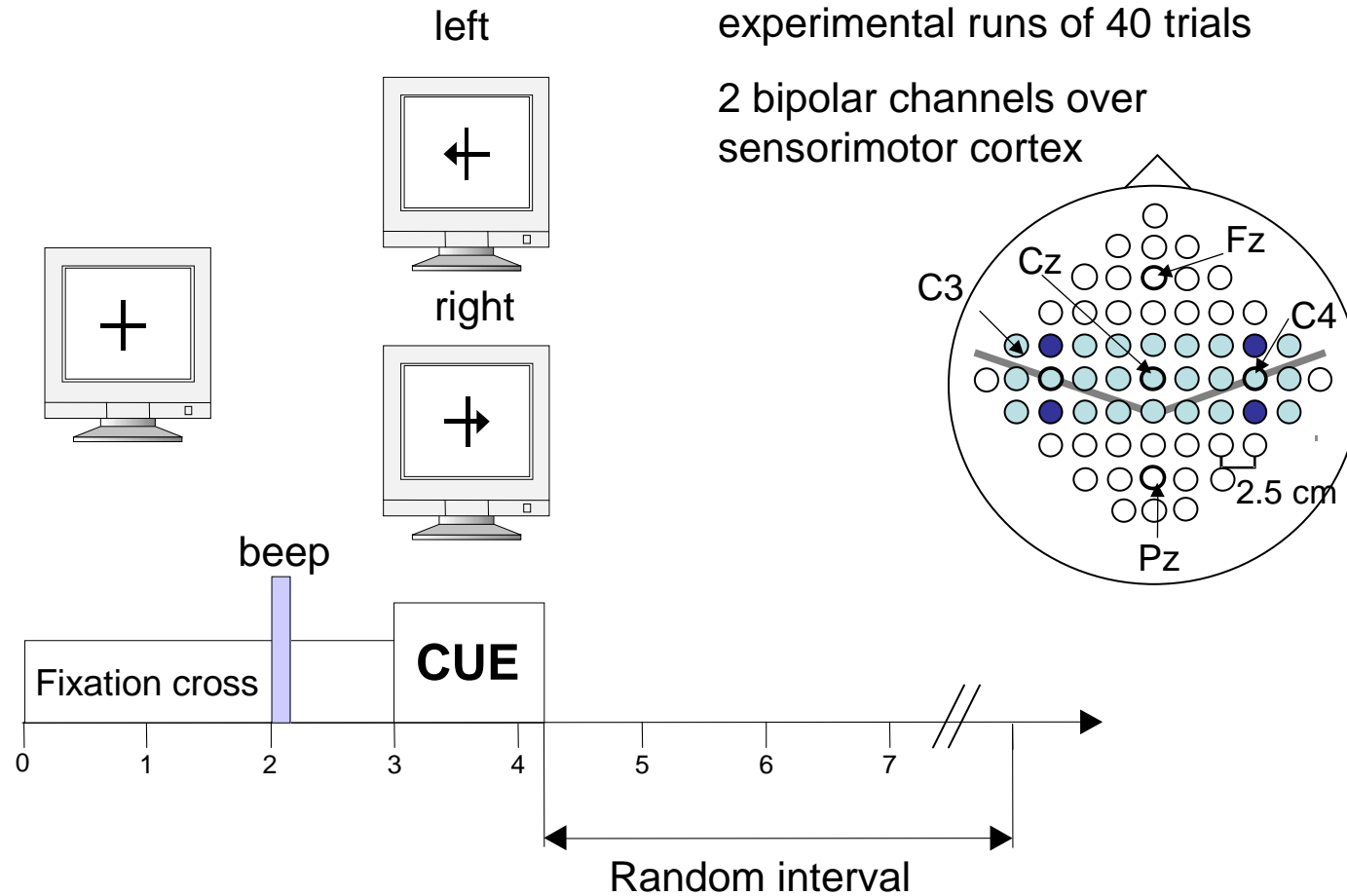




## Off-line simulation - Paradigm

Each session was divided into 4 experimental runs of 40 trials

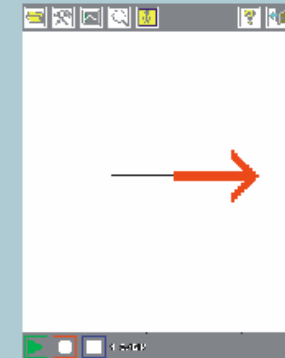
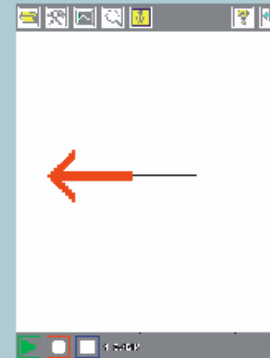
2 bipolar channels over sensorimotor cortex



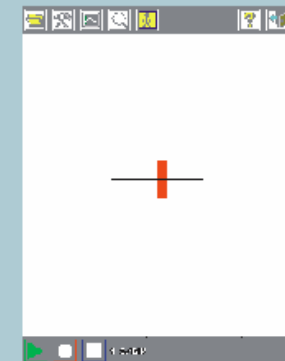
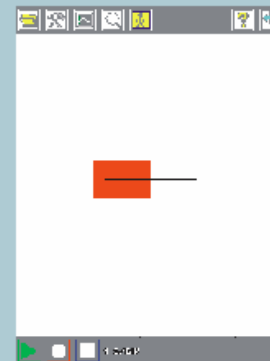
# Training BCI Control

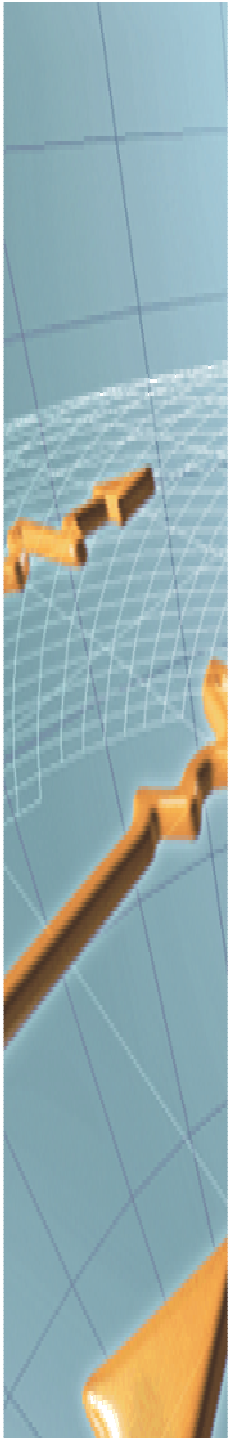


## Training phase

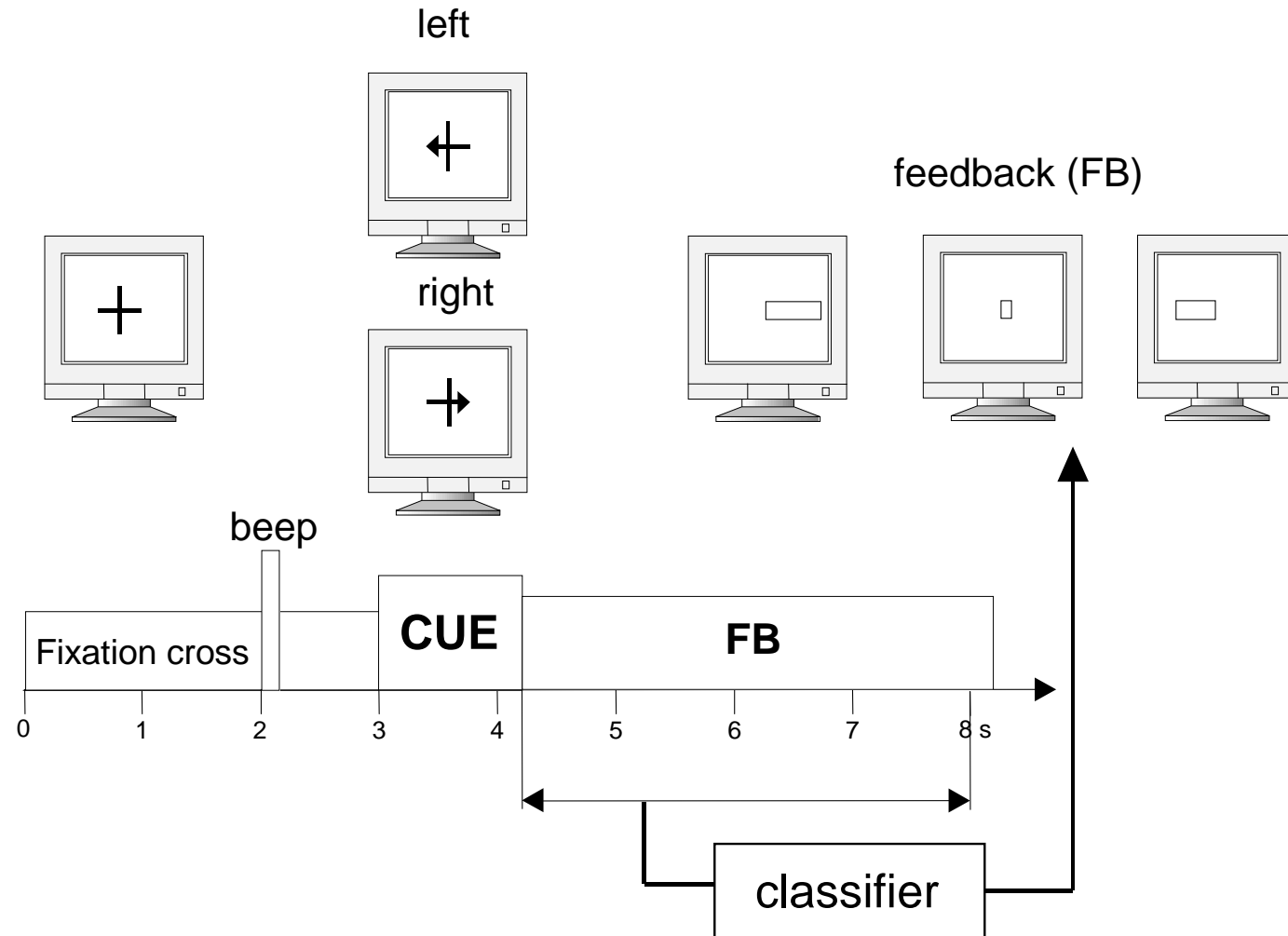


## Feedback / BCI application phase



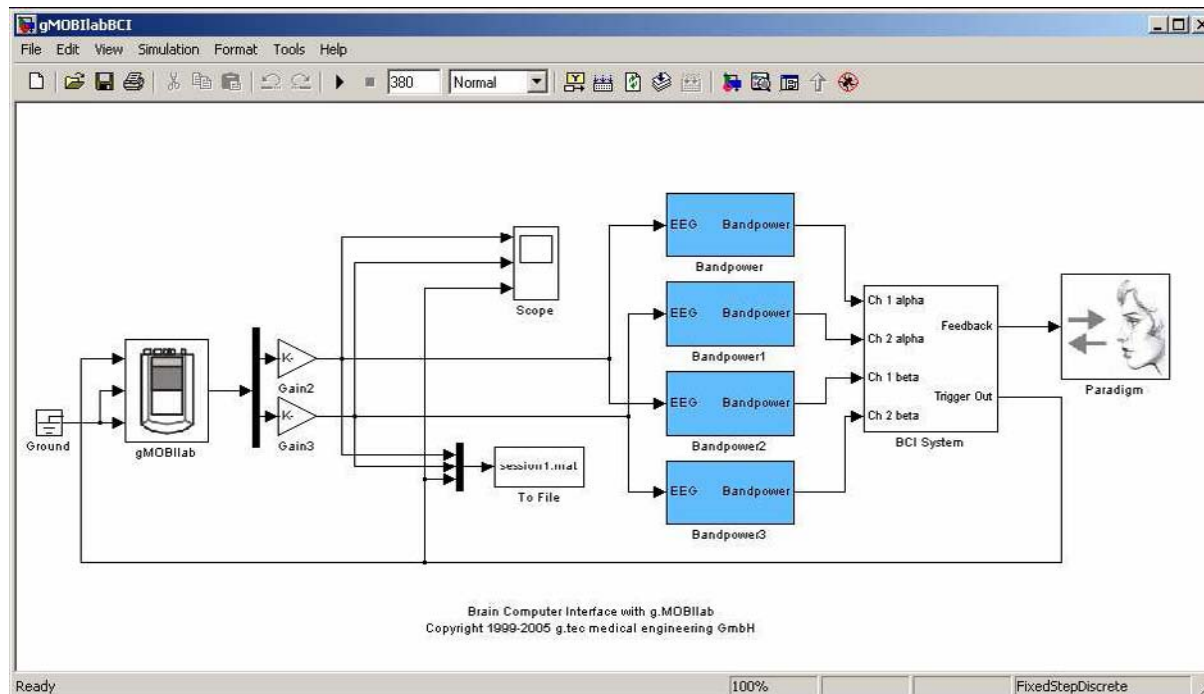


## Connection to real world – Imagination with continuous feedback



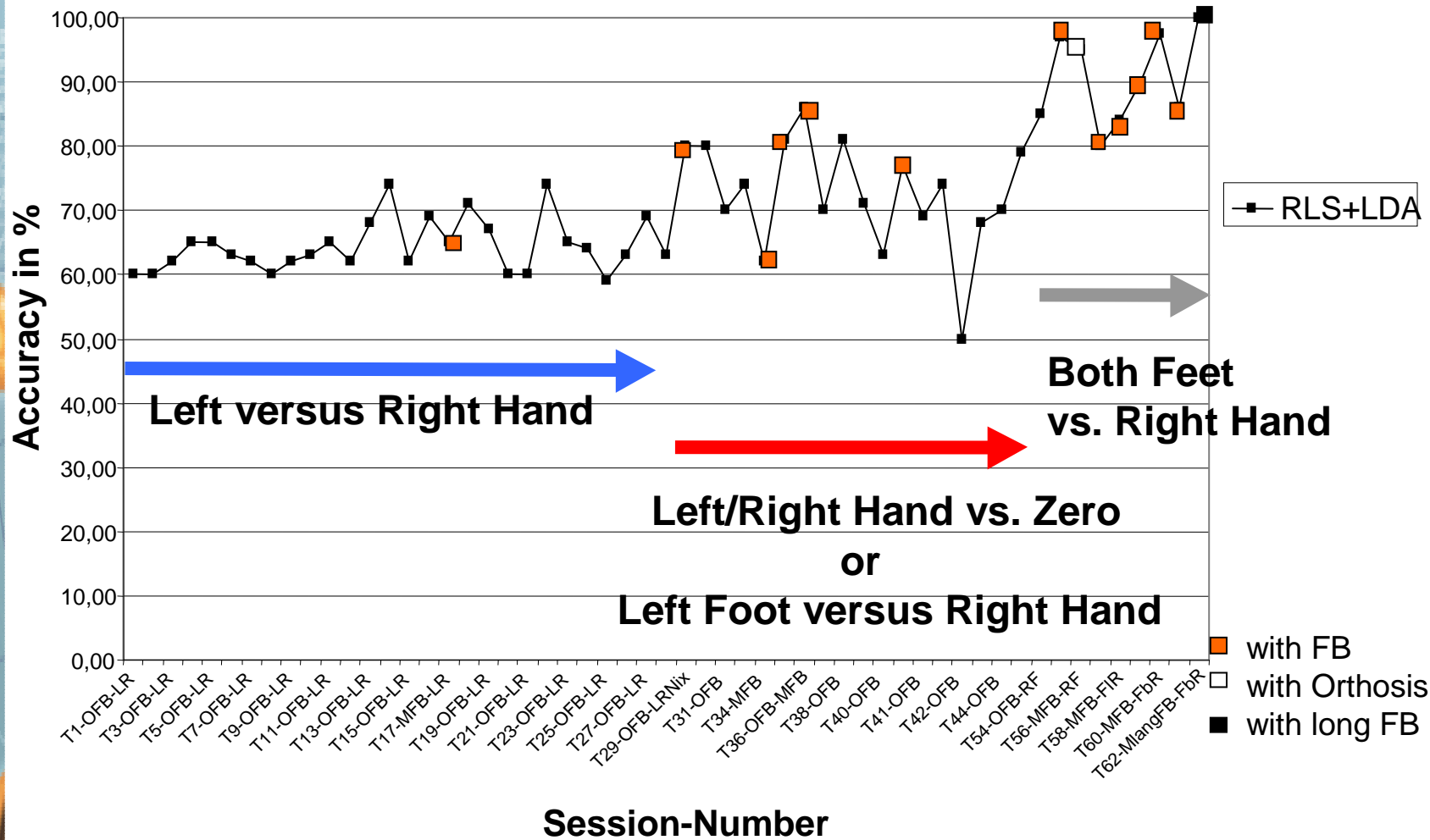
## g.USBamp Simulink Highspeed on-line Processing

- amplifier device driver block reads data into Simulink in real-time
- blocks for signal visualization and data storage
- feature extraction with bandpower algorithm implemented as S-function in C
- on-line linear discriminant analysis
- paradigm implemented as S-function with MATLAB code

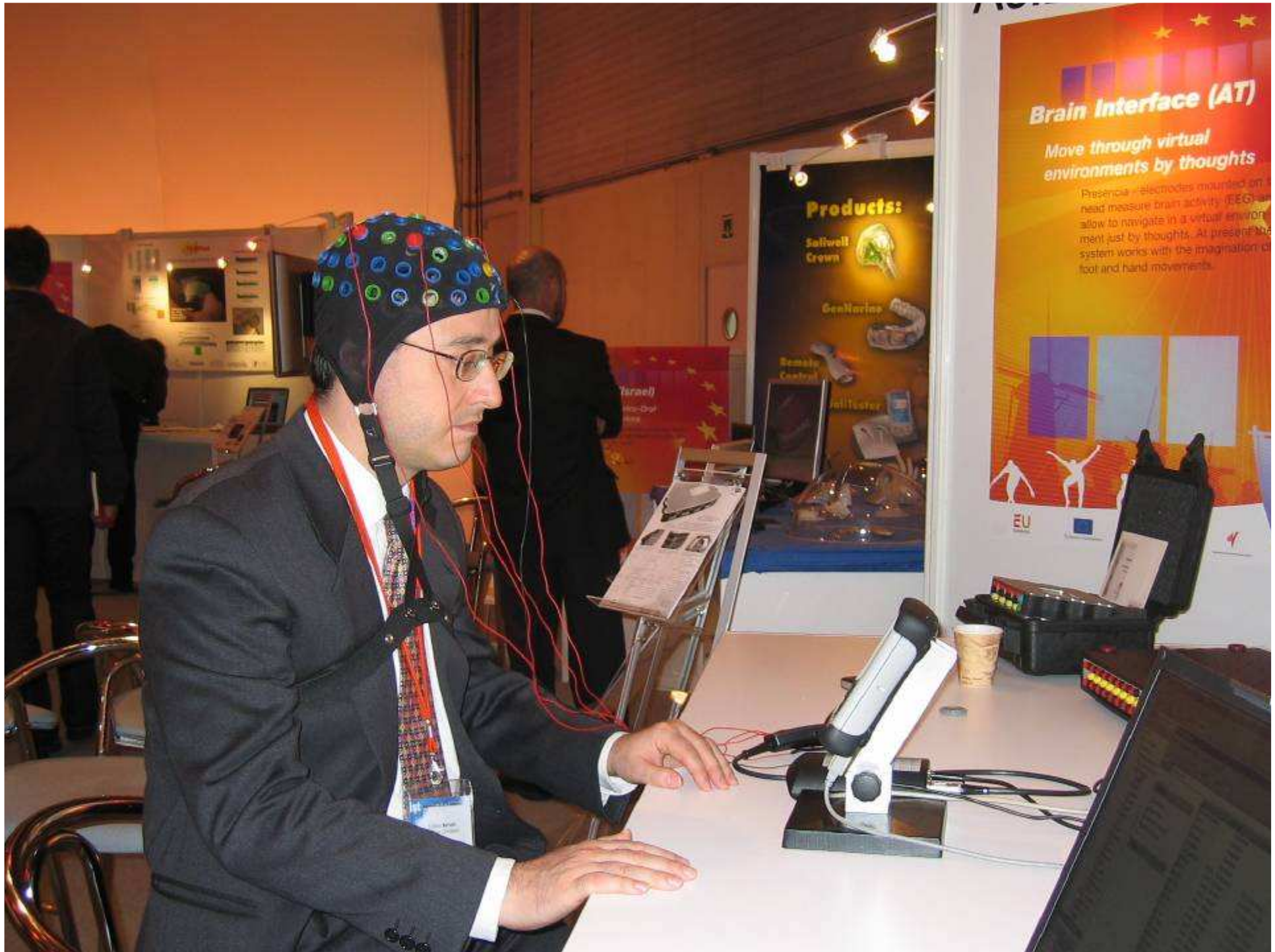


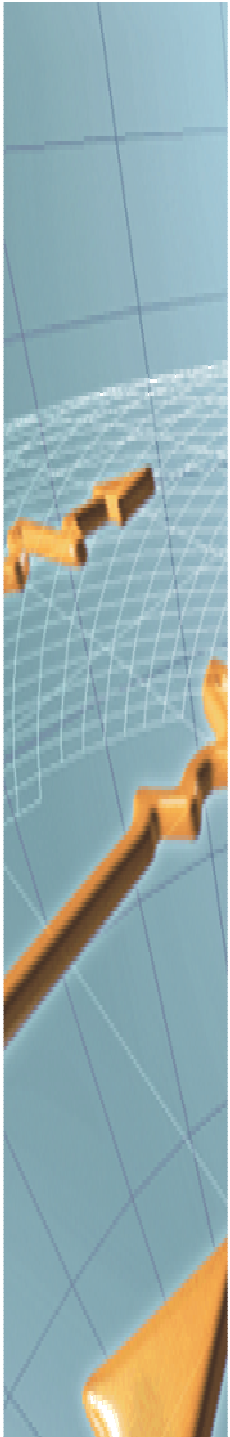
# Training Results

Classification Results, T.S., Age: 22, Mai - September, T1-T62









## How many people can control a BCI?

- BCI system at exhibition about bio-technology in Graz  
(6 months duration)
- data of all 99 subjects (first 2 month)
- 1 run without feedback
- next run with feedback
- 2 bipolar derivations analyzed with adaptive autoregressive parameters or bandpower of predefined frequency bands

Classification Accuracy in %	RLS Percentage of Runs (N=76)	BP Percentage of Runs (N=117)	RLS+BP Percentage of Runs (N=193)
90-100	6.6	6.0	6.2
80-89	10.5	14.5	13.0
70-79	30.3	33.3	32.1
60-69	40.8	42.7	42.0
50-59	11.8	3.4	6.7
	100	100	100



## Position reconstruction with place cells

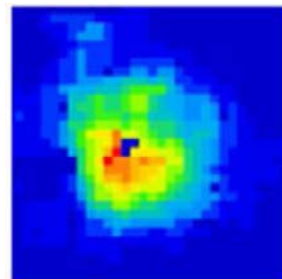
Place cells are located in the hippocampus

Place cells fire only at specific positions

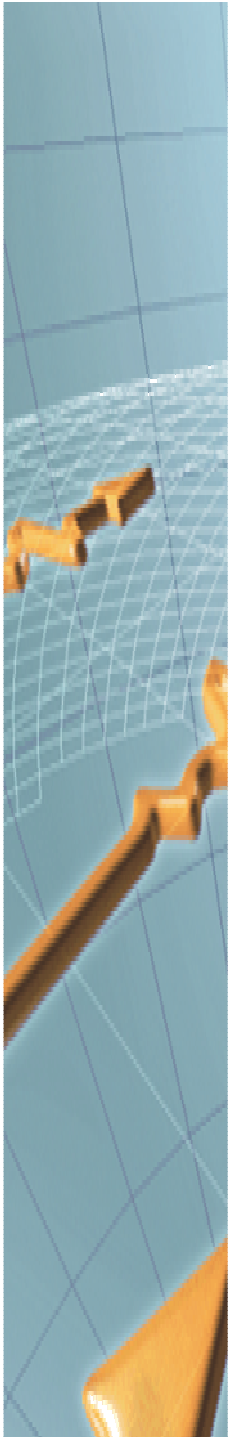
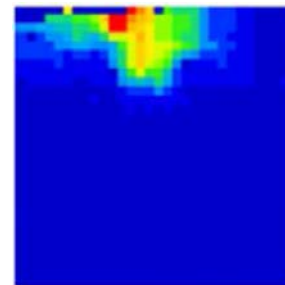
The action potentials are measured with tetrodes inserted into the animal brain

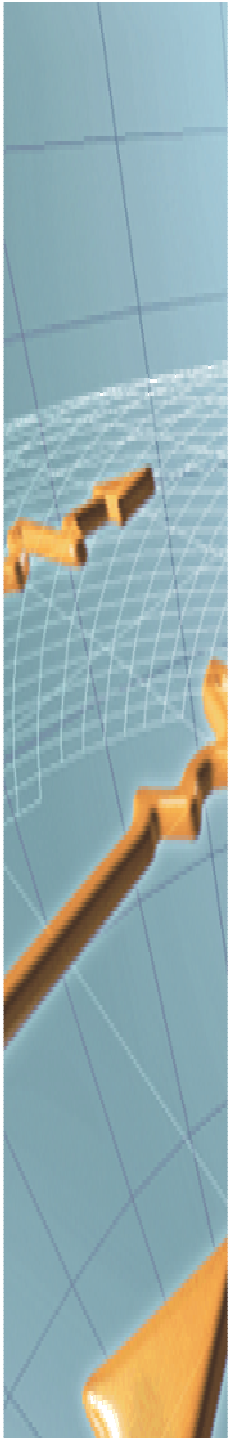
Recordings performed with rats

cell 1

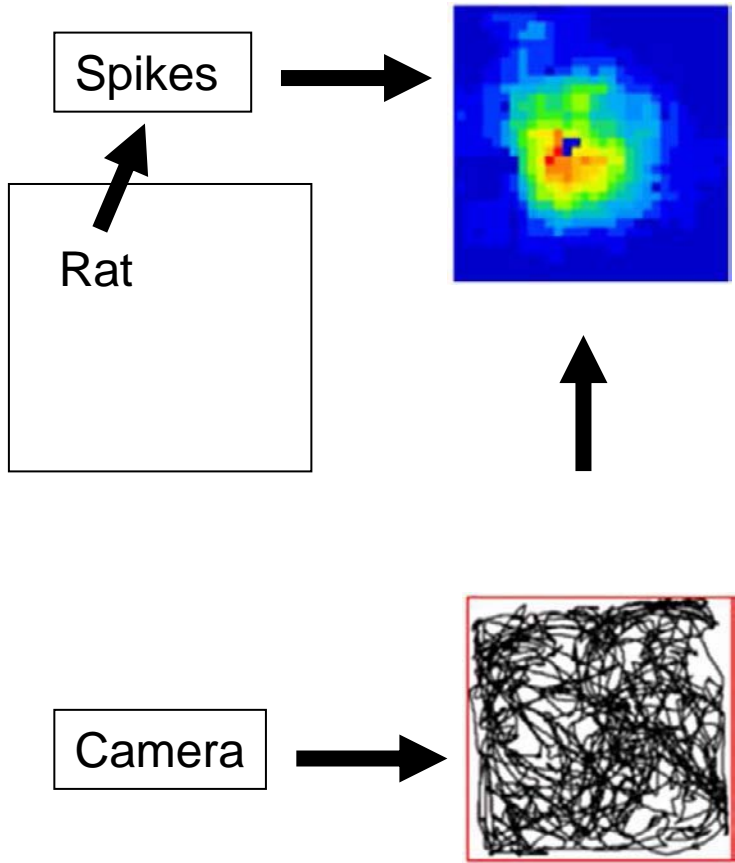


cell 2

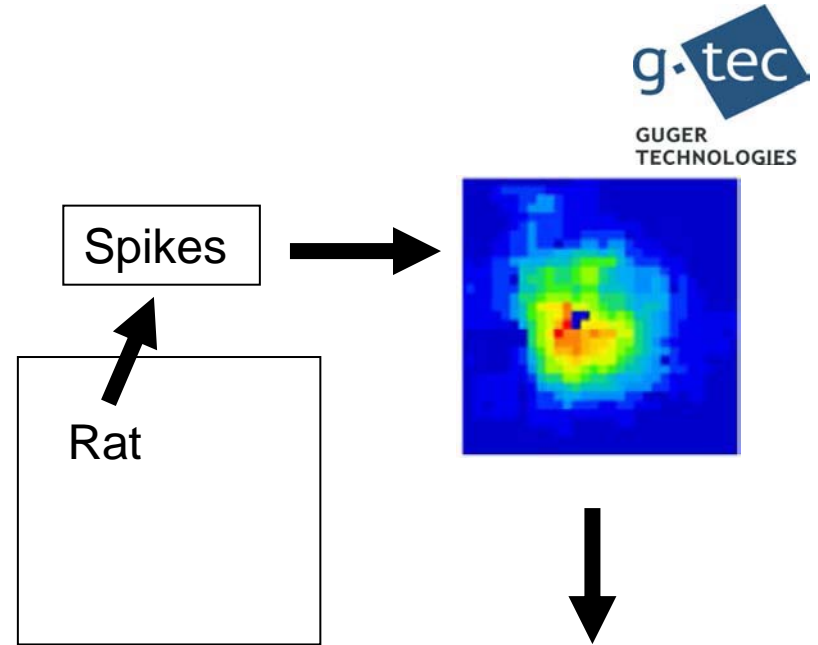




# The Rat-GPS



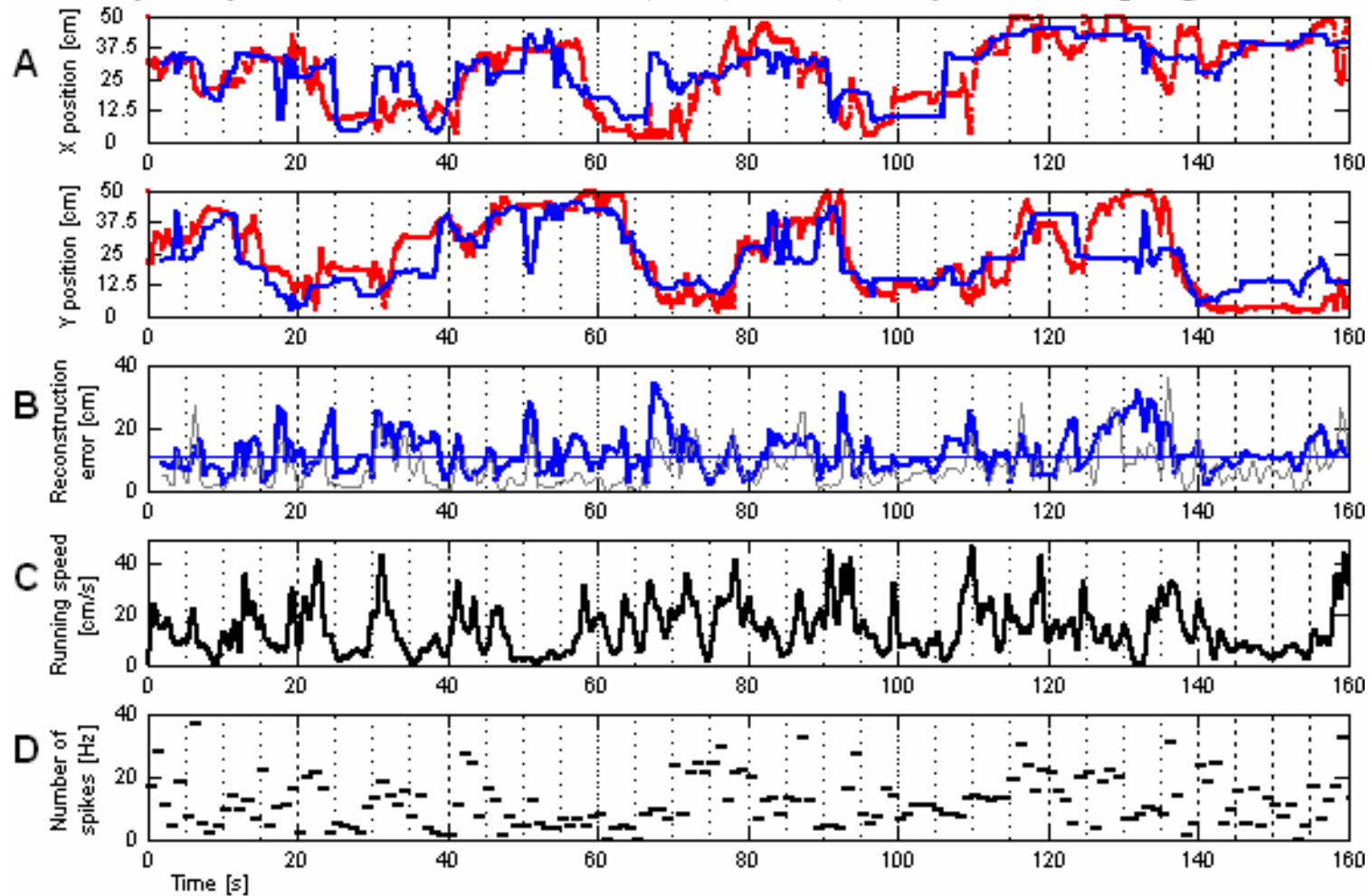
Encoding Step



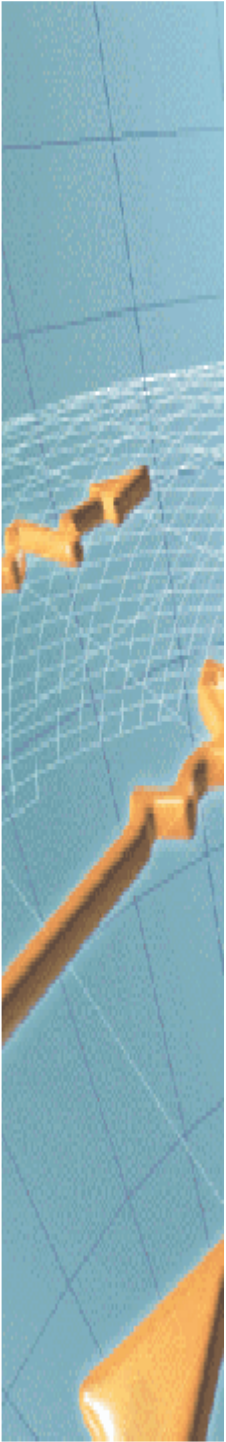
Decoding Step

# Accuracy of position recognition

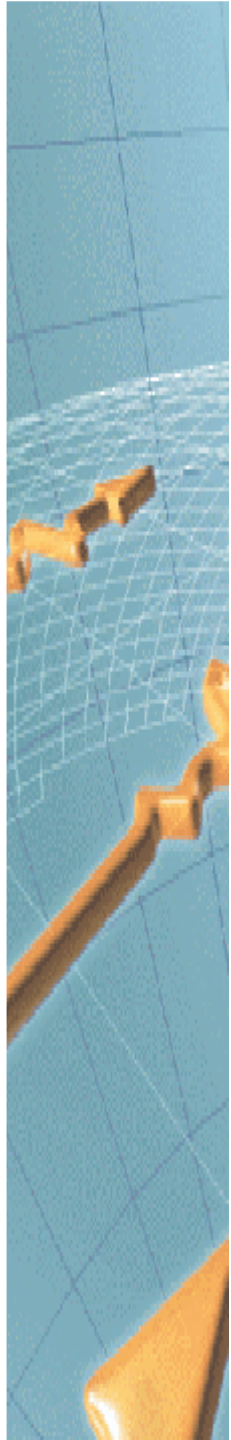
### Trajectory reconstruction for rat 3 (CA1, 9 cells) – Bayesian 2-Step algorithm



We are already able to do this on-line !



**Live Experiment:  
I) P300 based speller**



## Changes of brain electrical activity and mental strategies

- Slow cortical potentials (anticipation tasks)  
DC-derivation, artifact problem, difficult strategy, feedback method
- **Evoked potentials (focus of attention task)**  
Thalamic gating, various methods of stimulation (visual, tactile, electrical, auditory, ...), P300
- Phase-locked potentials, readiness potentials, motor potentials (motor tasks)  
Template matching, spatial distribution, large number of electrodes, ECoG electrode grid
- Event-related, non-phase-locked changes of oscillatory activity  
ERD/ERS (motor imagery tasks)  
Changes of mu-rhythm, alpha activity and beta activity over sensorimotor areas, Imageries of hand-, foot-, tongue- movements

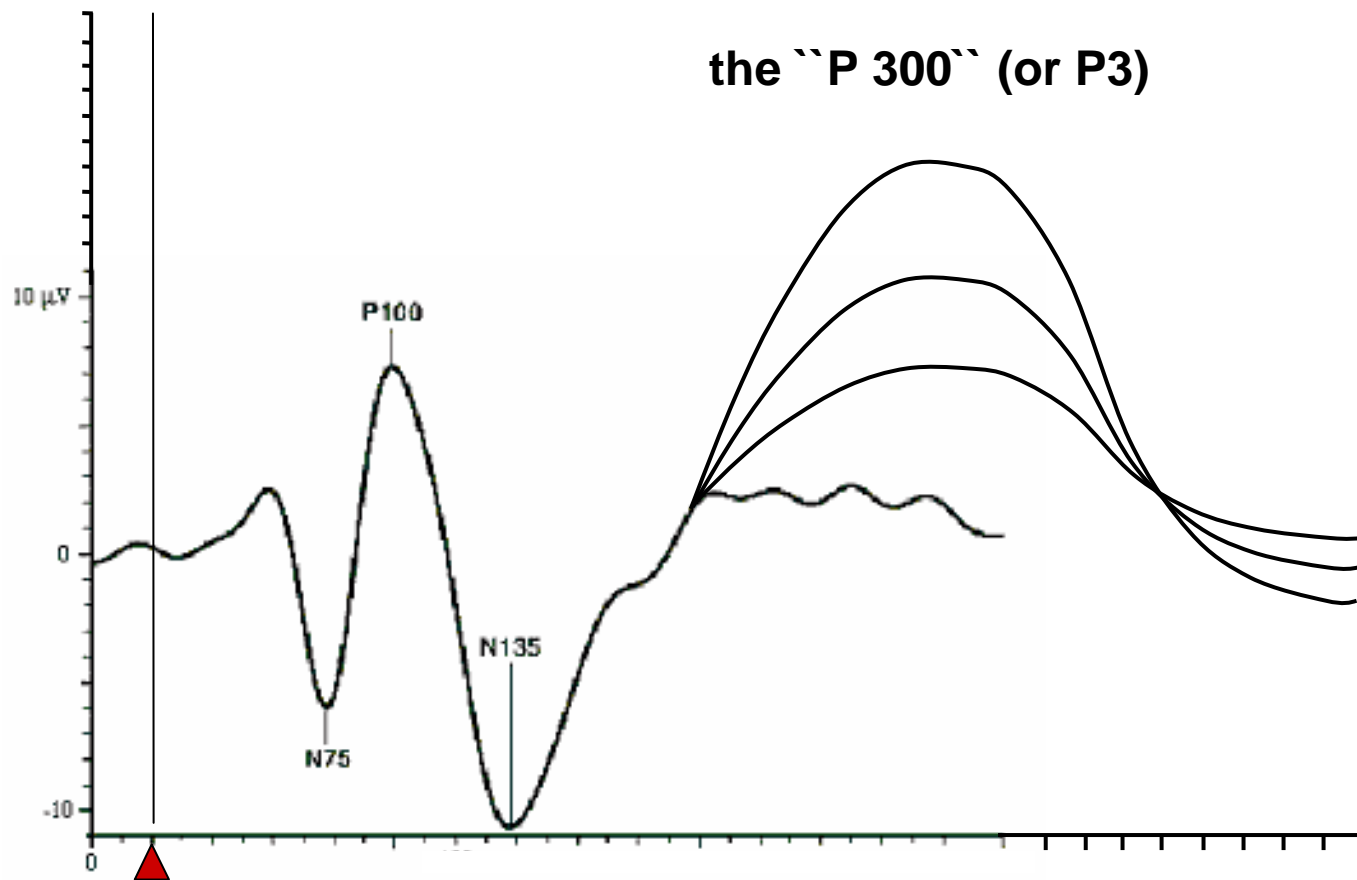
## Physiological background

- **P300 - Evoked Response Potential (ERP)**

- is obtained from EEG's (spontaneous brain activity) by averaging techniques
- is generated by a specific stimulus, i.e. visual or auditory cue.
- elicited commonly in an "oddball" paradigm when a subject detects an occasional "target" stimulus in a regular train of standard stimuli.
- only occurs if the subject is actively engaged in the task of detecting the targets.

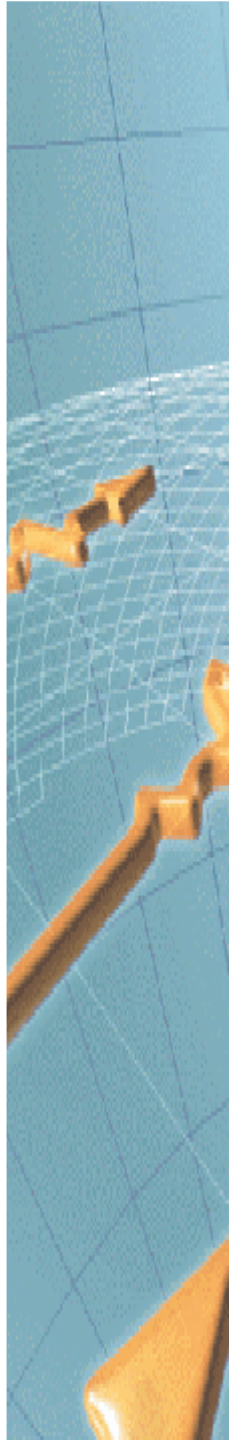
*Its amplitude varies with the improbability of the targets. Its latency varies with the difficulty of discriminating the target stimulus from the standard stimuli (Picton 1992, discovered by Sutton et al. 1965)*

## P 300 Visually Evoked Potentials



visual stimulation **with cognitive relevance**

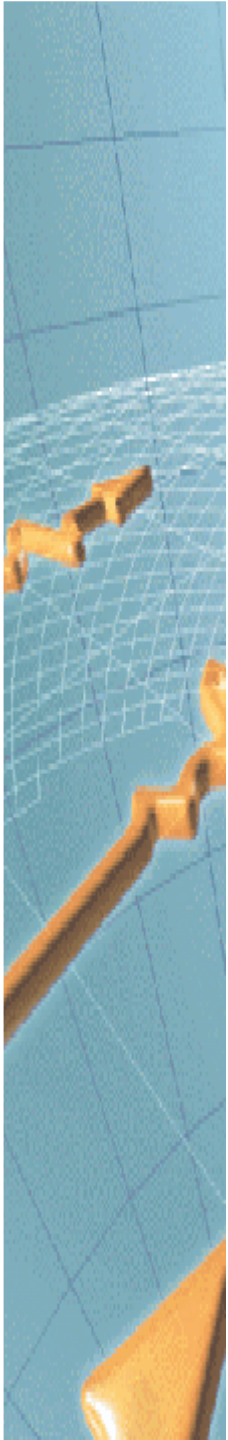




## **P 300 Visually Evoked Potentials**

**Cognitive relevance: What generates a large P 300 component?**

- I can detect the target stimulus out of a number of non-targets**
- I draw more attention to the target stimulus than to the others**
- I can recognize the target stimulus**
- I am waiting for the target stimulus to appear**
- The target stimulus contains more information than the non-target**
- The target has any other property that makes it unique**

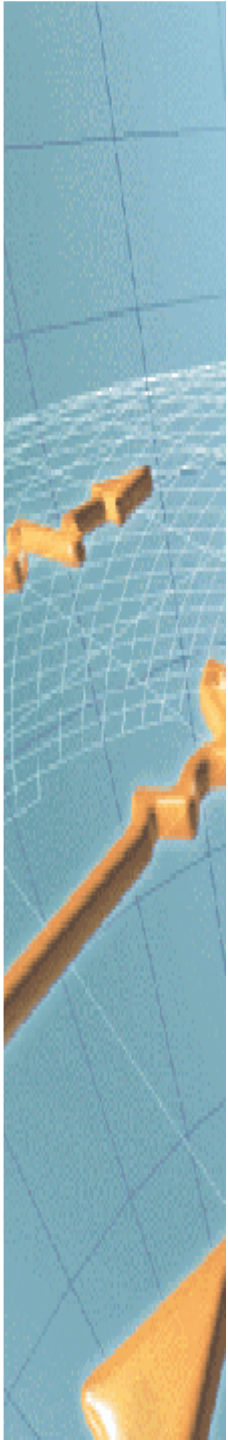


## The 6 x 6 matrix speller, single character flash

concentrate on „W“

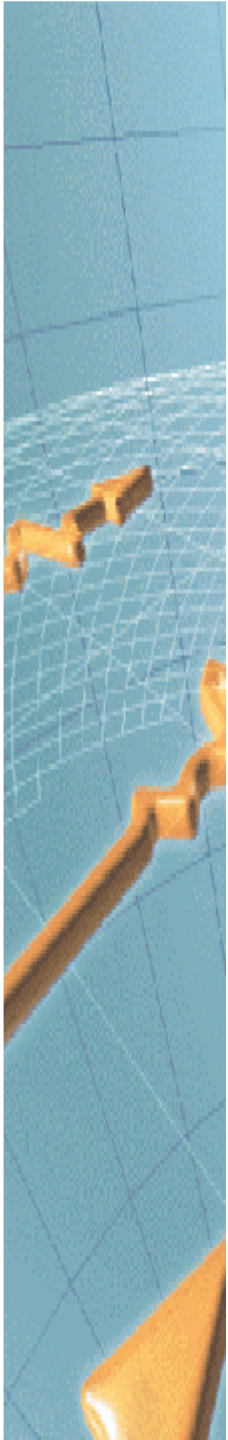
Individual character intensifies for 60ms with 10ms between each intensification

A	B	C	D	E	F
G	H	I	J	K	L
M	N	O	P	Q	R
S	T	U	V	W	X
Y	Z	0	1	2	3
4	5	6	7	8	9



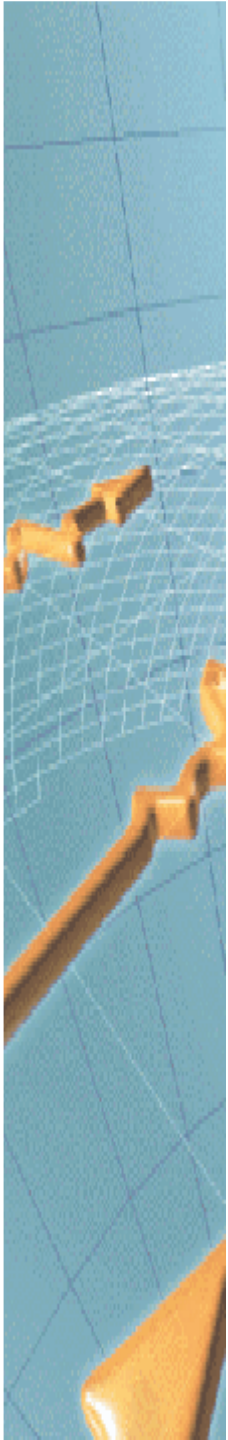
## The 6 x 6 matrix speller, single character flash

<b>A</b>	<b>B</b>	<b>C</b>	<b>D</b>	<b>E</b>	<b>F</b>
<b>G</b>	<b>H</b>	<b>I</b>	<b>J</b>	<b>K</b>	<b>L</b>
<b>M</b>	<b>N</b>	<b>O</b>	<b>P</b>	<b>Q</b>	<b>R</b>
<b>S</b>	<b>T</b>	<b>U</b>	<b>V</b>	<b>W</b>	<b>X</b>
<b>Y</b>	<b>Z</b>	<b>0</b>	<b>1</b>	<b>2</b>	<b>3</b>
<b>4</b>	<b>5</b>	<b>6</b>	<b>7</b>	<b>8</b>	<b>9</b>



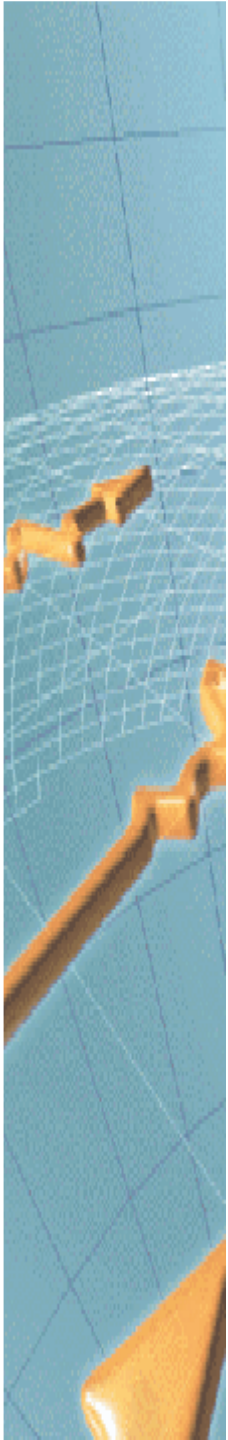
## The 6 x 6 matrix speller, single character flash

A	B	C	D	E	F
G	H	I	J	K	L
M	N	O	P	Q	R
S	T	U	V	W	X
Y	Z	0	1	2	3
4	5	6	7	8	9



## The 6 x 6 matrix speller, single character flash

A	B	C	D	E	F
G	H	I	J	K	L
<b>M</b>	N	O	P	Q	R
S	T	U	V	W	X
Y	Z	0	1	2	3
4	5	6	7	8	9



## The 6 x 6 matrix speller, single character flash

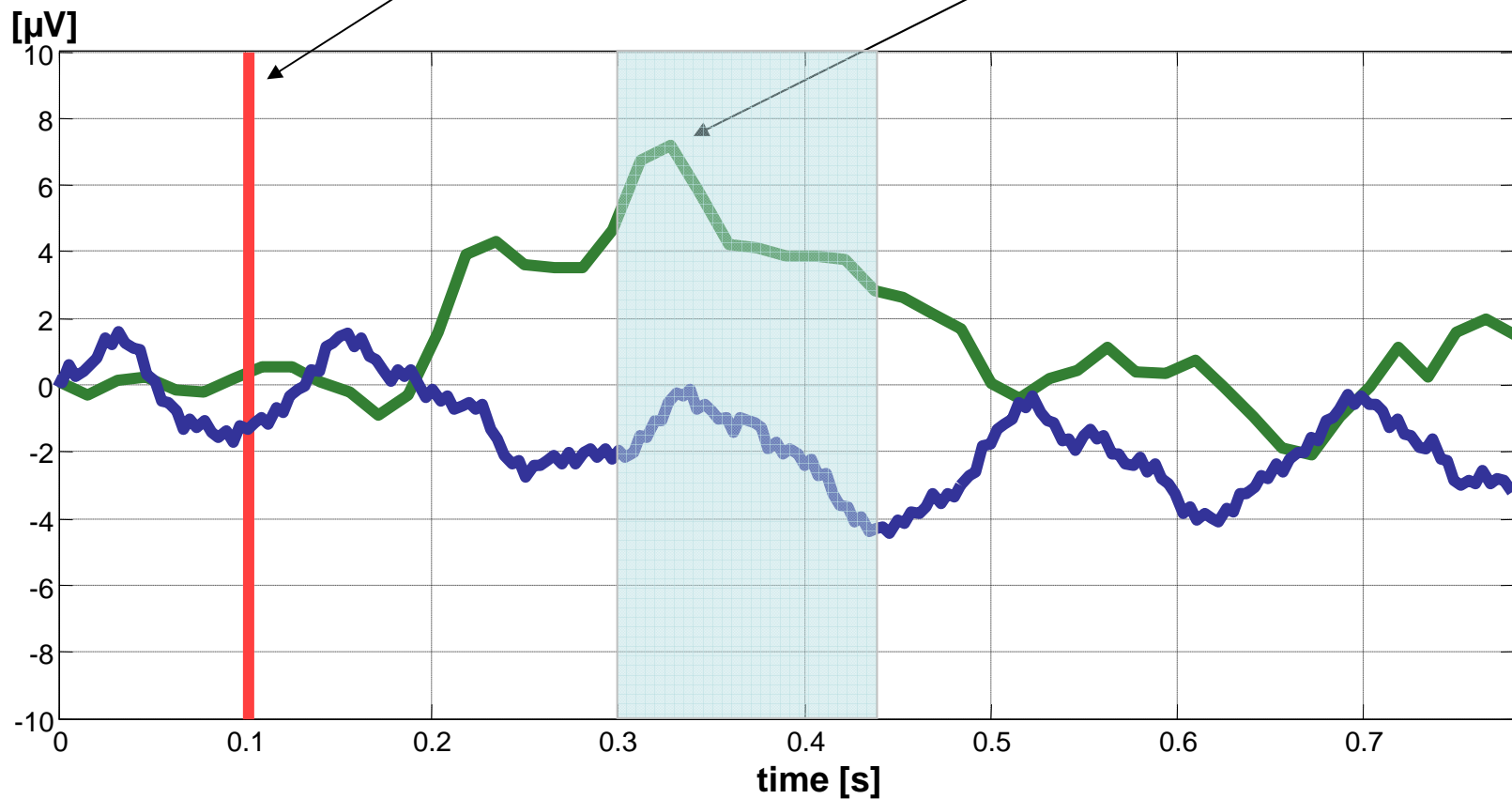
A	B	C	D	E	F
G	H	I	J	K	L
M	N	O	P	Q	R
S	T	U	V	<b>W</b>	X
Y	Z	0	1	2	3
4	5	6	7	8	9



# The 6 x 6 matrix speller, single character flash

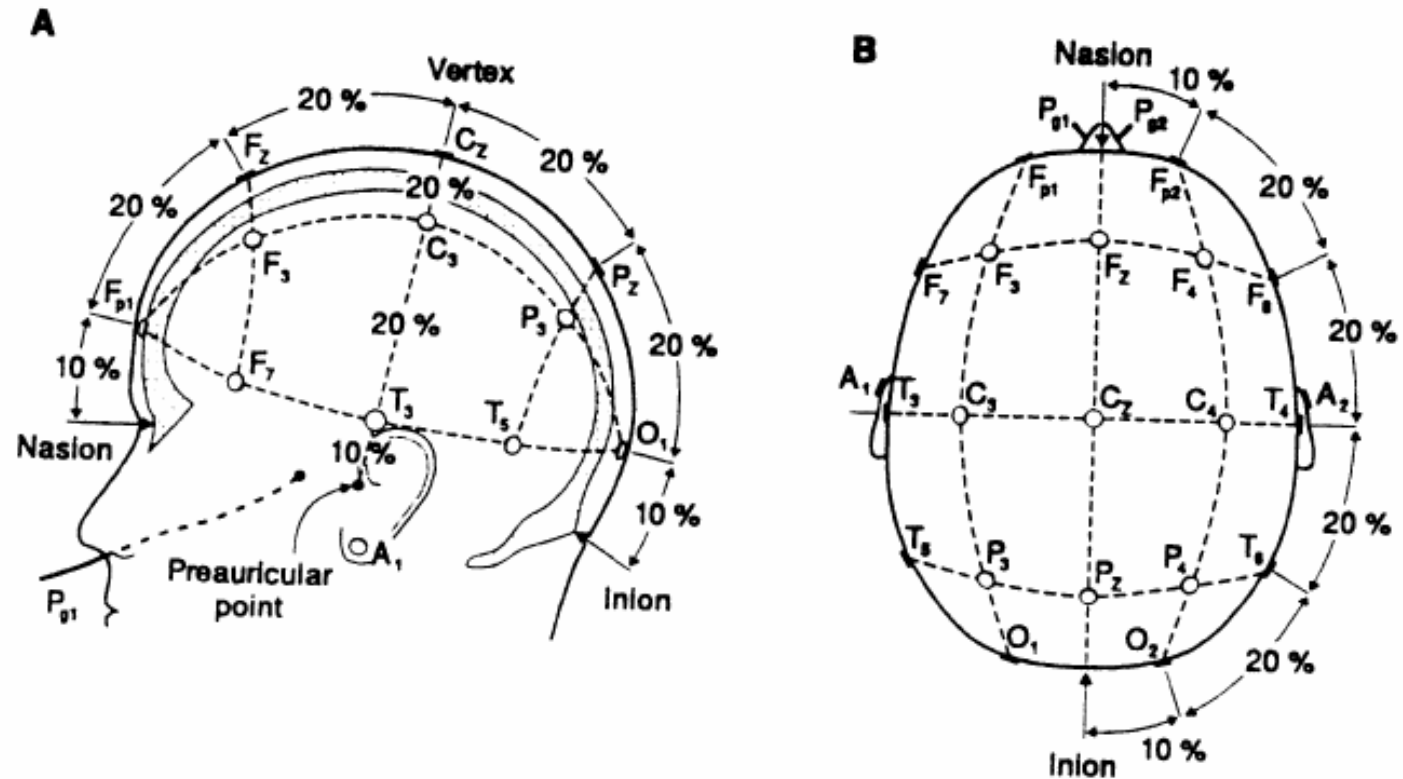
Letter W Presentation

P300



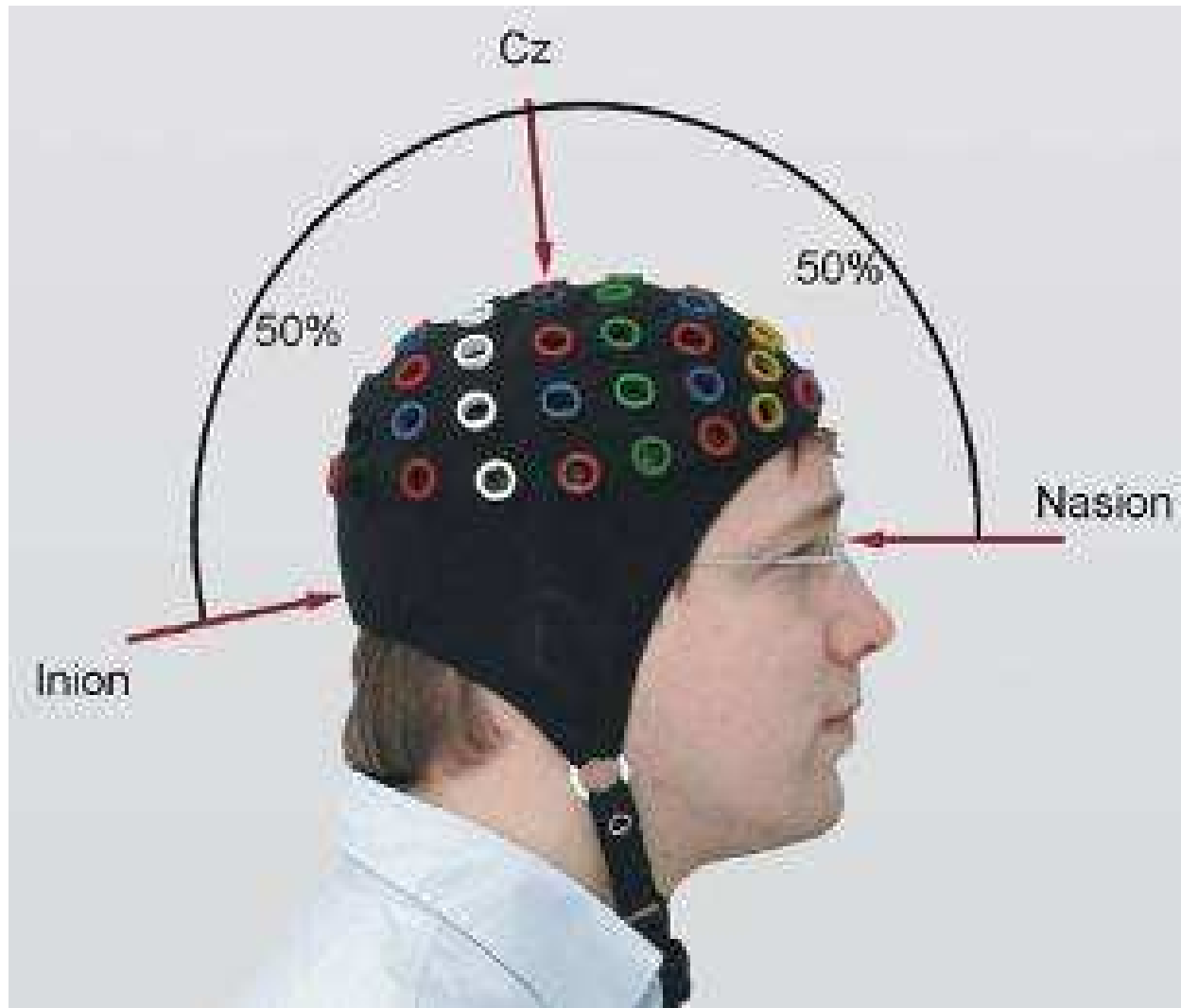
— Target  
— NON Target

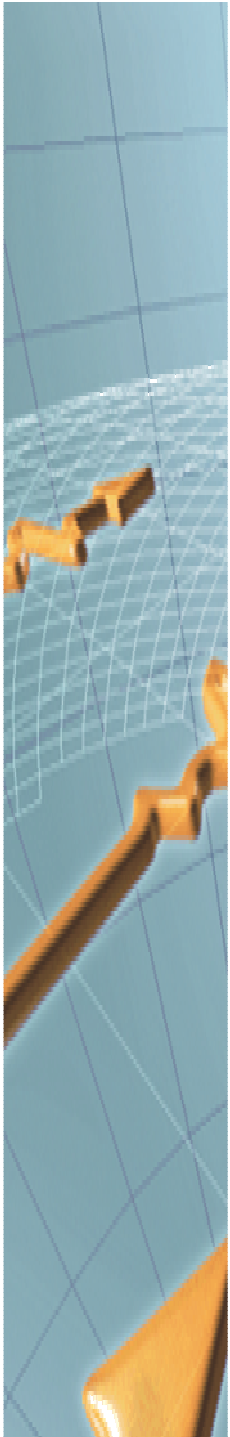
## Mount electrodes



International 10/20 system. The distances between Inion-Nasion and the left and right preauricular points are the basis for the location of all electrode positions.

## Placement of the cap





## P300 BCI? Study Design

5 subjects, 8 EEG channels recorded

Fz, Cz, P3, Pz, P4, PO7, Oz, PO8

Referenced to right mastoid, grounded to the forehead

Data recorded with g.USBamp

Fa = 256 Hz, bandpass 0.1 – 30 Hz

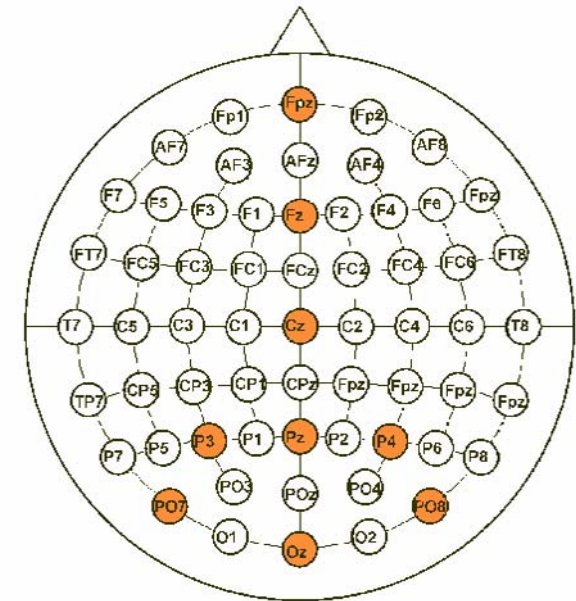
1st training run -> 5 letters

Application runs -> up to 42 letters

„Spelling Device“ Application

Single character flash experiment

→ Total of ~ 45 min incl. electrode montage and instruction of the subject



## Feature Extraction

Event related data triggering:

100ms pre-stimulus, 700ms post-stimulus

Baseline correction was performed for pre-stimulus interval

Downsampling (15 features/channel \* 8 channel)

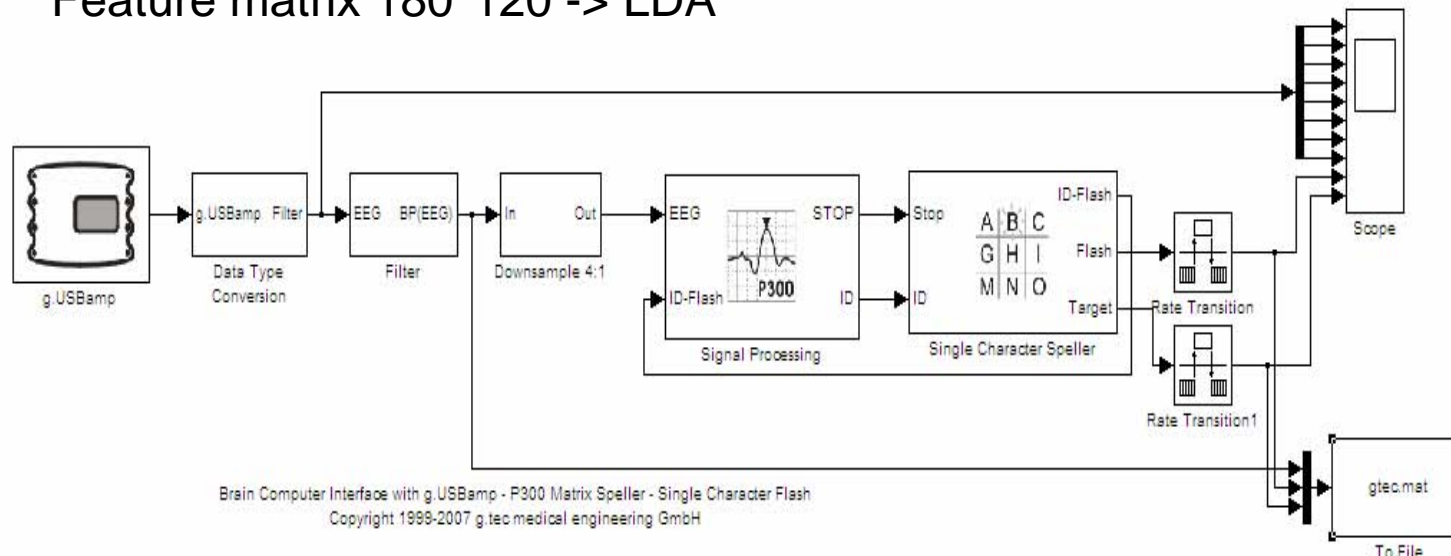
Data segments were concatenated by channel

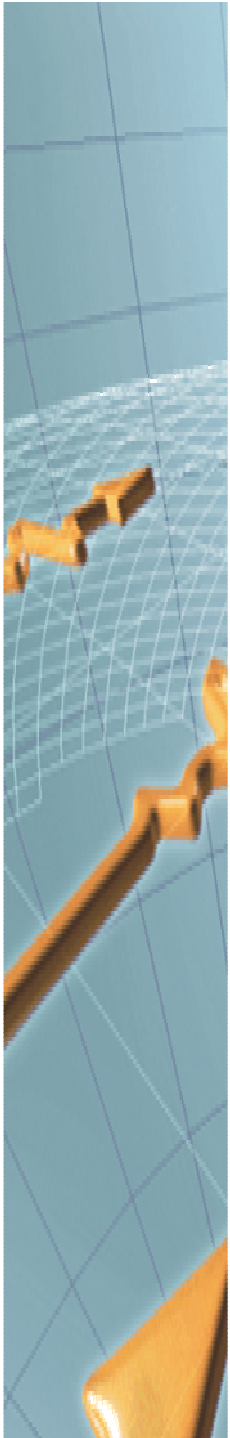
Assume 5 flashes were selected for training, 3 letter word e.g. BCI

single character mode:  $36 \cdot 5 = 180$  flashes \* 3 repetitions

540 trials, 15 target trials, 525 non target trials

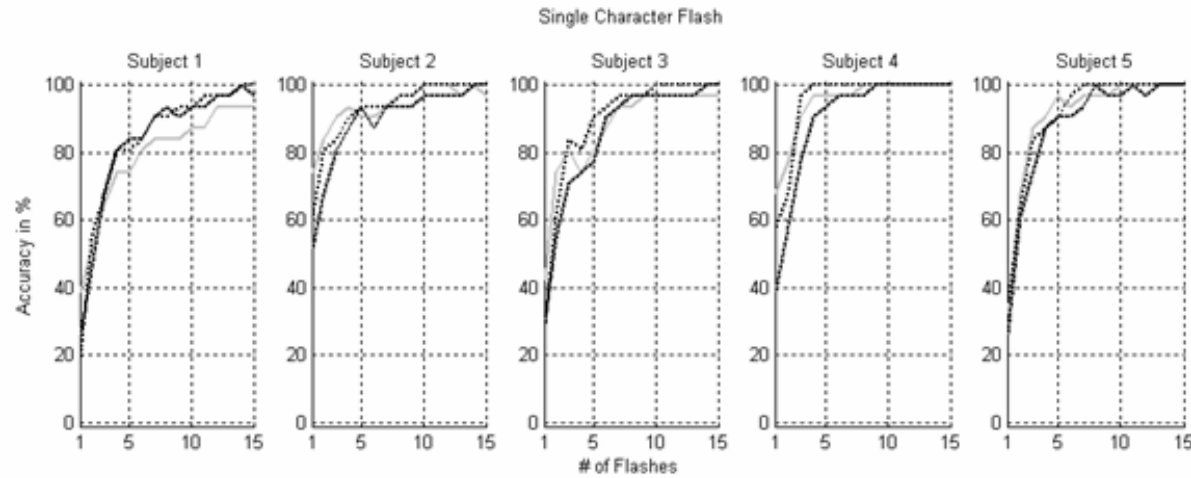
Feature matrix  $180 \cdot 120 \rightarrow$  LDA



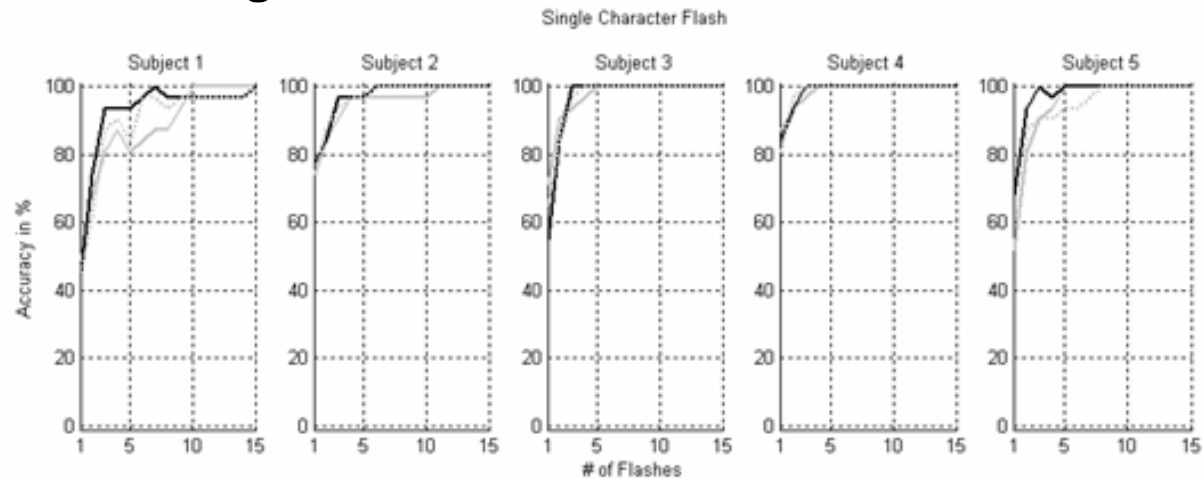


# Accuracy depends on letters used for classifier training

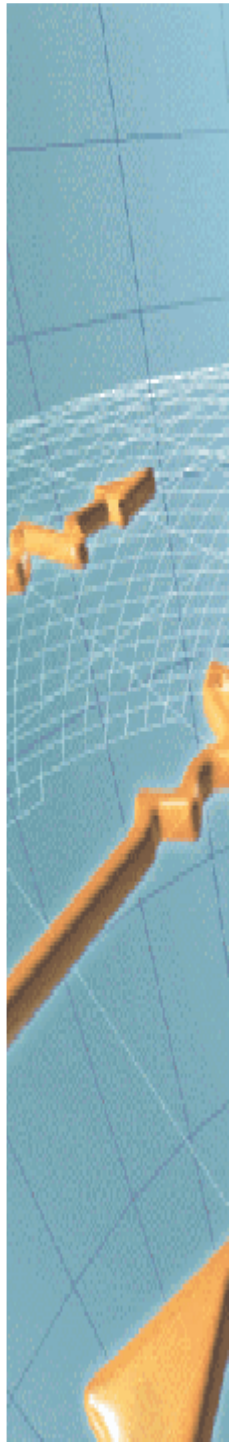
## 3 training characters



## 42 training characters



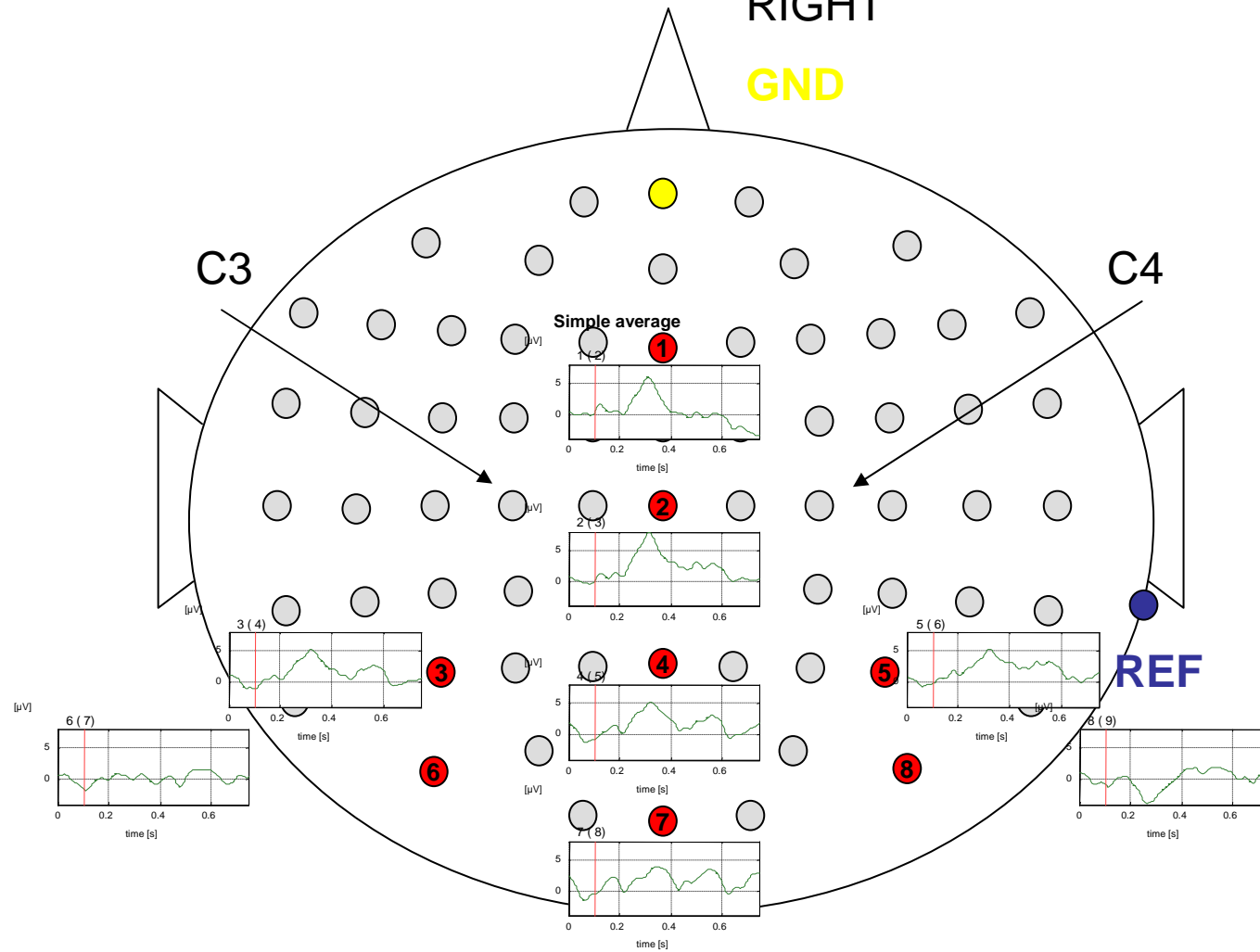


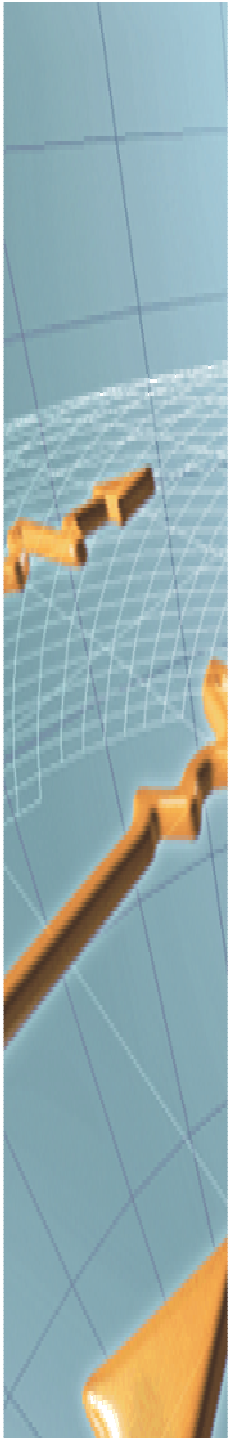


# P300 Topography TARGET

RIGHT

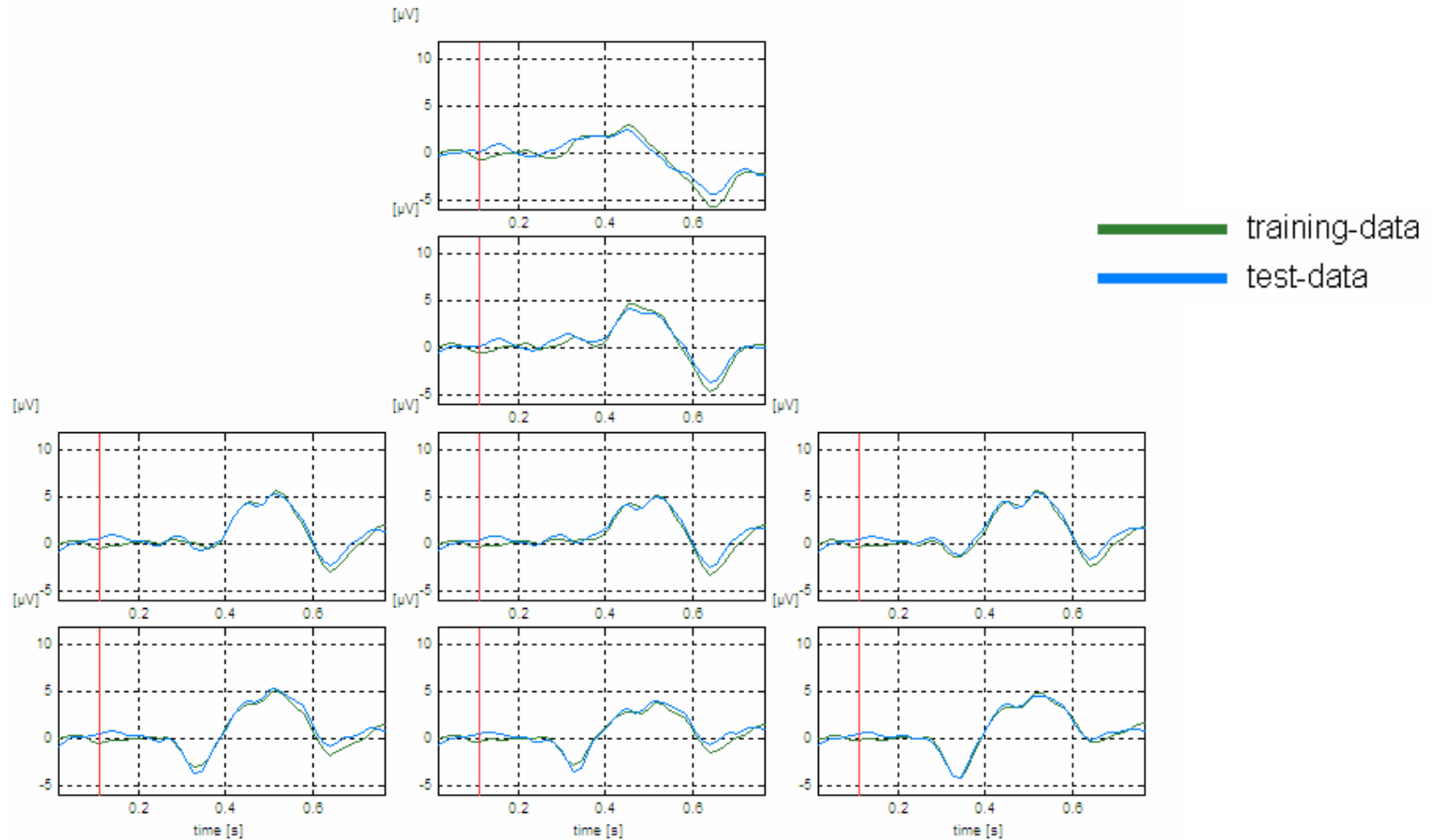
GND

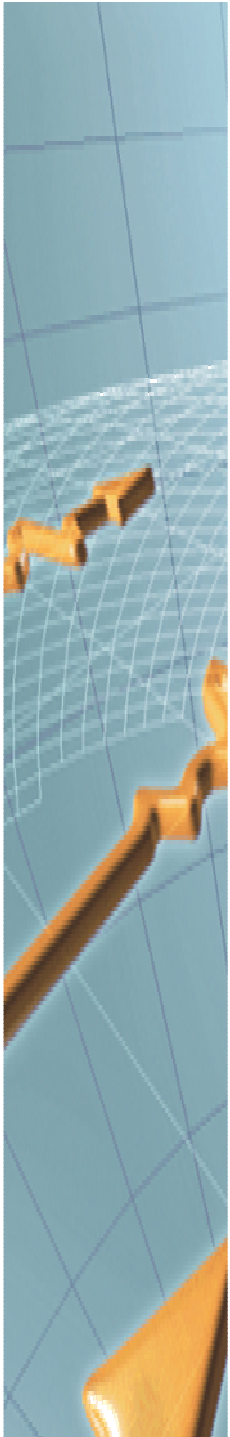




## Grand Average P300 responses

EP reaches about 5-6  $\mu\text{V}$ , 350 ms after stimulus  
No difference over time  $\rightarrow$  stable





## Transfer rates calculation

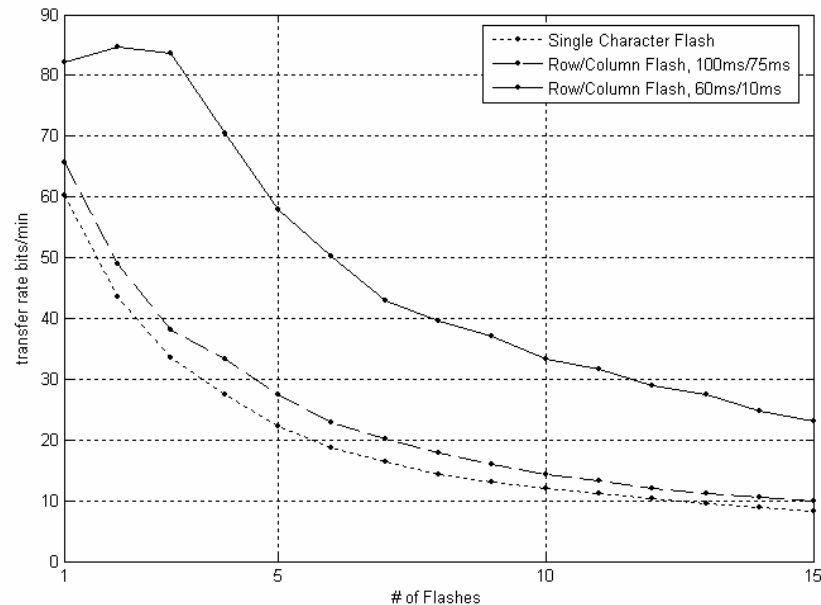
The bit rate  $R$  in bits/min is given by

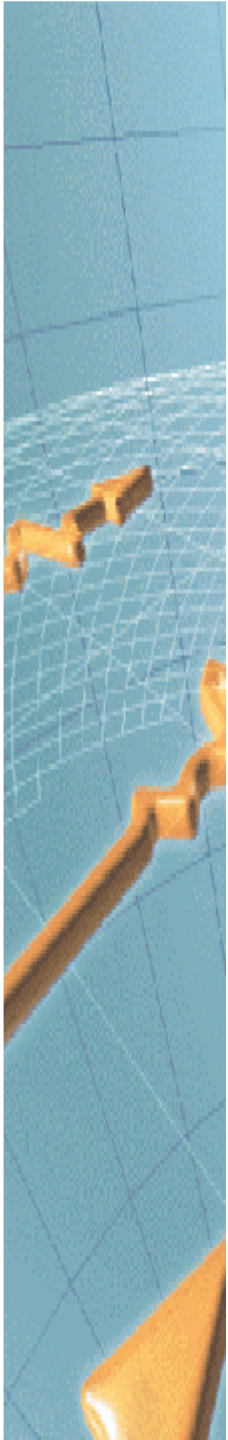
$$R = B \cdot M$$

$$B = \log_2 N + P \cdot \log_2 P + (1 - P) \cdot \log_2 \left[ \frac{(1 - P)}{(N - 1)} \right]$$

where  $N$  is the number of possible selections,  $P$  is the accuracy probability and  $M$  is the average number of decisions per minute

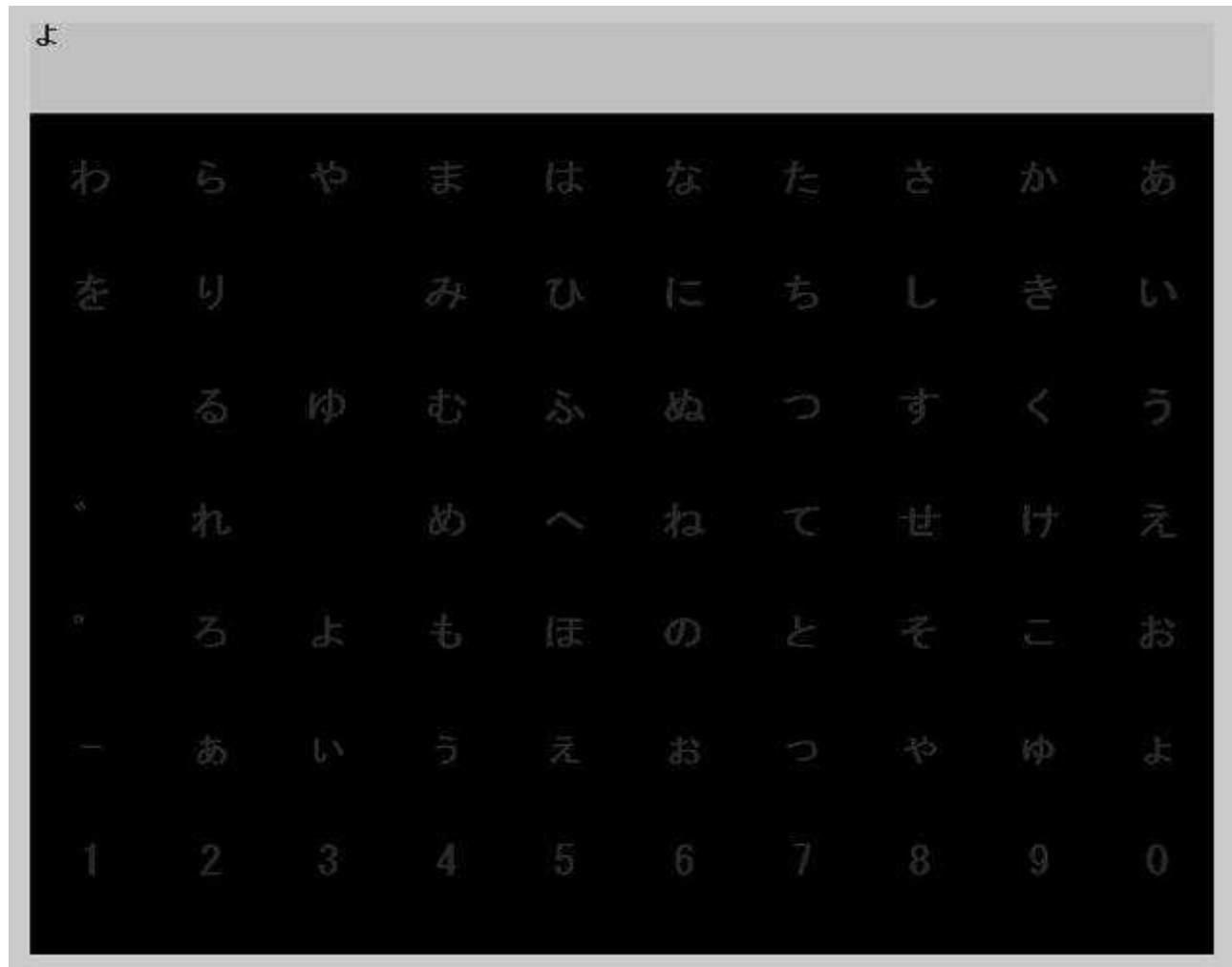
### Average transfer rates of all subjects





## Neurofeedback Applications: P300 Speller, row/column flash

**g.USBamp, g.MOBllab, High-Speedonline Processing, g.RTanalyze, different sensors**



Time [1:24]



**Live Experiment:  
II) Smart Home Control XVR and BCI**

## P300 for smart home control

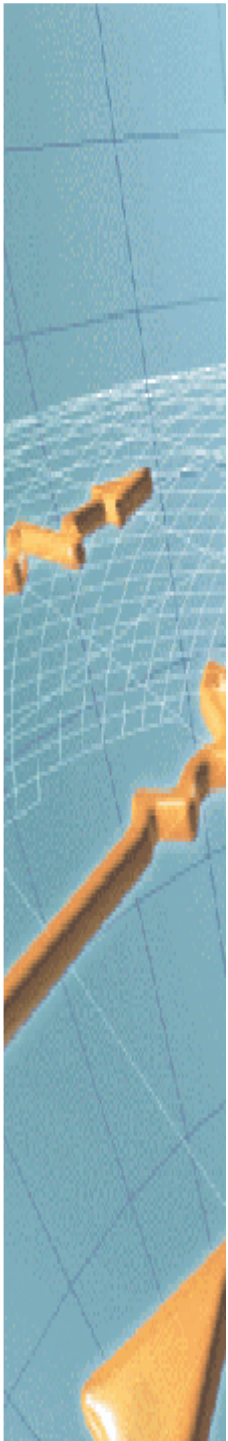


Designed by Chris Groenegress, Mel Slater

[www.gtec.at](http://www.gtec.at)



## P300 for smart home control



Designed by Chris Groenegress, Mel Slater

[www.gtec.at](http://www.gtec.at)

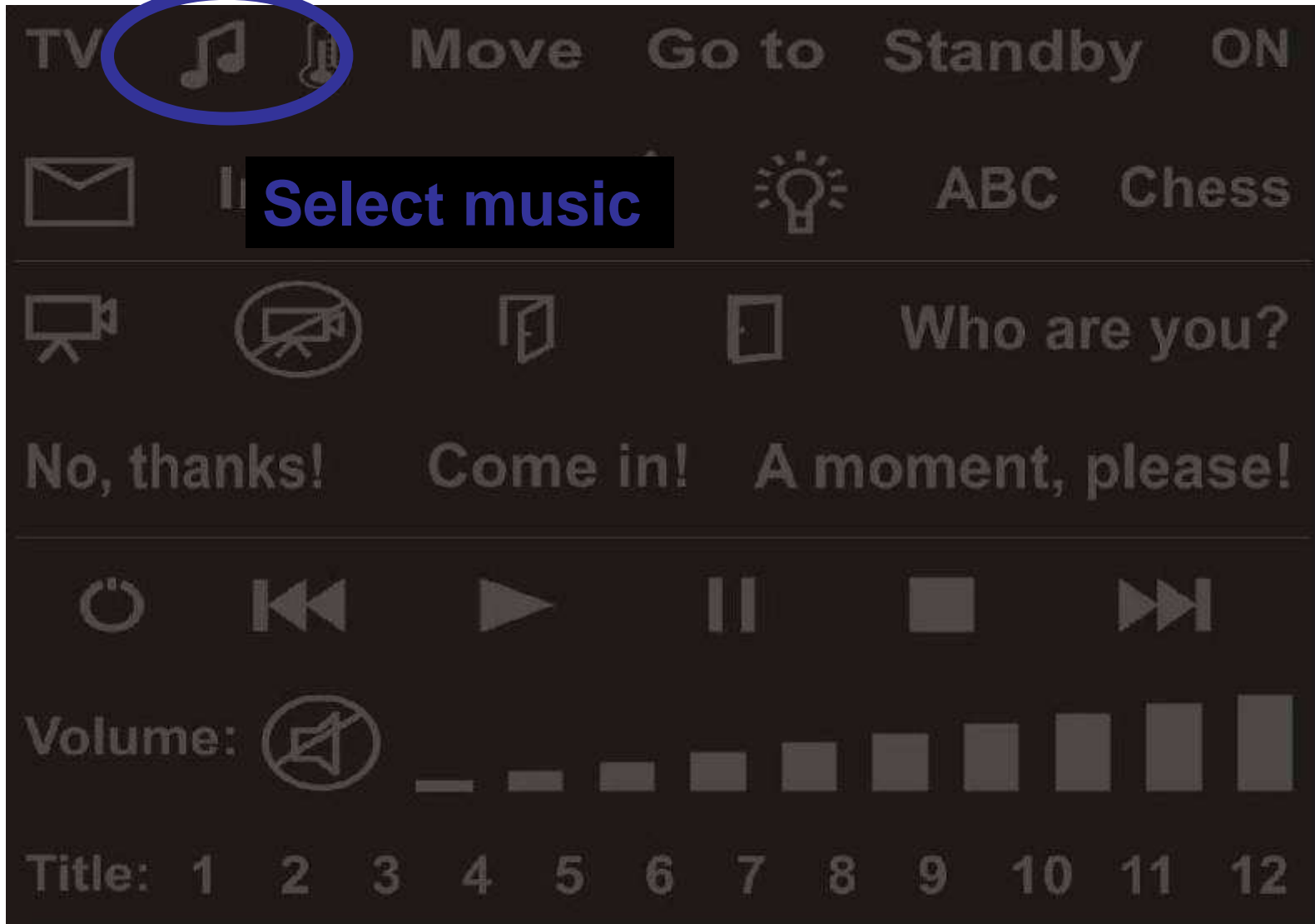
## P300 for smart home control







Designed by Chris Groenegress, Mel Slater





[www.gtec.at](http://www.gtec.at)

# Control matrix for smart home











TV   Move Go to Standby ON

 **Select music**  ABC Chess

    Who are you?

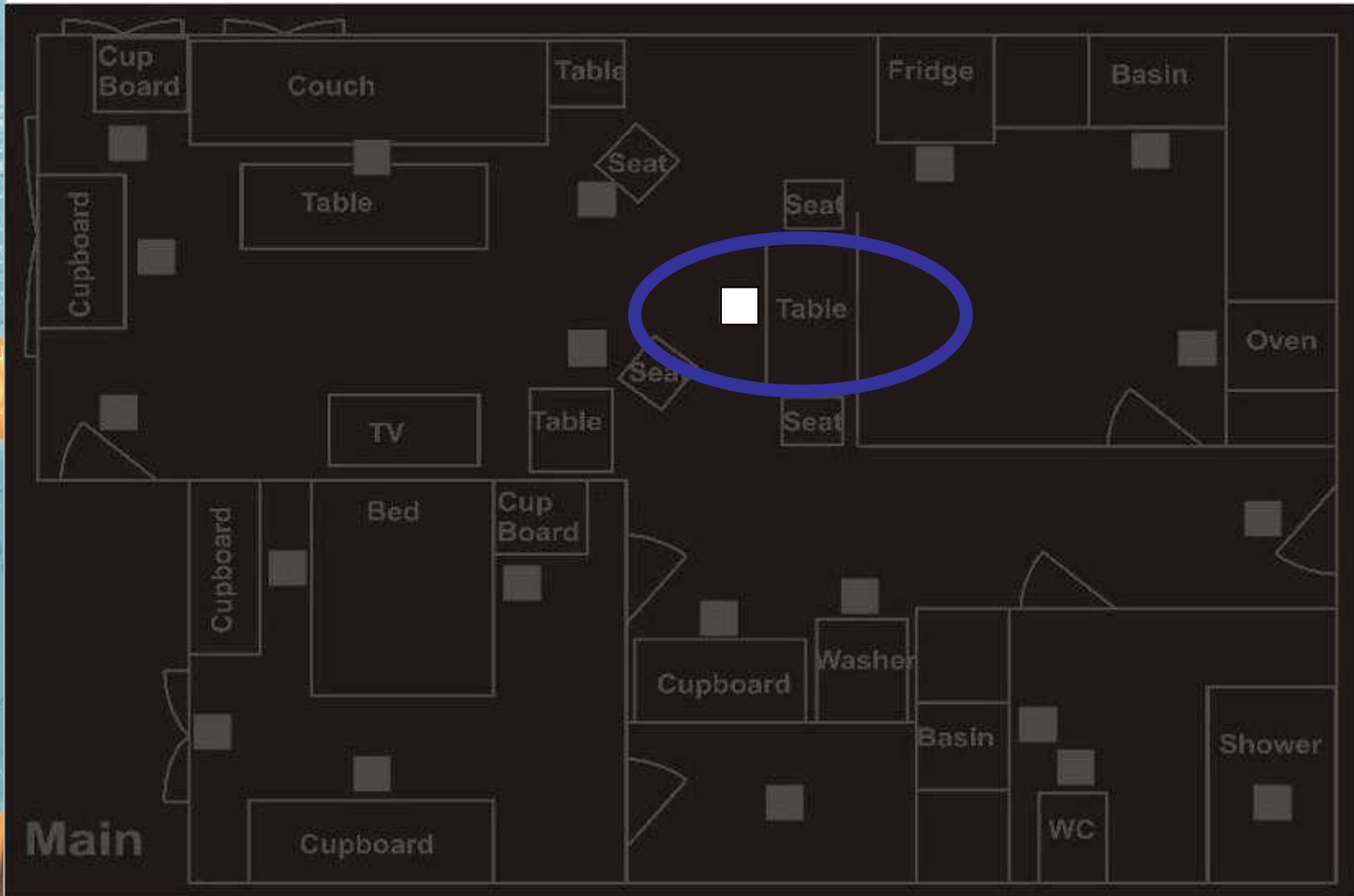
No, thanks! Come in! A moment, please!

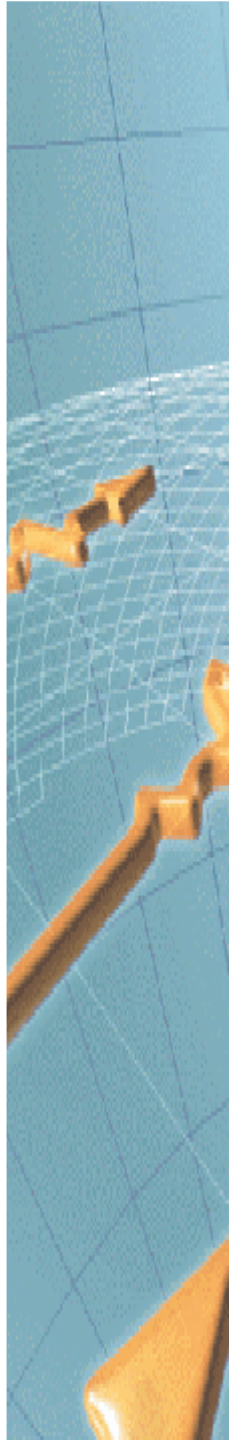
Volume:  

Title: 1 2 3 4 5 6 7 8 9 10 11 12

# Goto specific position – The Beamer







## Discussion

The performance of a BCI system can be measured in terms of:

**Decision speed** (how many seconds are required for one decision?)

1-10 seconds for one decision with P300  
same for oscillatory, SSVEP and slow waves

**BUT**

**Degrees of freedom** (how many classes can be selected?)

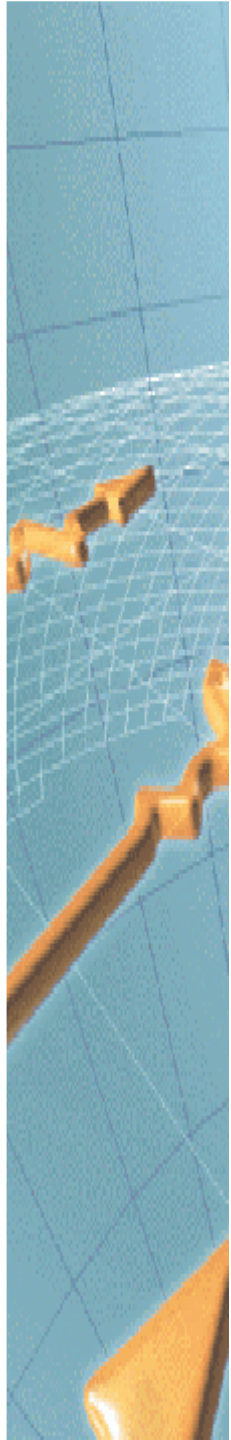
motor imagery task: max. 3 – 4 classes possible

slow cortical shift: continuous feedback for one dimension (up-down)

steady-state evoked potentials: up to 12 keys (phone keyboard)

P300-spelling: e.g. 36 letters (6 x 6 matrix) or more

**P300 allows better control of smart home**



## Discussion

### External visual stimuli

P300 need flashing characters -> it is not the thought of the subject

SSVEP – needs flickering light

Motor imagery BCI detect left/right hand movement, but there is also a trigger signal required that tells the subject when to think about the movement

Slow waves – need timing information

### Accuracy (how many decisions are correct?)

Accuracy of 95 – 100 % possible for most subjects

### Next steps:

Integration of the P300 BCI into highly immersive environment as a new way of communication



## **Some General Remarks:**

- **The Accuracy-vs.-Speed Problem (Transfer rate bit/min)**
- **Adaptive Algorithms: 2 Learning Systems !!!**
- **`State of the Art`: from Research to Practical Use**
- **Acceptance & Usability: Evaluation by Patients and Caregivers**
- **Assets and Drawbacks of BCI compared to other Interfaces**

# Potential for Further Improvement

**Parameter  
Extraction  
Methods**

**Classification  
Algorithms**

**Improved  
Sensors and  
Electrodes**

**Implanted Sensors  
with Wireless  
Transmission**

**Combination of  
different Methods**

**New Applications**

**Online-Statistics  
for Optimized  
Decision Speed**

**Artifact  
Reduction  
Methods**

**Assistive Systems:  
Text Completion,  
Speech output, ...**

# Biomedical Engineering Lectures in PDF format



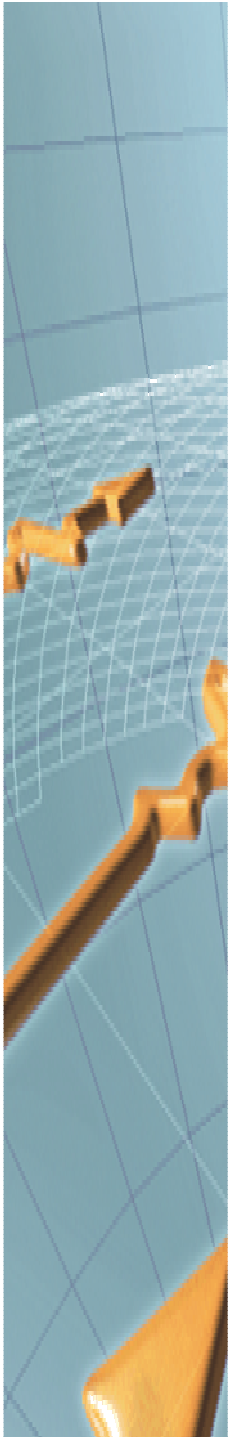
Tutorial contain theory and tasks (measurements, analysis,...)

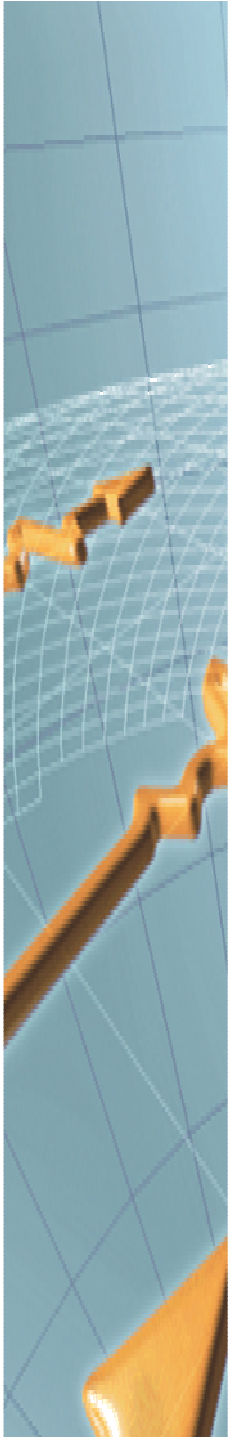
Solutions in a second manual

Very useful in education and to get into the field



**FREE AVAILABLE**





## **BCI WORKSHOP Graz, Austria**

**g.tec BCI Workshop**

**TU Graz BCI Conference**

**September 2008**

**150 people**



## **BCI Workshop @ Neuroscience, Washington DC, USA**

**November 2008**

**We have open positions for PHD students and master students.**

<http://www.presencia.org>



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